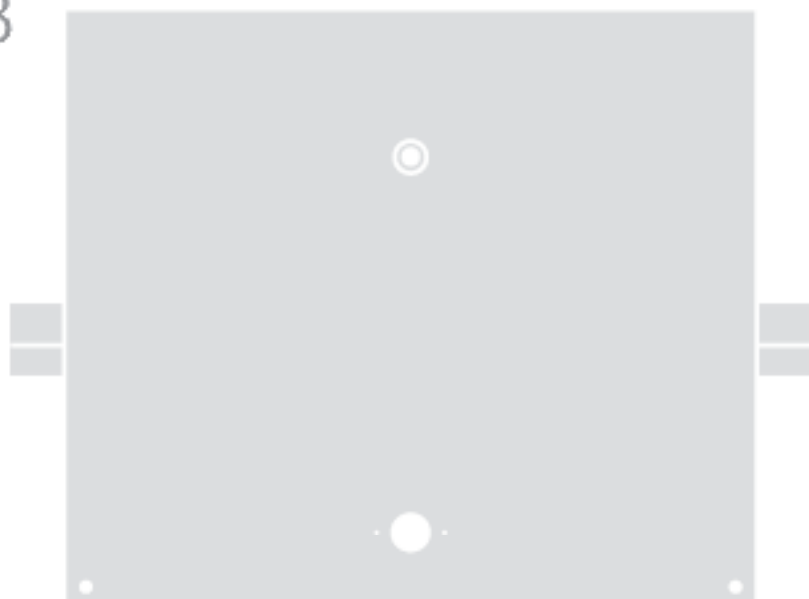


SlideDriver™

SlideDriver 15
SlideDriver 30F
SlideDriver 40
SlideDriver 50VF2/3
SlideDriver 80
SlideDriver 200



Slide gate operator

EN - Programming and operations manual

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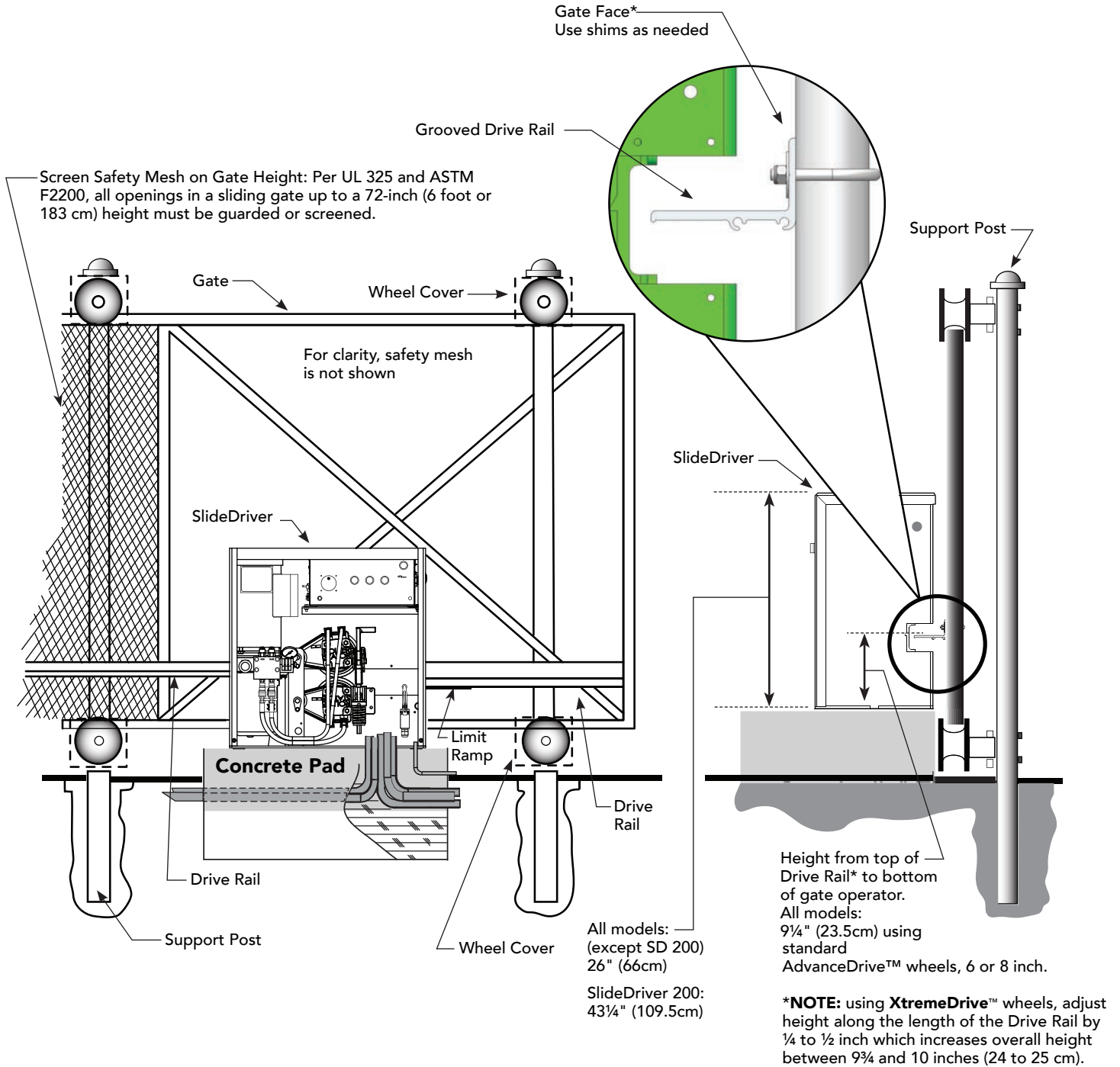
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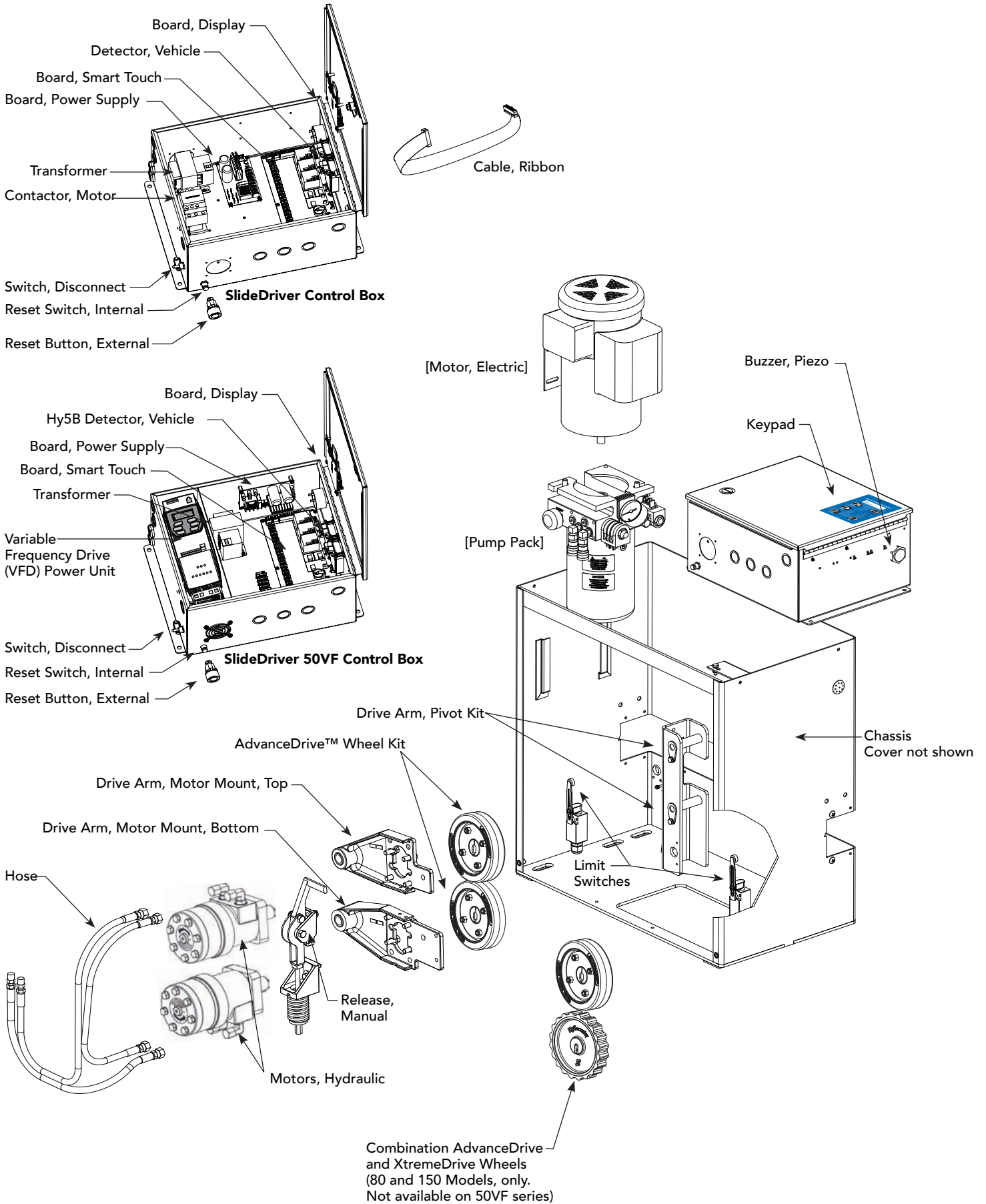
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SlideDriver 15, 30F, 40, 80, 200 SlideDriver 50VF Site Installation Overview

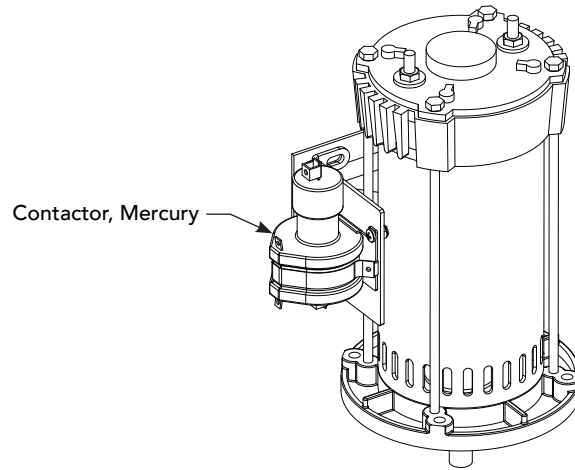


SlideDriver (all models) 50VF Components

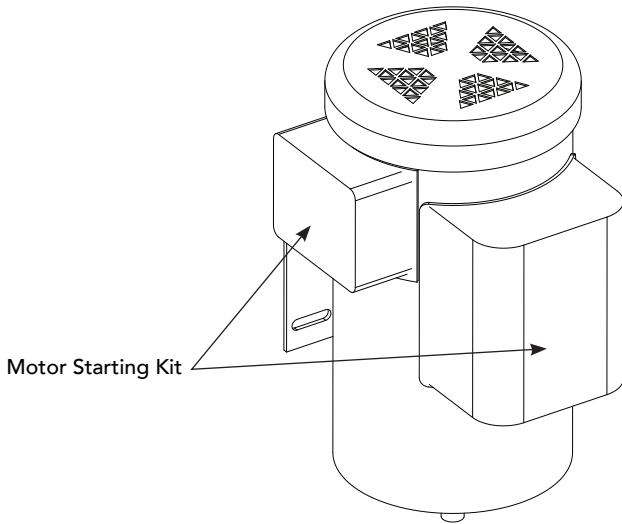


SlideDriver (all models) 50VF Components

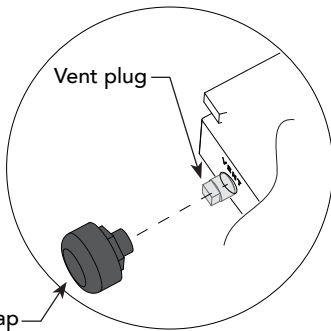
Motor, Electric, DC



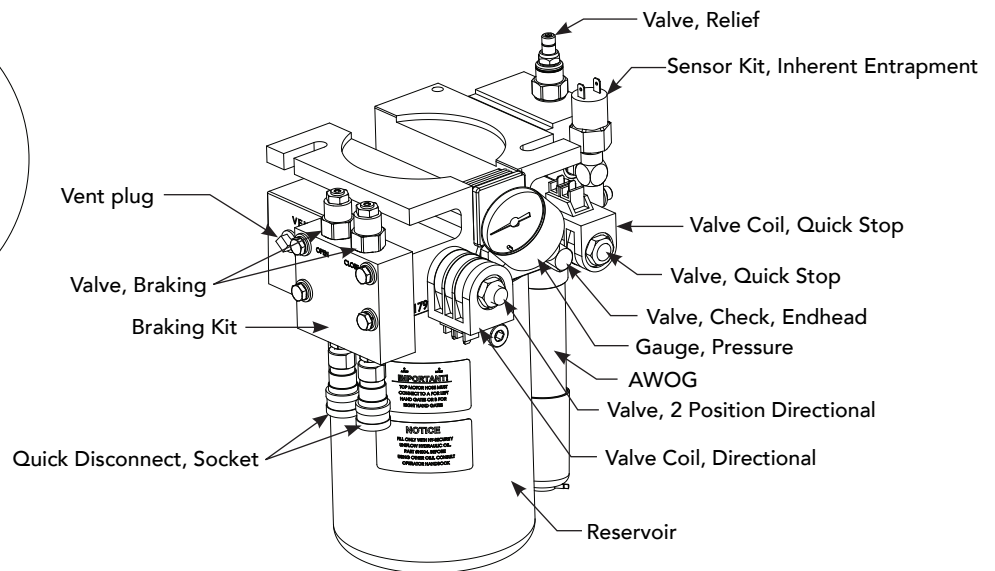
Motor, Electric, AC



Motor Starting Kit



Breather cap



Contact Information

Contact Information

Qualified HySecurity distributors are experienced and trained to assist in resolving any problems. For the name of a qualified distributor near you, call HySecurity at 800-321-9947.

Before contacting your distributor or HySecurity Technical Support, obtain the serial number of your operator.

For information about HySecurity training for installers, maintenance personnel, and end users, refer to the company website at www.hysecurity.com.

Notices and Bulletins

Installers should visit HySecurity's online Technical Support page at www.hysecurity.com or contact HySecurity prior to installing product to make sure they have received the most up-to-date information.

Supplemental Documents

The product literature is comprehensive and contains information needed to plan, install, operate and maintain your gate operator. Additional general information concerning HySecurity gate operators can be obtained from the following:

- The [gate safety section](#) of the HySecurity website contains published materials regarding industry changes due to UL 325 - 2016 requirements involving external entrapment protection sensors.
- Links to the product catalogs, product order form, [operator manuals](#), operator software downloads, technical support bulletins and other useful information.
- [S.T.A.R.T. User's Guide \(D0049\)](#) - Smart Touch Analyze and Retrieve Tool - details the extensive software, diagnostic and troubleshooting capabilities of the Smart Touch Controller board.
- DC Power Supply with HyCharger DC, supplement
- AC Power Supply with HyInverter AC, Installation and Reference Manual
- Technical Bulletins (as applicable).

NOTE: Technical Bulletins are automatically issued to registered users of HySecurity products. The product warranty registration card can be filled out online at www.hysecurity.com.


IMPORTANT SAFETY INFORMATION

SAFETY MESSAGES


The safety messages below inform you about potential hazards that can result in injury. Safety messages specifically address level of exposure to operator and are preceded by one of four words: **DANGER**, **WARNING**, **CAUTION** or **NOTICE**.

 **DANGER**

Indicates a hazardous situation which, if not avoided, **WILL** result in **DEATH** or **SERIOUS INJURY**.

 **WARNING**

Indicates a hazardous situation which, if not avoided, **COULD** result in **DEATH** or **SERIOUS INJURY**.

 **CAUTION**





Indicates a hazardous situation which, if not avoided, **COULD** result in **MINOR** or **MODERATE INJURY**.

NOTICE

Addresses practices not related to personal injury. Indicates damage to equipment is probable if the hazardous situation is not avoided.

COMMON INDUSTRIAL SYMBOLS

These international safety symbols may appear on product or in its literature to alert of potential personal injury hazards. Obey all safety messages that follow these symbols to avoid possible injury or death.

| Symbol | Safety Hazard |
|---|-------------------------|
|  | Attention - Take Notice |
|  | Danger - Keep Away |
|  | Entrapment Zone |
|  | Possible Pinch Point |

IMPORTANT SAFETY INSTRUCTIONS

Hazards, associated with automatic gates, can be reduced with proper site design, installation, and use. Installers, maintenance crews, and owners/users must read and follow the safety requirements found in HySecurity® product manuals.



It is important that only qualified installers handle installation of HySecurity Gate vehicular gate operators. A “qualified” installer has one of the following:



1. A minimum of three years experience installing similar equipment.
2. Proof of attending a HySecurity Technical Training seminar within the past three years.
3. Significant manufacturer endorsements of technical aptitude in gate operator installation and operation.

Underwriter Laboratories (UL) and the American Society for Testing and Materials (ASTM) are responsible for current safety standards and regulations regarding gate operators and automated gates. All aspects of gate installation must comply with the appropriate safety standard. For the most up-to-date ASTM F2200 Gate and Fence Standards, refer to www.astm.org. For UL 325 Safety Standard, refer to www.ul.com. Consult local government agencies for up-to-date rules and regulations as certain municipalities have established licensing, codes or regulations that regulate automated gate system design and installation.

GENERAL SAFETY INFORMATION

A gate operator is only a component in a gate system. The other parts of the gate system can include the gate, the external safety sensors, access controls, and vehicle detectors. To have a gate system that provides for safety, security, and reliable operation it is essential these components operate together as a system. It is the responsibility of the system designer and/or installer to ensure any safety or operational issues have been addressed.

IMPORTANT SAFETY INFORMATION

WARNING

To reduce the risk of injury or death:

1. READ AND FOLLOW ALL INSTRUCTIONS.
2. Never let children operate or play with gate controls. Keep the remote control away from children.
3. Always keep people and objects away from the gate. **NO ONE SHOULD CROSS THE PATH OF THE MOVING GATE.**
4. Test the gate operator monthly. The gate **MUST** reverse on contact with a rigid object or stop when an object activates the non-contact sensors. After adjusting the force or the limit of travel, retest the gate operator. Failure to adjust and retest the gate operator properly can increase the risk of injury or death.
5. Use the emergency release only when the gate is not moving.
6. **KEEP GATES PROPERLY MAINTAINED.** Read the user's manual. Have a qualified service person make repairs to gate hardware.
7. The entrance is for vehicles only. Pedestrians must use separate entrance.
8. **SAVE THESE INSTRUCTIONS.**

IDENTIFYING GATE OPERATOR CATEGORY AND UL 325 USAGE CLASS

The UL 325 standard covers gate operators. Within this safety standard several Usage Classes are described that define different types of installations where gate operators can be applied. Some operators are restricted in their usage application. Appropriate Usage Classes are shown in the Specifications.

Class I



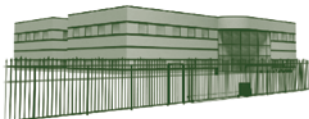
Class I: Intended for use in a location of one to four single family dwellings or a parking area associated with one to four single family dwellings.

Class II



Class II: Intended for use in a commercial location or building such as a multi-family housing units (five or more single family units) hotels, garages, retail stores or other buildings servicing general public.

Class III



Class III: Intended for use in an industrial location or building such as factories or loading docks or other locations not accessible by the general public.

Class IV



Class IV: Intended for use in guarded industrial locations or buildings such as an airport security area or other restricted access location, not servicing general public, in which access is monitored by security personnel or via closed circuitry.

IMPORTANT SAFETY INFORMATION

VEHICULAR TRAFFIC ONLY



WARNING

This automatic gate operator is not designed nor is it intended for pedestrian traffic. Vehicular gate operators must by their nature be powerful to function reliably. This power can cause injury or death. Accordingly, direct all pedestrian traffic to a separate walk-through gate.

Install this gate operator only when:

- The operator is appropriate for the construction of the gate and the Usage Class of the site.
- All openings of a horizontal slide gate are guarded or screened from the bottom of the gate to a minimum of 1.83 m (6 ft) above the ground to prevent a 57.2 mm (2-1/4 in) diameter sphere from passing through the openings anywhere in the gate, and in that portion of the adjacent fence that the gate covers in the open position.
- All exposed pinch points are eliminated or guarded.
- Guarding is supplied for exposed rollers.

The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come in contact with the vehicular gate during the entire path of travel of the vehicular gate.

The gate must be installed in a location so that enough clearance is supplied between the gate and adjacent structures when opening and closing to reduce the risk of entrapment. Swinging gates shall not open into public access areas.

The gate must be properly installed and work freely in both directions prior to the installation of the gate operator. Do not over-tighten the operator clutch or pressure relief valve to compensate for an improperly installed, improperly functioning, or damaged gate.

Permanently mounted controls intended for user activation must be located at least 1.83 m (6 ft) away from any moving part of the gate and where the user is prevented from reaching over, under, around or through the gate to operate the controls.

- Exception: Emergency access controls only accessible by authorized personnel (e.g. fire, police, EMS) may be placed at any location in the line-of-sight of the gate.

The Stop and/or Reset button must be located in the line-of-sight of the gate. Activation of the reset control shall not cause the operator to start.

A minimum of two (2) WARNING SIGNS shall be installed, in the area of the gate. Each placard is to be visible by persons located on the side of the gate on which the placard is installed.

For gate operators utilizing a non-contact sensor (Photo Eye):

- See instructions on the placement of non-contact sensors for each type of application.
- Care shall be exercised to reduce the risk of nuisance tripping, such as when a vehicle trips the sensor while the gate is still moving.
- One or more non-contact sensors shall be located where the risk of entrapment or obstruction exists, such as the perimeter reachable by a moving gate or barrier.

For a gate operator utilizing a contact sensor (Edge):

- One or more contact sensors shall be located where the risk of entrapment or obstruction exists, such as at the leading edge, trailing edge, and postmounted both inside and outside of a vehicular horizontal slide gate.
- A hardwired contact sensor shall be located and its wiring arranged so that the communication between the sensor and the gate operator is not subjected to mechanical damage.
- A wireless device that transmits radio frequency (RF) signals to the gate operator for entrapment protection functions shall be located where the transmission of the signals are not obstructed or impeded by building structures, natural landscaping or similar obstruction. A wireless device shall function under the intended end-use conditions.
- One or more contact sensors shall be located on the inside and outside leading edge of a swing gate. Additionally, if the bottom edge of a swing gate is greater than 152 mm (6 in) but less than 406 mm (16 in) above the ground at any point in its arc of travel, one or more contact sensors shall be located on the bottom edge.

USE OF VEHICLE DETECTORS

Use of vehicle detectors (loop detectors) is strongly encouraged to prevent damage to vehicles caused by gates closing on them. This is not considered to be a safety item as most vehicle detectors cannot provide protection to pedestrians. In some situations, photoelectric devices may be used as vehicle detectors, but should be wired accordingly.

GATE CONSTRUCTION AND SAFETY

Gate construction plays a very important role in ensuring the safety of any automated gate system. The standard for gate construction is ASTM F2200. Below are key areas to address in gate design for safety. For complete information consult the standard. Copies of the standard are available at: <https://www.astm.org/Standards/F2200.htm>.

IMPORTANT SAFETY INFORMATION

Another source of information is available from DASMA, the Door and Access System Manufacturer's Association. The Association publishes Technical Data Sheets, one of which concerns ASTM F2200. For more information, see:

<http://www.dasma.com/PDF/Publications>

General Requirements for gate construction:

- Gates shall be constructed in accordance with the provisions given for the appropriate gate type listed. Refer to ASTM F2200 for additional gate types.
- Gates shall be designed, constructed and installed to not fall over more than 45 degrees from the vertical plane, when a gate is detached from the supporting hardware.
- Gates shall have smooth bottom edges, with vertical bottom edged protrusions not exceeding 0.50 in (12.7 mm) other than the Exceptions listed ASTM F2200.
- The minimum height for barbed wire shall not be less than 6 ft (1.83 m) above grade. The minimum height for barbed tape shall not be less than 8 ft (2.44 m) above grade.
- An existing gate latch shall be disabled when a manually operated gate is retrofitted with a powered gate operator.
- A gate latch shall not be installed on an automatically operated gate.
- Protrusions shall not be permitted on any gate. Consult ASTM F2200 for exceptions.
- Gates shall be designed, constructed and installed such that their movement shall not be initiated by gravity when an automatic operator is disconnected.
- For pedestrian access in the vicinity of an automated vehicular gate, a separate pedestrian gate shall be provided. The pedestrian gate shall be installed in a location such that a pedestrian shall not come in contact with a moving vehicular access gate. A pedestrian gate shall not be incorporated into an automated vehicular gate panel.
- Any non-automated gate that is to be automated shall be upgraded to conform to the provisions of this specification.
- This specification shall not apply to gates generally used for pedestrian access and to vehicular gates not to be automated.
- Any existing automated gate, when the operator requires replacement, shall be upgraded to conform to the provisions of this specification in effect at that time.

The following provisions shall apply to Class I, Class II, Class III, and Class IV vehicular horizontal slide gates:

All weight bearing exposed rollers 8 ft (2.44 m), or less, above grade shall be guarded or covered.

All openings shall be designed, guarded, or screened from the bottom of the gate to the top of the gate or a minimum of 72 inch (1.83 m) above grade, whichever is less, to prevent a 2-1/4 inch (57 mm) diameter sphere from passing through the openings anywhere in the gate, and in that portion of the adjacent fence that the gate covers in the open position. The gate panel shall include the entire section of the moving gate, including any back frame or counterbalance portion of the gate.

A gap, measured in the horizontal plane parallel to the roadway, between a fixed stationary object nearest the roadway (such as a gate support post) and the gate frame when the gate is in either the fully open position or the fully closed position, shall not exceed 2-1/4 inches (57 mm).

Exception: All other fixed stationary objects greater than 16 inches (406 mm) from the gate frame shall not be required to comply with this section.

Positive stops are provided to limit travel to the designed fully open and fully closed positions. These stops shall be installed at either the top of the gate, or at the bottom of the gate where such stops shall horizontally or vertically project no more than is required to perform their intended function.

All gates shall be designed with sufficient lateral stability to assure that the gate will enter a receiver guide. Consult ASTM F2200 for details on various gate panel types.

EXTERNAL ENTRAPMENT PROTECTION SENSORS

Most HySecurity gate operators are equipped with a Type A, Inherent Entrapment Sensor (IES). UL 325 Safety Standard compliance requires installation of external entrapment protection sensors, the number of which, depends on entrapment hazards that exist at each particular installation.

To comply with UL 325, the following external sensors may be used:

- Contact sensors, such as edge sensors
- Non-contact sensors, such as photo eyes

Site designer or installer can choose either photo eyes, edge sensors, or a combination of these devices.

UL 325 Safety Standard for automatic sliding gates specifically requires that edge sensors, photo eyes, or a combination of both devices be installed to protect against pedestrian entrapment in BOTH directions of gate travel and wherever entrapment hazards exist.

IMPORTANT SAFETY INFORMATION

UL 325 LISTING: Edge sensors and photo eyes must be tested and labeled as “Recognized Components” or otherwise certified to UL 325 requirements in order to be deemed acceptable for use in a gate operator. Study Important Safety Instructions and consider your specific installation to determine where greatest entrapment risks exist. Locate edge sensors and/or photo sensors accordingly. Be certain that a sufficient number of sensors are used so that pedestrians are protected from entrapment in both directions of gate travel and all hazard areas are fully protected. Most HySecurity gate operators require external entrapment sensors that utilize Normally Closed (NC) contact means of monitoring. HySecurity gate operators utilizing the SmartCNX Controller require external entrapment sensors that have a 10k Ohm or 4-wire pulsed monitoring scheme. Refer to UL website at www.ul.com for most up-to-date list of gate operator safety standards (UL 325). Refer to www.astm.org for a complete list of ASTM F2200 Gate and Fence Standards.



Recommended External Entrapment Protection Sensors List

The following sensors have been tested with Nice | HySecurity gate operators by an independent laboratory and certified to comply with UL 325 7th Edition. Select sensors from this list for UL compliant gate automation solutions. Contact the sensor manufacturer for specific recommendations for use.

UL 325 Standard:

- The operator shall monitor for the presence of every device at least once during each open and close cycle (32.1.8)
- It shall not be possible to make simple modifications in the field by adding, suppressing or changing, either on the operator or external entrapment protection device(s), to bypass, interfere with, or otherwise defeat the monitoring function. (32.1.10)
- Entrapment zones are now defined for each gate type (4.23, 4.24, 4.29, 4.34)

Slide Gates: To enable fully automatic operation, all SLIDE gate operators will require a minimum of TWO monitored external entrapment protection sensors (one for each direction) to protect entrapment zones in both the open and close direction of travel.

Preferred solution for slide gates: A photo eye for the close direction and a hard-wired edge sensor for the open direction that is mounted to the face of the leading post of the fence behind the gate. (Reach through injuries are the most common hazard associated with automatic sliding gates)

Swing Gates: To enable fully automatic operation, all SWING gate operators will require a minimum of ONE monitored external entrapment protection sensor to protect entrapment zones in either the open or close direction of travel. However, an additional monitored sensor is required if there is a risk of entrapment in both directions of gate travel.

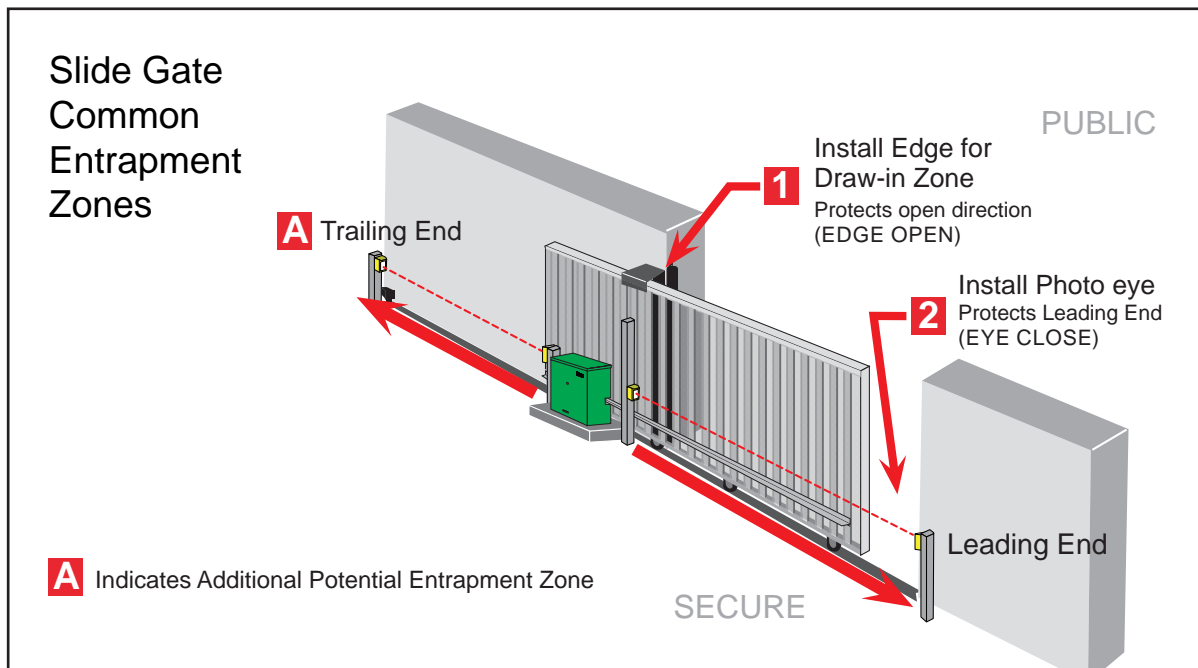
Preferred solution for swing gates: A photo eye for the close direction and/or a hard-wired wraparound edge sensor on the leading edge of the gate, which protects for both directions of gate travel.

IMPORTANT SAFETY INFORMATION

| | Mfg. Part # or Model | Brand | Nice Hysecurity Part # | Max Range | Smart Touch | Smart DC | SmartCNX | 1050 | Mercury 310 |
|---------------------------------------|--|-----------------------|---|-----------|-------------|----------|----------|------|-------------|
| Photo Eyes (Retro -reflective) | E3K-R10K4-NR-1 | Omron | MX000999 | 40 ft | • | • | • | | |
| | NIR-50-325 | EMX | - | 45 ft | • | • | • | • | • |
| | IRB-RET | EMX | - | 53 ft | • | • | • | • | • |
| | E-931-S50RRGQ | Seco-Larm | - | 46 ft | • | • | • | | • |
| Photo Eyes (Thru-Beam) | Blue Bus Era Photo Eyes | Nice HySecurity | EPMB/A EPMOB/A EPLOB/A EPMAB/A EMBORB/A | 45 ft | | | | • | • |
| | OVS-50TNR | Optex | - | 33 ft | • | • | | | |
| | IRB-MON | EMX | MX3990 | 65 ft | • | • | • | | • |
| | E-960-D90GQ | Seco-Larm | - | 90 ft | • | • | • | | • |
| Edge Sensors | Sentir Series | ASO Safety | "AS1502- AS1501-" | | • | • | • | • | • |
| | CPT210-2U-#-T2 | Miller Edge | - | | • | • | • | • | • |
| Edge Sensor Converters | Hy2NC (Converts 10K to NC Monitoring) | HySecurity | MX4018 | | • | • | | | |
| | GEM103 (Converts 10K to Pulsed Monitoring) | Miller Edge | - | | | | | • | |
| Edge Wireless Kits | iGAZE RE Kit | Transmitter Solutions | - | | • | • | • | • | • |
| | WEL-200 | EMX | - | | • | • | • | • | • |
| Multi-Input Module | The Solution – MIM-62 | Miller Edge | - | | • | • | • | | • |

Installers must assess each specific site and install sensors that protect all potential entrapment zones.

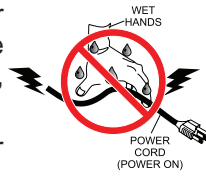
For more information visit Safety or see latest operator manuals at support.hysecurity.com



IMPORTANT SAFETY INFORMATION

ELECTRICAL SAFETY

- Turn gate operator and all circuit breakers OFF before performing maintenance on the gate operator or making contact with output receptacles.
- Never insert any objects into output receptacles during operation. The possibility exists of electrical shock, electrocution, or death.
- Never let power wires lay in water.
- Never use damaged or worn wire when connecting equipment. Inspect for cuts in the insulation.
- Never grab or touch a live power cord or cable with wet hands. The possibility exists of electrical shock, electrocution or death.
- Always make certain that proper power has been selected for the job. See Cable Selection Chart in this manual.



GROUNDING SAFETY

- Always make sure that electrical circuits are properly grounded to a suitable earth ground (ground rod) per the National Electrical Code (NEC) and local codes. Severe injury or death by electrocution can result from operating an ungrounded operator.
- Never use gas piping as an electrical ground.



BATTERY SAFETY

HySecurity operators use sealed Absorbed Glass Mat (AGM) batteries and HySecurity highly recommends replacing used batteries with new AGM-type batteries.

CAUTION

Batteries used with HySecurity gate operator contain materials considered hazardous to environment. Proper battery disposal is required by federal law. Refer to *Hazardous Waste Regulations* federal guidelines.

To reduce risk of fire or injury to persons:

- Observe polarity between batteries and charging circuit.
- Never mix battery sizes, types, or brands. Charging circuit on HySecurity DC operators is designed for AGM-type batteries, not flooded lead acid-type batteries.
- Exercise care in handling batteries. Be aware metal found in rings, bracelets, and keys can conduct electricity, short batteries, and cause potential injury.
- Do not open or mutilate batteries. Battery cells contain corrosive materials which may cause burns and other injuries. Material within batteries is toxic.
- Always dispose of batteries properly. Do not place batteries in fire. Battery cells may explode. Follow federal guidelines for proper disposal of hazardous waste.
- Always keep battery cables in good working condition. Repair or replace all worn cables.
- Replace batteries according to instructions found in *DC Battery Replacement*.
- Do not charge frozen battery. Battery can explode. If frozen, warm the battery to at least 61°F (16°C).



ENVIRONMENTAL SAFETY/ HAZARDOUS MATERIALS AND PROPER DISPOSAL

Decommissioning is a controlled process used to safely retire a piece of equipment that is no longer serviceable. If the equipment poses an unacceptable and unreparable safety risk due to wear or damage or is no longer cost effective to maintain (beyond life-cycle reliability) and is to be decommissioned (demolition and dismantlement), be sure to follow rules below.



- Do not pour waste or oil directly onto the ground, down a drain or into any water source.
- Contact your country's Department of Public Works or recycling agency in your area and arrange for proper disposal of any electrical components, waste or oil associated with this equipment.
- When the life cycle of this equipment is over, remove battery and bring to appropriate facility for lead reclamation. Use safety precautions when handling batteries that contain sulfuric acid.
- When the life cycle of this equipment is over, it is recommended that the frame and all other metal and plastic parts be sent to a recycling center.

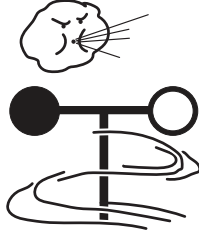
Metal and plastic recycling involves the collection of metal and plastic from discarded products and its transformation into raw materials to use in manufacturing a new product.

IMPORTANT SAFETY INFORMATION

Recyclers and manufacturers alike promote the process of recycling metal and plastic. Using a metal and plastic recycling center promotes energy cost savings.

WIND LOAD FACTORS & SITE PREP

Wind load is always a factor when considering the appropriate gate for a particular site. Solid gate panels produce a larger wind load than gates with slats or open decorative features. If you are installing a gate operator in a high wind area, gate design will affect the load on the gate operator because wind load acts the same as an obstruction. Good gate panel design presents a low surface area to reduce the wind load.



If gate is heavy and near weight capacity of what the gate operator can handle (see specifications), make sure it has an open design that allows wind to flow through it. A solid or semi-solid gate design under certain wind load conditions may cause damage to gate operator and is not covered by the HySecurity Limited Warranty.

Several factors play into calculations of wind load on a gate panel. To find out maximum wind speed in areas around the United States, search for US government wind speed maps on the internet. If you don't know how to calculate for wind load, ask a mechanical engineer or site architect for assistance prior to installing gate operator and gate panels.

When the IES trips, it sends a signal to gate operator to stop and reverse direction. This feature may be falsely triggered in excessively windy conditions because wind itself, acting over surface area of gate panel, can provide necessary force to trigger IES.

CAUTION

Do not adjust IES sensitivity to accommodate for inappropriately designed gate panels. Loss of IES sensitivity increases mechanical wear on gate hardware and gate operator. It may also pose a safety hazard. Compensating for wind loads by adjusting IES may set IES sensitivity to a level which, when encountering an obstruction, ignores obstruction and fails to reverse direction. For more information, refer to Adjusting the IES Sensitivity.

MAINTENANCE OF GATE SYSTEMS

To keep your automated gate system performing both safely and reliably it is important to ensure that the components of that system are functioning properly.

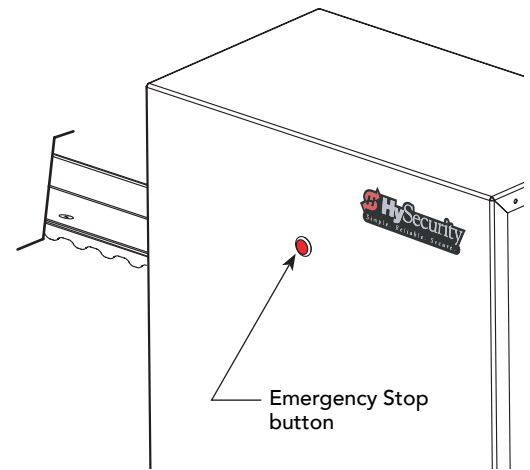
At least monthly:

- Disconnect the gate operator and manually move the gate through its range of travel. Note any squeaks from rollers or hinges or areas of binding. The gate should travel smoothly and quietly throughout its range. If it does not, contact a gate professional to correct the problem.
- Reconnect the gate operator and perform the following tests:
 - With the gate opening, block any photo eyes and/or depress any safety edges used to protect the open direction. The gate should stop and/or reverse.
 - With the gate closing, block any photo eyes and/or depress any safety edges used to protect the close direction. The gate should stop and/or reverse.
 - Using a suitable obstruction in the path of the gate (a solid, immovable object), run the gate in the open direction until it contacts the obstruction. The gate should stop and reverse.
 - Using a suitable obstruction in the path of the gate (a solid, immovable object), run the gate in the close direction until it contacts the obstruction. The gate should stop and reverse.

Emergency Stop Button

Make sure all users of the gate know where the emergency stop button is located (see illustration). It complies with UL 325 Standard of Safety requirements.

Pressing the emergency stop button while the gate is opening or closing disables the automatic close timer and stops gate travel. Gate travel remains stopped until the operator receives another open or close signal.



Emergency Release



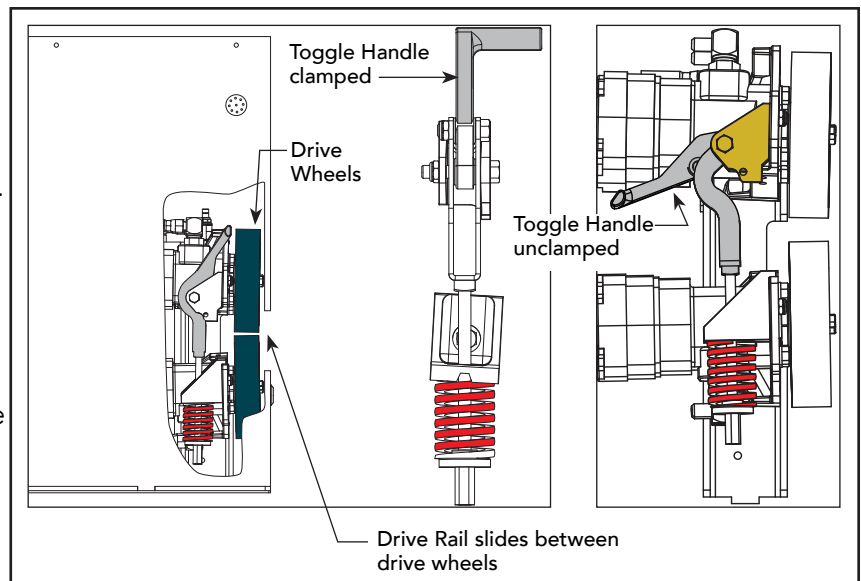
Before attempting a manual release, the gate cannot be moving and the power must be disconnected.

Make sure and teach all users how to turn off electric power, how to move the gate manually, and how to release the drive wheels.

Know the weight of the gate you are moving. Excessively heavy gates can be difficult to move and may cause serious injury to those involved in moving the gate. Take the necessary precautions when manually moving any gate.

To disengage the drive wheels from the drive rail and manually move the gate, take the following steps:

1. Remove the front chassis cover and set it aside.



When releasing the handle inside the chassis, be careful as the mechanism is spring-loaded and drops rapidly. Hold the handle appropriately so your fingers do not get injured or pinched.

2. Pull the toggle handle down. The manual release is located under the electric control panel and to the right of the hydraulic motors.

NOTE: For more information, refer to *Drive Wheel Spring Tension (Adjustment of Manual Release)* on page 126.

Other types of release mechanisms exist. For example, the Fire and Emergency Access Lock Box is available through HySecurity distributors. Contact your distributor for more information.

How to wire the operator is presented in the *Installation Instructions*, but detailed information about the earth and equipment ground, wiring to AC power and the availability of UPS systems are described in this section.

[Supplemental documents](#) to this section include:

- DC Power Supply with HyCharger DC
- AC Power Supply with HyInverter AC

Installing the Earth Ground

An earth ground refers to the grounding rod and accompanying equipment ground which need to be installed to safeguard against potential electrical shock and damage to personnel and equipment.

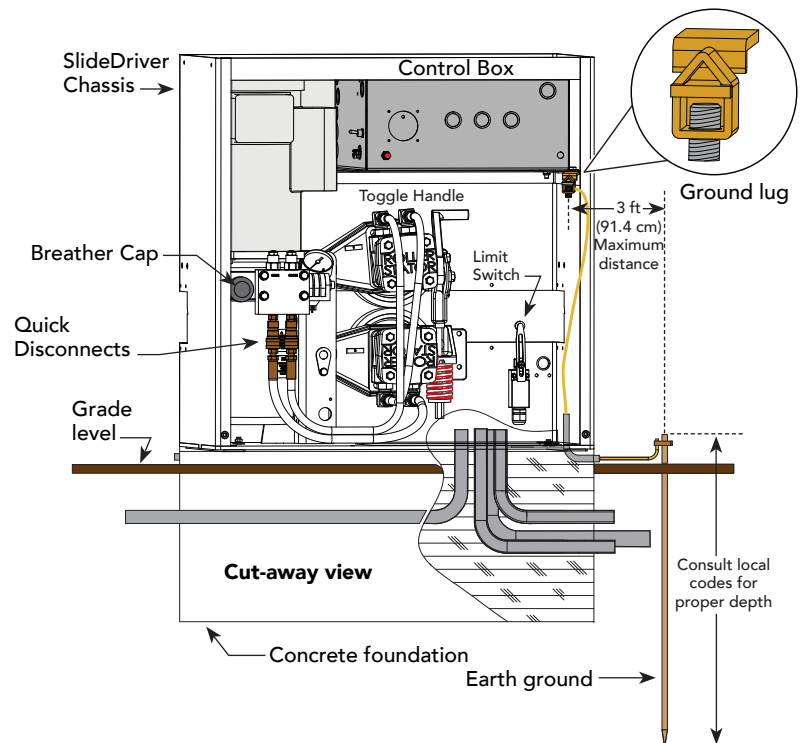


The potential for lightning discharge exists with all gates, fences and gate operators. National Electric Code (NEC) - Article 250 requires a separate earth ground in addition to the required equipment ground.

HySecurity recommends grounding the operator with a separate earth ground rod (or a similar device in the case of crash products) to shield the operator against electromagnetism and other electrical signals that may cause, erratic operation with, or damage to, the Smart Touch Controller and other electrical parts.

For earth grounding requirements in the U.S.A., refer to the National Fire Protection Association (NFPA) 780 - Standard for the Installation of Lightning Protection Systems. Highlights of the standard include:

- The ground rod must be UL listed copper-clad steel, solid copper, hot-dipped galvanized steel, or stainless steel. Minimum requirements: $\frac{5}{8}$ inch (16 mm) diameter and 8 feet (244 cm) in length.
- The ground rod is driven into the earth (refer to local codes for proper depth requirements).
- The ground rod is electrically bonded to the chassis with a single length of un-spliced 6 AWG copper wire less than 3 feet (91 cm) long. Due to the large concrete foundation on crash products, make the necessary adjustments to accommodate for earth ground requirements.
- Local jurisdictions may impose other requirements above the NEC, Article 250 and NFPA 780. Consult the local codes and regulations regarding requirements in your area.



NOTICE: Properly grounding the gate operator is critical to gate operator performance and the life of its electrical components. Use sufficient wire size during installation. If you do not ground the operator with a separate earth ground, you risk voiding the HySecurity Warranty.

Site Considerations

HySecurity gate operators are intended for permanent installation. Make sure you prepare the site with the following considerations:

- Make sure all electrical wiring is properly routed via conduits.
- Check the distance of the wiring run from the main panel to the gate operator. Make sure the wire size of the branch circuit supplying power to the gate operator is large enough to avoid excess voltage drop. Refer to *Wire Sizing and Runs* on page 23.
- Make sure the available power source matches the electrical requirements specified on the voltage nameplate.



Each gate operator is built to run on a specific line power voltage and phase. Failure to ensure the source voltage (phase and frequency match what is specified for the equipment) may result in severe damage to the equipment.

- Make sure a 20-amp circuit (minimum) protected with a 20-amp Inverse Time Breaker (slow blow) is provided for all AC power connections.
- Verify that the operator is electrically grounded per NFPA 780 and NEC Article 250 and local codes.

Wiring AC Power

The SlideDriver has separate *Installation Instructions* that explain how to connect to AC power. For reference purposes, the same information is provided below.

In-rush Current is the current needed to start the electric motor spinning in the proper direction (CCW). It may take as much as 6 to 9 times the in-rush current to start one of the heavy duty operators.

NOTE: Use a 20A (minimum) Inverse Time Breaker circuit breaker for all AC motors.

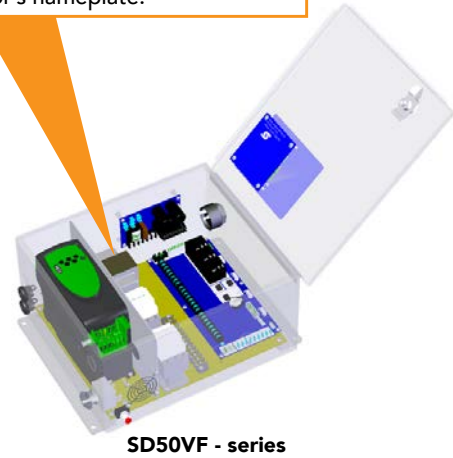
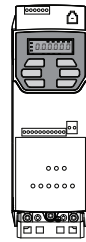
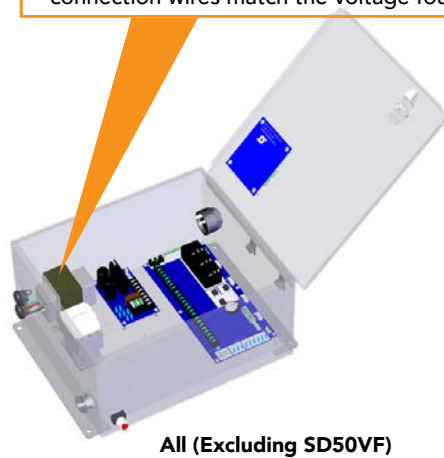
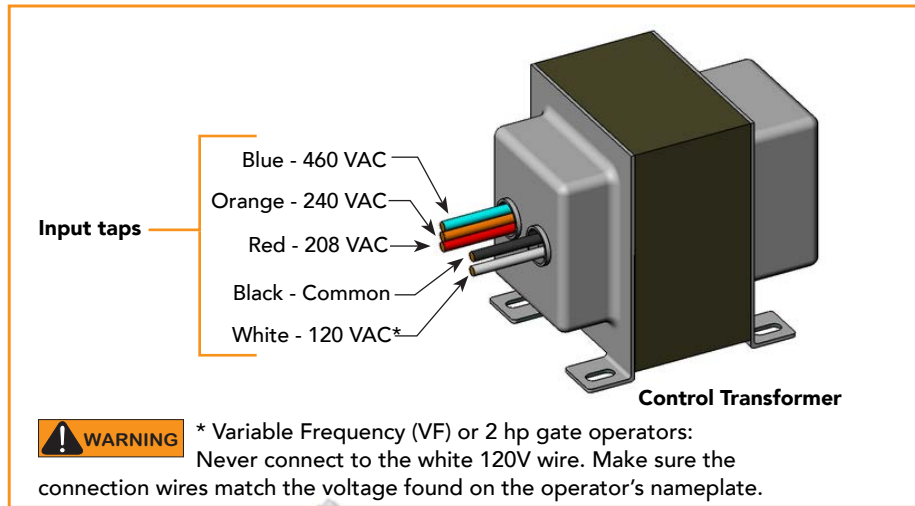
Size the primary wires. Consider the voltage, horsepower, and length of the wire run from the main power panel.

Make sure you have the proper voltage and conversion of voltage taps at the motor and transformer.



Turn OFF AC power at the source (circuit breaker panel) before accessing the wires in the SlideDriver. Follow facility Lock Out/Tag Out procedures. Make sure all power switches are in the OFF position. Follow all electrical code standards and regulations.

1. **Connect to Power:** Two or Three wires and a ground wire are provided for connection of incoming power whether the operator is configured for 1 phase or 3 phase from the factory.
2. **Connect AC Power:** Ensure the site voltage and phasing matches the voltage label on the operator. A wiring diagram is provided in the appendix.



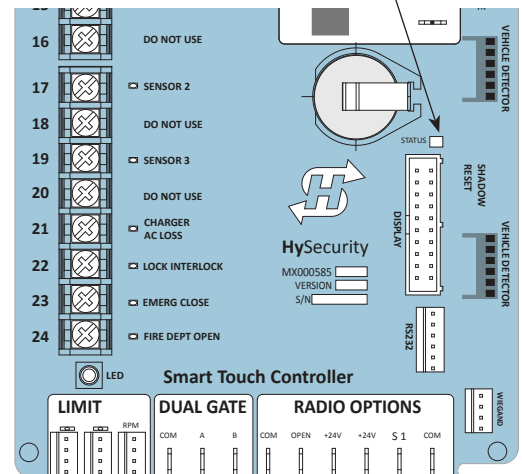
Wiring of gate operators must conform to NFPA and NEC standards and comply with all local codes. When the installation is compliant and complete, turn on AC power at the source and at the control box.

Turning the Power Switch ON

The AC power disconnect switch is located on the same enclosure (control box) where the electrical components, Smart Touch Controller, transformer, power supply board, etc., are found.

When power is turned ON, a green status light on the Smart Touch Controller blinks. The status light appears below the coin battery and indicates that the processor is receiving power. For more information, refer to *Smart Touch Controller Inputs* on page 73.

Green LED flashes indicating processor is receiving power.



Wire Sizing and Runs

Supplying a gate operator with the correct electrical service is crucial to the performance of the operator and the life of its electrical components. If the wire size used is too small, the voltage loss, especially during motor startup, will prevent the motor from attaining its rated horsepower. The percentage of horsepower lost is far greater than the percentage of voltage loss.

A voltage loss can also cause the control components to chatter while the motor is starting, substantially reducing their life due to the resultant arcing. There is no way to restore lost performance resulting from undersized wires, except to replace them. To avoid costly rewiring, be sure to choose a sufficient wire size during site planning phases and at initial installation.

The tables on the following page are based on copper wire and allow for a 5% voltage drop. The ampere values shown are the service factor ampere rating of the motor (maximum full load at continuous duty). At minimum, a 20A circuit (protected with a 20A Inverse time Breaker) should be provided.

Always connect electrical power and ground the operator in accordance with the NFPA 780 & NEC, Article 430 and Article 250. Research and adhere to other local codes that may apply.

Low Voltage Control Wiring

The Smart Touch Controller has very sensitive control inputs. The following is a chart of maximum distances for wire size:

| Wire Size | Maximum Distance |
|------------------|-------------------------|
| 18 ga | 7.0 miles (11 km) |
| 20 ga | 3.5 miles (5.6 km) |
| 22 ga | 2.7 miles (4.3 km) |
| 24 ga | 2.0 miles (3.2 km) |
| 26 ga | 1.0 mile (1.6 km) |
| 28 ga | 3700 feet (1.1 km) |

SlideDriver Wiring Charts (Incoming Power)

The maximum distance shown is from the operator to the power source, assuming that source power is from a panel box with adequate capacity to support the addition of this motor load. The values are for one operator, with no other loads applied to the branch circuit. Avoid placing more than one operator to a circuit, but if you must, be certain to reduce the maximum allowed wire distance by half.

NOTE: Distance shown in U.S. Standard "feet." Metric equivalent shown in parentheses.

| SlideDriver Wire Size Chart – 115V Single Phase | | | | |
|--|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 |
| Amps | 10 | 11.6 | 14.4 | 27.2 |
| Wire Gauge | Distance | Distance | Distance | Distance |
| 12 | 90 (27m) | 75 (23m) | 60 (18m) | 30 (9m) |
| 10 | 140 (43m) | 120 (37m) | 100 (30m) | 50 (15m) |
| 8 | 220 (67m) | 190 (58m) | 155 (47m) | 80 (24m) |
| 6 | 350 (107m) | 300 (91m) | 245 (75m) | 130 (40m) |
| 4 | 555 (169m) | 480 (146m) | 385 (117m) | 205 (62m) |
| 2 | 890 (271m) | 765 (233m) | 620 (189m) | 330 (101m) |

| SlideDriver Wire Size Chart – 208V Single Phase | | | | | |
|--|-----------------|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 | 3 |
| Amps | 5.5 | 6.1 | 7.6 | 14.2 | 16.2 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance |
| 12 | 290 (88m) | 260 (79m) | 205 (62m) | 110 (33m) | 100 (30m) |
| 10 | 460 (140m) | 415 (126m) | 330 (101m) | 175 (53m) | 155 (47m) |
| 8 | 725 (221m) | 650 (198m) | 525 (160m) | 280 (85m) | 245 (74m) |
| 6 | 1150 (350m) | 1040 (317m) | 835 (254m) | 445 (135m) | 390 (119m) |
| 4 | 1825 (556m) | 1645 (501m) | 1320 (402m) | 710 (216m) | 620 (189m) |
| 2 | 2920 (890m) | 2630 (801m) | 2110 (643m) | 1130 (344m) | 1000 (305m) |

| SlideDriver Wire Size Chart – 230V Single Phase | | | | | | |
|--|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 | 3 | 5 |
| Amps | 5.0 | 5.8 | 7.2 | 13.6 | 14.8 | 27.0 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance | Distance |
| 12 | 350 (107m) | 300 (91m) | 245 (75m) | 130 (40m) | 120 (37m) | 65 (20m) |
| 10 | 560 (171m) | 480 (146m) | 385 (117m) | 205 (62m) | 190 (58m) | 105 (32m) |
| 8 | 880 (268m) | 760 (232m) | 610 (186m) | 325 (99m) | 300 (91m) | 165 (50m) |
| 6 | 1400 (427m) | 1120 (341m) | 975 (297m) | 515 (157m) | 475 (145m) | 260 (79m) |
| 4 | 2220 (670m) | 1915 (584m) | 1550 (472m) | 815 (248m) | 750 (229m) | 410 (125m) |
| 2 | 3550 (1082m) | 3080 (939m) | 2465 (751m) | 1305 (398m) | 1200 (366m) | 650 (198m) |

NOTE: Distance shown in U.S. Standard "feet." Metric equivalent shown in parentheses.

| SlideDriver Wire Size Chart – 208V Three Phase | | | | | | |
|---|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 | 3 | 5 |
| Amps | 2.7 | 3.1 | 4.2 | 6.5 | 6.7 | 16 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance | Distance |
| 12 | 590 (180m) | 510 (155m) | 375 (114m) | 245 (75m) | 235 (72m) | 100 (30m) |
| 10 | 930 (283m) | 810 (247m) | 600 (183m) | 390 (119m) | 575 (175m) | 160 (49m) |
| 8 | 1475 (449m) | 1285 (392m) | 950 (289m) | 615 (187m) | 595 (181m) | 250 (76m) |
| 6 | 2350 (716m) | 2045 (623m) | 1510 (460m) | 975 (297m) | 945 (288m) | 400 (122m) |
| 4 | 3720 (1134m) | 3240 (987m) | 2390 (728m) | 1545 (471m) | 1500 (457m) | 630 (192m) |

| SlideDriver Wire Size Chart – 230V Three Phase | | | | | | |
|---|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 | 3 | 5 |
| Amps | 2.4 | 3.0 | 3.8 | 6.2 | 6.4 | 15.4 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance | Distance |
| 12 | 730 (222m) | 585 (178m) | 460 (140m) | 280 (85m) | 270 (82m) | 115 (35m) |
| 10 | 1160 (353m) | 930 (283m) | 730 (222m) | 450 (137m) | 435 (133m) | 180 (55m) |
| 8 | 1835 (559m) | 1470 (448m) | 1160 (353m) | 710 (216m) | 690 (210m) | 285 (87m) |
| 6 | 2925 (891m) | 2340 (713m) | 1845 (562m) | 1130 (344m) | 1095 (334m) | 455 (139m) |
| 4 | 4625 (1410m) | 3700 (1128m) | 2920 (890m) | 1790 (546m) | 1735 (529m) | 720 (219m) |

| SlideDriver Wire Size Chart – 460V Three Phase | | | | | | |
|---|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| Horsepower | ½ | ¾ | 1 | 2 | 3 | 5 |
| Amps | 1.2 | 1.5 | 1.9 | 3.1 | 3.2 | 7.7 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance | Distance |
| 12 | 2915 (888m) | 2350 (716m) | 1850 (564m) | 1130 (344m) | 1100 (335m) | 455 (139m) |
| 10 | 4640 (1414m) | 3710 (1131m) | 2930 (893m) | 1800 (549m) | 1740 (530m) | 725 (221m) |
| 8 | 7340 (2237m) | 5870 (1789m) | 4650 (1417m) | 2840 (866m) | 2750 (838m) | 1150 (350m) |
| 6 | 11700 (3566m) | 9350 (2850m) | 7400 (2255m) | 4550 (1387m) | 4400 (1341m) | 1800 (549m) |
| 4 | 18500 (5639m) | 14800 (4511m) | 11700 (3566m) | 7200 (2194m) | 7000 (2134m) | 2900 (884m) |

SlideDriver 50VF-series Wiring Chart (Incoming Power)

The maximum distance shown is from the operator to the power source, assuming that source power is from a panel box with adequate capacity to support the addition of this motor load. The values are for one operator, with no other loads applied to the branch circuit. Avoid placing more than one operator to a circuit, but if you must, be certain to reduce the maximum allowed wire distance by half.

Make sure proper wiring is being used. The following table shows the maximum allowable wire run from the power source to the operator for various wire sizes. Performance of 50VF-series operators on 1Ø and 3Ø 50 or 60 Hz Power.

NOTE: Distance shown in U.S. Standard "feet." Metric equivalent shown in parentheses.

| SlideDriver 50VF-series Wire Size Chart | | | | | | |
|--|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| Phase Ø | 1 | 1 | 3 | 3 | 3 | 3 |
| Voltage | 208 | 230 | 208 | 230 | 380 | 460 |
| Horsepower | 2 | 2 | 2 | 2 | 2 | 2 |
| VFD Rating Amps | 17.4 | 17.4 | 8.7 | 8.7 | 5.2 | 5.2 |
| Wire Gauge | Distance | Distance | Distance | Distance | Distance | Distance |
| 12 | 90 (27m) | 100 (30m) | 220 (67m) | 240 (73m) | 680 (207m) | 830 (253m) |
| 10 | 150 (46m) | 170 (52m) | 350 (107m) | 390 (119m) | 1090 (332m) | 1310 (399m) |
| 8 | 240 (73m) | 270 (82m) | 560 (171m) | 620 (189m) | 1730 (527m) | 2100 (640m) |
| 6 | 390 (119m) | 430 (131m) | 900 (274m) | 990 (302m) | 2750 (838m) | 3330 (1015m) |
| 4 | 620 (189m) | 680 (207m) | 1430 (436m) | 1580 (482m) | 4380 (1335m) | 5300 (1615m) |
| 2 | 990 (302m) | 1090 (332m) | 2280 (695m) | 2530 (771m) | 6990 (2130m) | 8470 (2582m) |

Performance of 50VF-series Operators on 1 and 3 Phase, 50 or 60Hz

A HySecurity 50VF-series operators can operate on a wide variety of incoming power.

- 50Hz/60Hz operation with no changes or reconnection
- 1Ø or 3Ø operation by field rewiring and reconnection. The incoming voltage must match the operator nameplate. Although the electric motor can be reconnected, a different VFD (motor controller inside the grey control box) is required between 460V and 208V/230V.
- Any AC powered peripherals such as locks, card readers and other devices need to be checked for compatibility.

How is this done?

- The VF controller in the operator is rated to operate on input frequencies ranging from 48Hz through 62Hz on 1Ø or 3Ø power (a jumper connection is required for phase change) but only on 208V/230V. (A change between 460V and 230V, either direction, requires replacing the VF controller).
- The control transformer in the operator is tapped for multiple voltages and rated for 50/60Hz operation.
- The VF controller first rectifies and filters the incoming power to DC, which has no frequency or phase. It then creates 3Ø variable voltage/variable frequency AC for the motor from the DC.
- Depending on the model, the VF controller ramps the motor voltage and frequency from 0V@0Hz at start, to either 208/230 or 460 VAC @ 60Hz for full speed. This allows use of 60Hz motors regardless of the incoming frequency.
- Since the input voltage/frequency is converted to DC to begin with, there is absolutely no relationship between the input frequency/phase and frequency/phase of the power supplied to the motor. The input could be 1Ø or 3Ø, 48Hz or 62Hz and the controller/motor combination wouldn't care. It will create the ramped 3Ø voltage and frequency for which it is programmed.

NOTE: SlideDriver 50VF operators connected for 1Ø operation will draw more current because the utility power to run the machine will be carried to the operator on two wires instead of the three used for 3Ø operators. Be sure to allow for this difference when specifying wire size.

In-Field Connections

SlideDriver 50VF-series operators are field re-connectable for 1Ø or 3Ø, 208/230VAC input power without changing the VFD.



SlideDriver 50VF-series operators CANNOT be connected to 120V, 1Ø power or 575V, 3Ø power. If any attempts are made to do so, serious injury, electrical shock, or death may result. Any electrical damage occurring to the operator will not be covered by the Warranty.

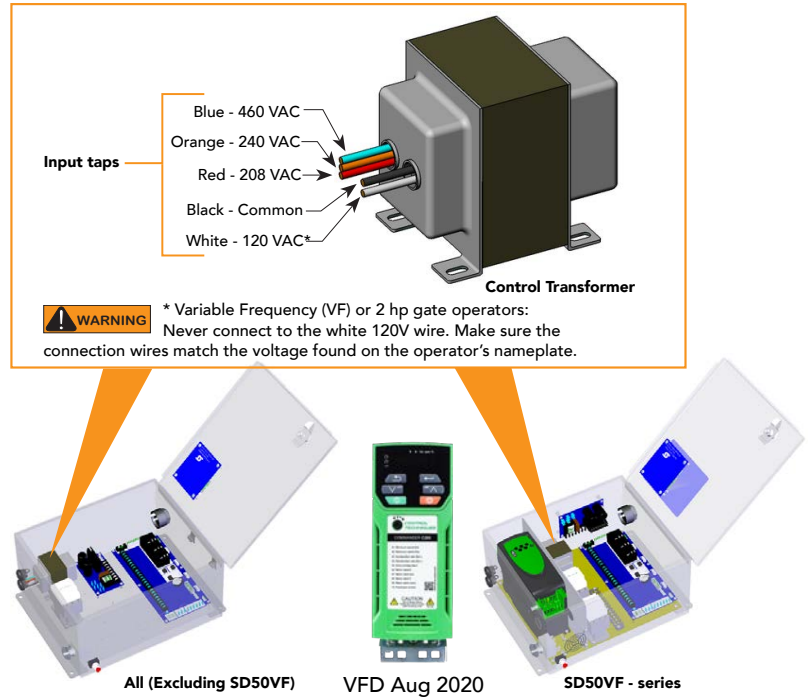


SlideDriver 50VF-series operators are NOT field reconfigurable between 208/230VAC and 460VAC power. The VFD Motor Controller in a 208/230VAC unit must be replaced with a VFD Motor Controller manufactured for the higher (460VAC) voltage input and the motor requires rewiring for the correct voltage.

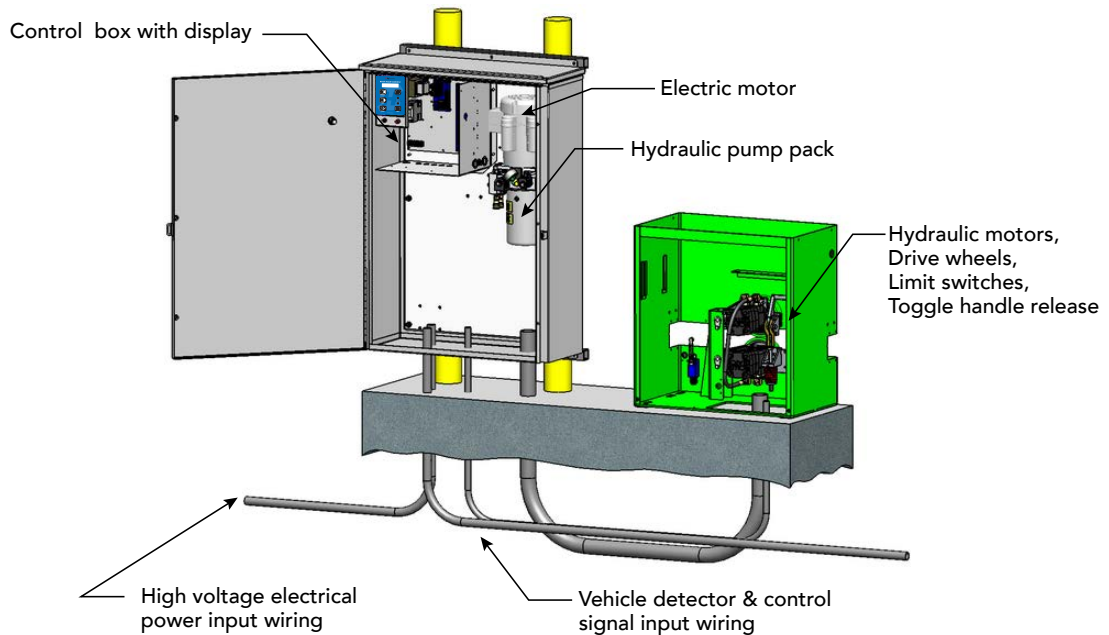
Control Transformer Connections (Non-UPS)

Connect the AC input power to the control transformer according to the following procedure.

1. Ensure that the primary tap on the control transformer matches the line voltage and frequency connected to the gate operator.
 2. Measure the line voltage carefully to distinguish between 208V and 230V branch circuits.
- NOTE:** A label on the transformer top identifies the various voltage taps available.
3. If needed, use wire nuts or crimp-connectors to connect the power input conductors to the applicable taps on the Control Transformer.



Gate Operator Connections (Modular Unit)



If you have the modular unit, additional conduit is needed to house the hydraulic hoses and electrical wiring. You need a 2-inch (5 cm) diameter conduit for hydraulic hoses and a ¾-inch (19 mm) conduit for electrical wiring. AC input power is connected to the hydraulic pump and electrical components enclosure (HydraSupply).

A supplemental manual, provided with the product, describes the installation overview, wiring and conduit considerations.

UPS Backup Power Options

If you plan to use back up power options, additional site considerations are needed for wiring between the power supply and operator. You need a 2-inch (5 cm) diameter conduit for large gauge motor power wires and a ¾-inch (19 mm) conduit for electrical controls wiring. Mounting locations such as pad mount or wall mount also need to be determined. See site planning overview in the installation instructions.

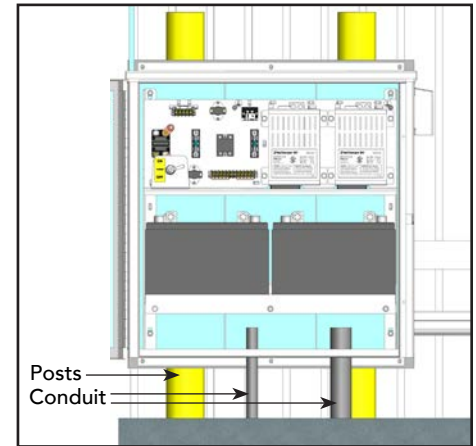
Supplemental manuals, available online (<https://support.hysecurity.com/hc/en-us/sections/360007341234-SlideDriver>), describe the installation overview, wiring and conduit considerations.

DC Power Supply (UPS) Connections

If you have a gate operator with a DC Power Supply unit, you will need to connect the primary AC input power to the DC Power Supply.

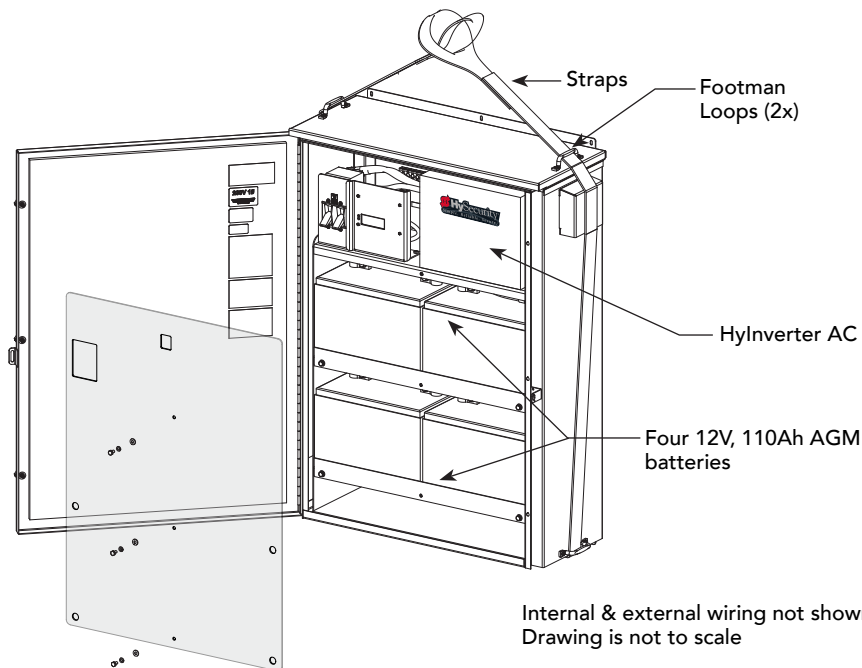
Additional ¾-inch (19 mm) conduit is needed for electrical wiring interconnections between the gate operator and DC Power Supply Cabinet. AC input power is connected to the electrical components in the DC supply, and additional wiring is run through conduit to the DC Power Supply Cabinet.

System features are covered in the DC Power Supply Installation Instructions supplement shipped with the product and available online at www.hysecurity.com.



AC Power Supply with HyInverter AC

Gate operators equipped with the AC Power Supply with HyInverter AC option are powered by four 12-Volt, 110Ah DC batteries which, when AC power loss occurs, maintain a true Uninterrupted Power Supply (UPS) system. When the local AC power fails, the UPS back up system continues to move the gate. System features are covered in the *HyInverterAC Installation and Reference Manual* shipped with the product and available online at www.hysecurity.com.



NOTICE: The AC Power Supply with HyInverter AC option is intended for single phase, 1 hp, gate operators and single phase, 2 hp, gate operators that use Variable Frequency Drives (VFD).

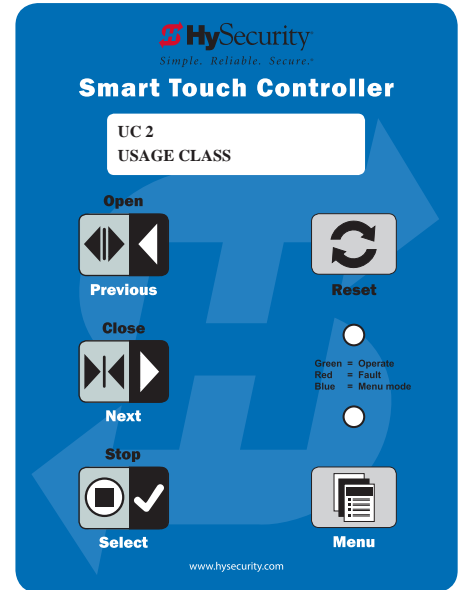
Initial Setup

When you first apply power to the gate operator, it is locked in Menu mode and prompts appear on the display. The gate will not move and the controls will not function until the prompts have been answered. The prompts include:

- Usage Class setting
- Gate handing
- Three external entrapment SENSOR assignments



Before turning the power switch to ON, be sure to replace the vent cap with the breather cap. See page 32. Make sure all site requirements concerning proper wiring, safety, foundation installation, and electrical power have been met.



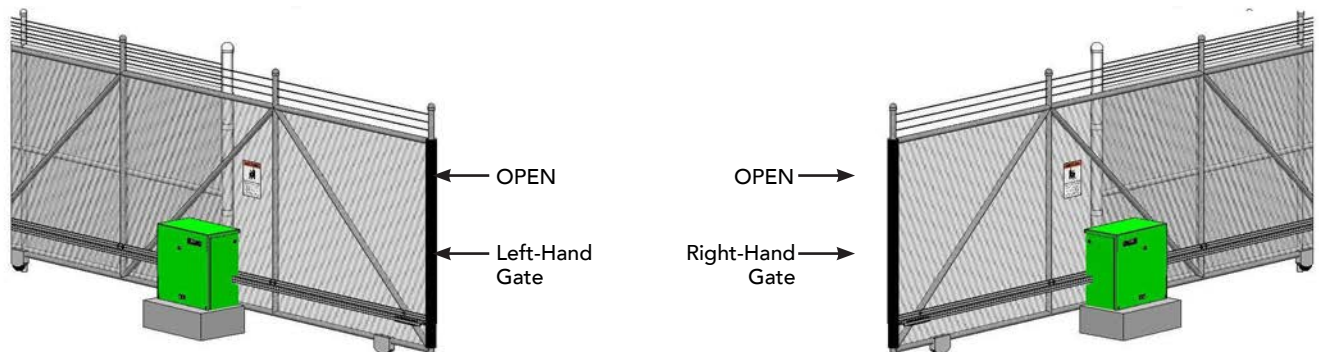
Five buttons on the display keypad provide operational controls. Refer to *Display & Menu Options on page 52* for more information. To answer the initial prompts, use the Previous, Next, and Select buttons as described in the chart below:

| Smart Touch Controller: Menu Mode Navigation Buttons | | | |
|--|--|---|---|
| To change that data appearing in the display | To navigate through the Selections | To choose what appears on the display | To navigate between menu items |
| Press Select . Two left characters blink. | Press Next . Continue pressing Next to view all selections. (Press Previous to reverse direction.) | Press Select . Blinking characters become static. | Press Next or Previous . Advance - press Next Previous - press Previous |

If you are unsure of the usage classification, refer to page 10. It explains the different usage site classifications for UL 325.

Gate Handing

The handing is determined by the position of the operator and which way the gate opens. To determine handing, face the front cover panel on the operator. All SlideDrivers have the hoses configured at the factory for right handing. If the gate has left handing, the hydraulic hoses must be swapped. See page 31.

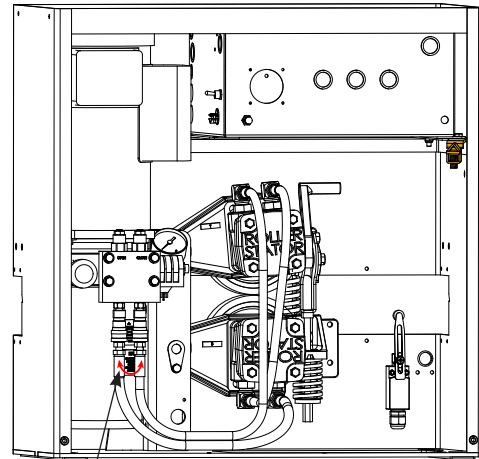


Hydraulic Hose Swap

Gate Handing is determined by viewing the gate opening from the secure side. See illustration on page 30. If the gate opens to the left, the gate must be set for left handing.

All SlideDrivers are set at the factory for right handing. If the gate has left handing, you must

- Select SH L when prompted (SH is an Installer Menu item.)
- Swap position of the hydraulic hoses.



Adjusting the Brake Valves

Proper adjustment of the brake valves is important for smooth operation of the gate. The position and placement of the limit ramps on the drive rail plays an important part on how the brake valves work.

In order for the brake valves to have time to function, the limit ramp must trigger the limit switch at least two inches before end of gate travel.

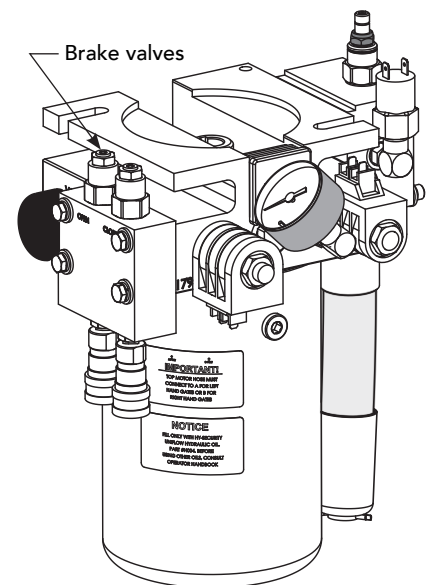
Adjustment of the brake valves, one for each direction of travel, will determine how quickly the gate actually stops.

The adjustment is counter-intuitive.

A counter-clockwise adjustment stops the gate more rapidly. If the adjustment is set too loose, the limit ramps will bang into the drive wheels. If the adjustment is set too tight, the system pressure will increase, the gate speed may decrease and the gate will jerk to a stop.

Brake valves are factory-set to midpoint, two turns. This should be sufficient for most applications.

1. If the limit switch triggers and the drive rail stops more than two inches into the limit ramp, increase braking. If adjustment is needed, loosen the $\frac{9}{16}$ -inch lock nut on the top of the brake valve and make $\frac{1}{4}$ -inch incremental turns on the adjustment stem with a hex key. Note that the adjustment screw varies depending on model type.
2. When the adjustment is complete, retighten the locking nut to hold the setting.



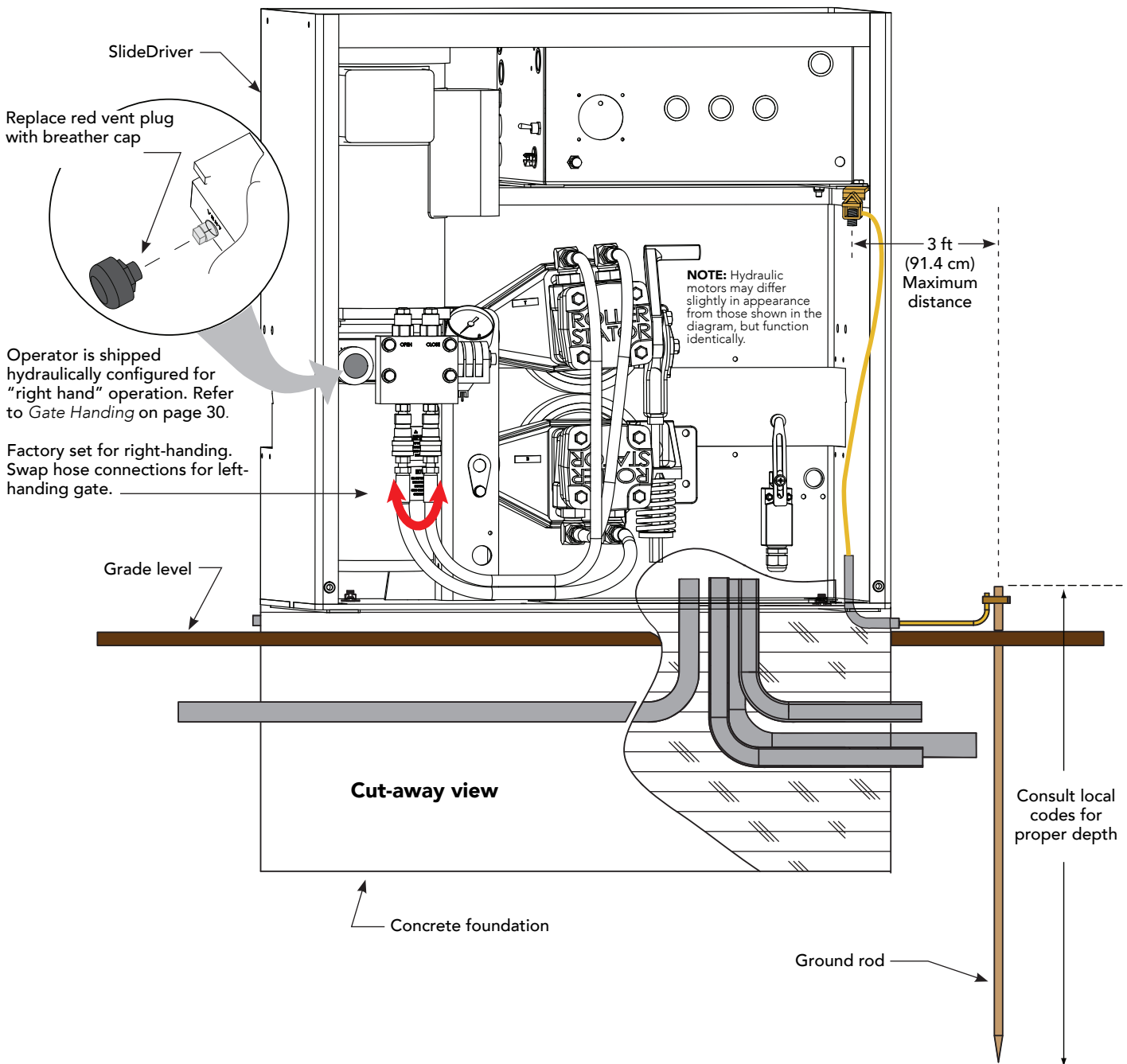
Grounding, Breather Cap Installation & Handing

The gate operator has a vent plug that keeps the hydraulic fluid from spilling during shipment. The vent plug must be replaced by the breather cap before operating the slide gate.

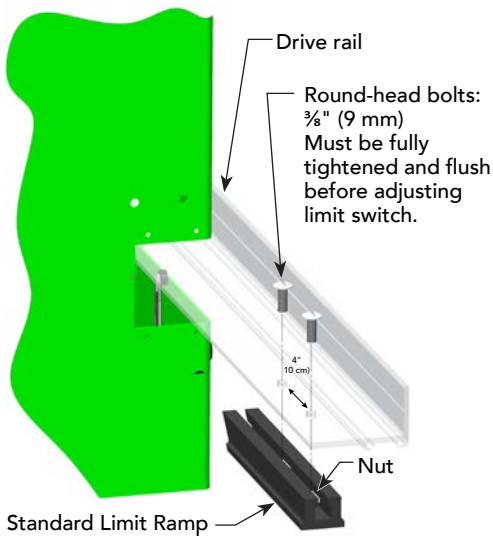


Failure to perform the following procedure will cause premature pump shaft failure and void the Warranty.

1. Remove the vent plug and discard it.
2. Replace the vent plug with the breather cap.

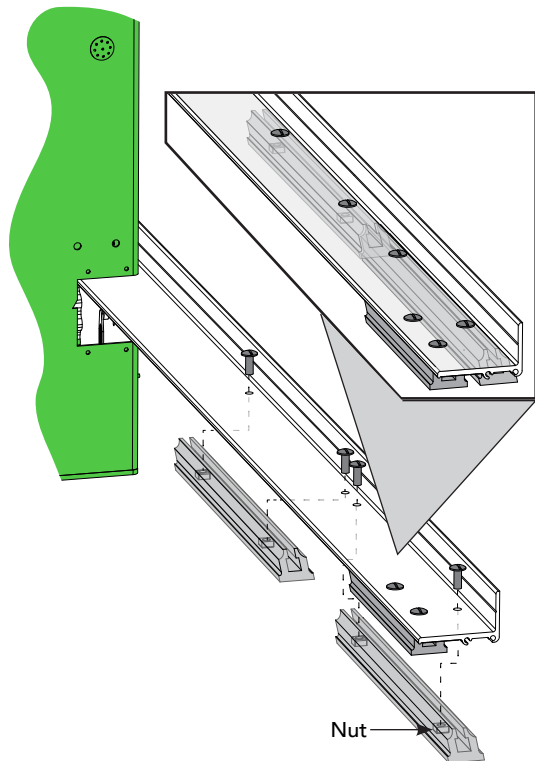


SlideDriver Standard and Slow Down Limit Ramps

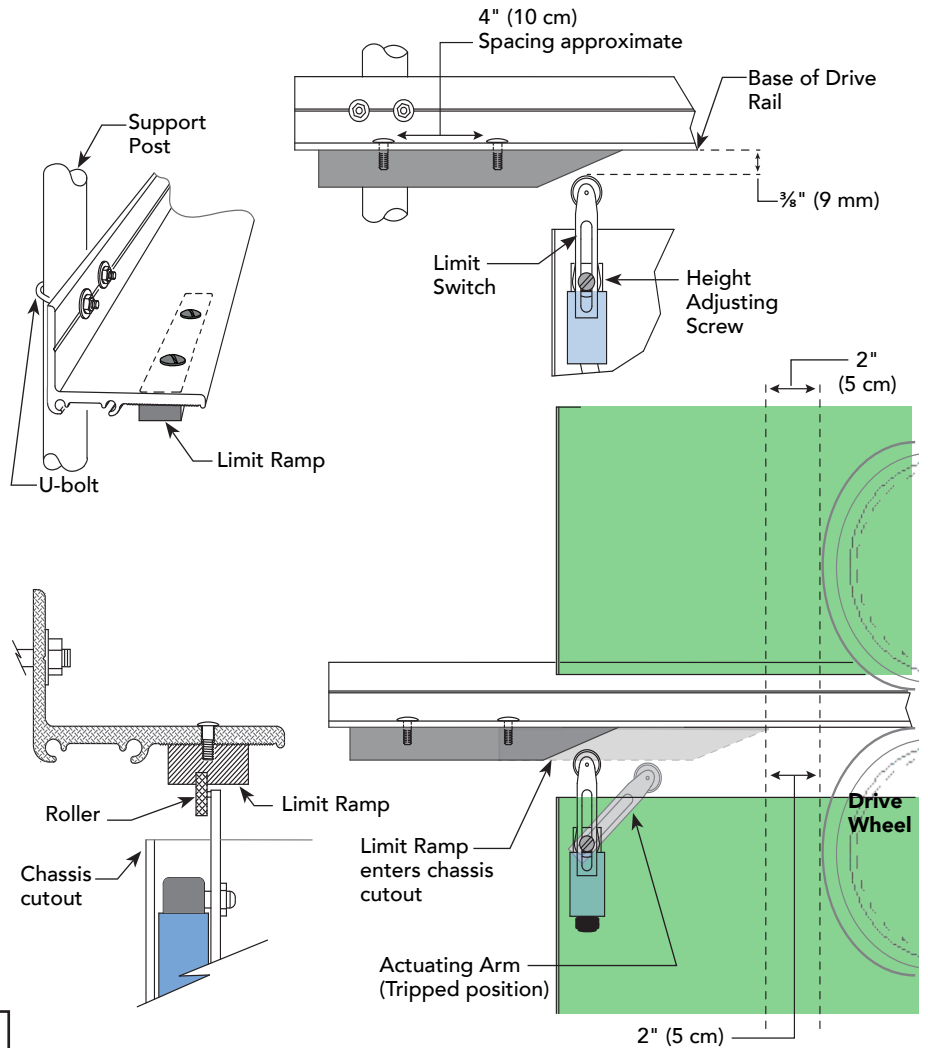


The standard limit ramp is positioned on the drive rail so it will make contact with the limit switch and stop approximately 2 inches (5 cm) from the drive wheel.

Limit ramps are attached to the underside of the drive rail when the gate is fully open and fully closed.



**SlideDriver 50VF
Slow Down Limit Ramp Kit**



Two truss head screws secure each limit ramp to the drive rail. The bolts are spaced about 4 inches (10 cm) apart.

The limit switch must be set $\frac{3}{8}$ -inch (9 mm) from the base of the drive rail. A screw on the limit switch allows for slight adjustments in height. If XtremeDrive wheels are used, you will need to raise the drive rail $\frac{1}{4}$ to $\frac{1}{2}$ inch (3 to 13 mm) along the gate uprights and the entire drive rail path. The limit switch placement will need to be adjusted accordingly.

All the limit ramps are the same length.

NOTE: For a 50VF-series SlideDriver, four (4) Slow Down Limit Ramp Kits will be included and all four must be installed as shown.



Be sure to securely fasten all limit ramps to the underside of the drive rail when installing a 50VF-series operator.

Adjusting the Pressure Relief Valve

When placing the operator into service, pressure relief valve adjustments are required! To provide instruction during installation, a cautionary yellow tag is wire tied to every pump pack. The same instructions are provided in this section.

Pressure relief valves differ depending on the model.

Tools Needed: $\frac{5}{32}$ " hex key, $\frac{1}{2}$ " and $\frac{9}{16}$ " box end wrenches.

CAUTION

ATTENTION INSTALLERS!

When placing the operator into service, pressure relief valve adjustments are required!

Pressure relief valves differ depending on the model.

Tools Needed: $\frac{5}{32}$ " hex key, $\frac{1}{2}$ " and $\frac{9}{16}$ " box end wrenches.

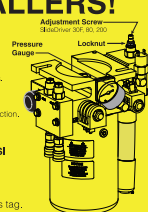
NOTICE: Pressure relief valve adjustments establish the threshold for the inherent entrapment sensor (IES). The optimal pressure setting produces uniform gate travel and trips the IES when the gate encounters an obstruction.

CAUTION: Never exceed the maximum psi setting.

| Model | Motor hp | Maximum PSI |
|---------------------------|----------|-------------|
| SlideDriver 15, 40 | 1 hp | 1000 psi |
| SlideDriver 30F, 80, 50VF | 2 hp | 1350 psi |
| SlideDriver 200 | 5 hp | 2000 psi |

To make adjustments, review the steps on the reverse of this tag.

The same steps are also available in the operator's manual. When the installation and pressure relief valve adjustment is complete, remove this tag.

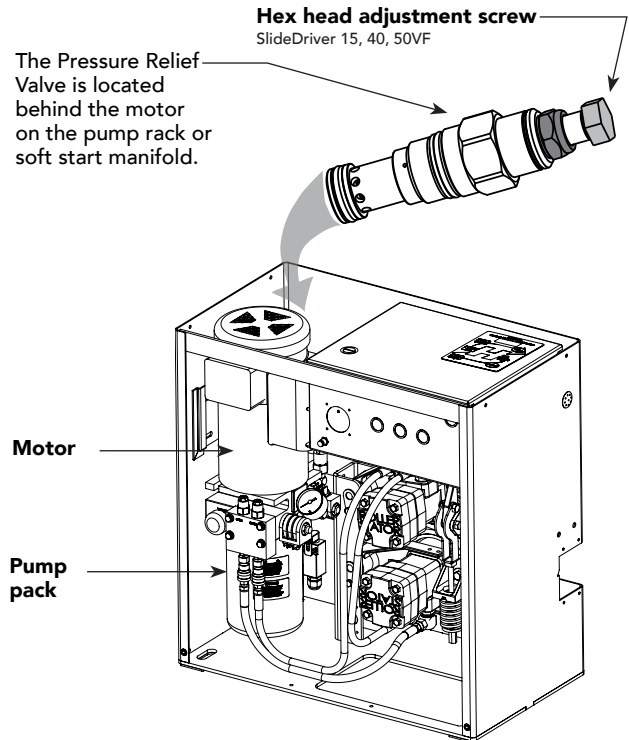
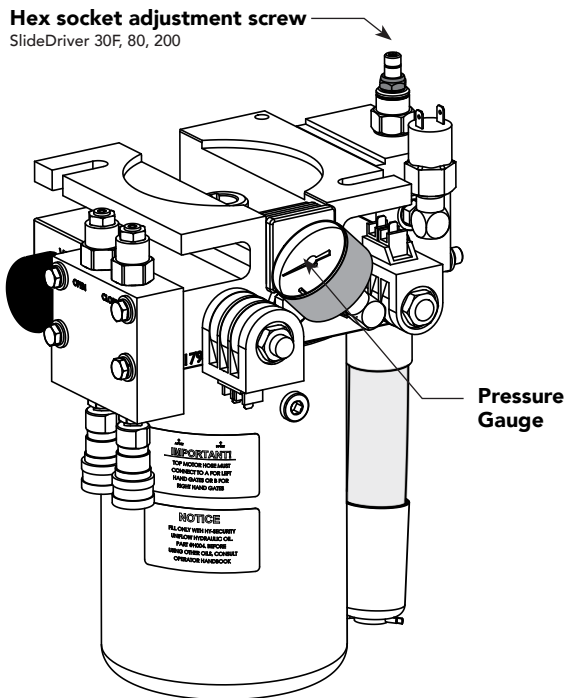


NOTICE: Pressure relief valve adjustments establish the threshold for the inherent entrapment sensor (IES). The optimal pressure setting produces uniform gate travel and trips the IES when the gate encounters an obstruction.

| Model | Motor hp | Maximum PSI |
|---------------------------|----------|-------------|
| SlideDriver 15, 40 | 1 hp | 1000 psi |
| SlideDriver 30F, 80, 50VF | 2 hp | 1350 psi |
| SlideDriver 200 | 5 hp | 2000 psi |



Never exceed the maximum psi setting.



Make sure the gate is properly installed and aligned before performing the following steps. Take precautionary measures to keep the gate's travel path clear. The gate will be moving while you adjust the pressure relief valve.



DO NOT attempt to adjust the pressure relief valve unless you are an experienced hydraulic gate operator installer. Incorrect pressure settings can cause injury and even death!

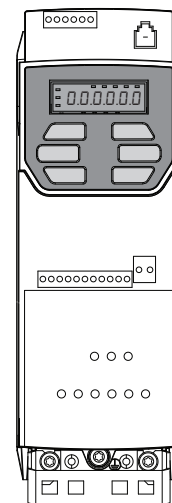
1. Expose several threads on the Pressure Relief Valve by loosening the locknut with a $\frac{9}{16}$ " box end wrench.
2. Depending on the model, insert a $\frac{5}{32}$ " hex key or use a $\frac{1}{2}$ " box end wrench to turn the Adjustment Screw.
3. Use the keypad to cycle the gate open or close and, while the motor is running, turn the Adjustment Screw clockwise (CW) to raise the pressure. The motor runs for a few seconds, stops, and then enters safe mode. SAFE appears on the display.
4. Press RESET and repeat step 3 until gate travel is reliably consistent without entering SAFE mode.
5. To lock in the pressure setting, hold the Adjustment Screw with a hex key or wrench and tighten the locknut.

ModBus RTU in SlideDriver 50VF-series

In the 50VF series SlideDriver™, a communication protocol allows the Smart Touch Controller to constantly monitor the Variable Frequency Drive (VFD) and record events in the STC history log. The history log is easily accessible using the HySecurity S.T.A.R.T. program and a PC laptop computer or view history log codes by accessing the User Menu, LG item (software version h5.53 or later).

With the ModBus RTU:

- Reduction in field calls is likely because the STC resets VFD faults or error codes upon receiving a new command.
- Quality issues with the site power are controlled better which results in less intermittent operator problems.
- Smoother operator acceleration and deceleration enhances gate travel.

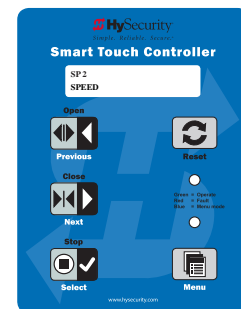


All 50VF2-3 series SlideDrivers shipped after January 1, 2012 have the new ModBus cable and RTU communication protocol installed. If you need replacement parts for your existing 50VF series operators, be sure to have the serial number of the operator available when you order parts.

NOTE: An upgrade to the VFD began shipping in May 2017. It requires software version 4.55 or later. The VFD is a manufacturer's replacement and it is not compatible with HySecurity VFD gate operators that were built prior to January 2012.

If you install a new 50VF2/3 operator, the speed is factory set at 2 foot per second (2 ft/s). To change the speed, you will need to access the Installer Menu.

- SP 2 sets the 50VF2/3 speed to approximately 2 ft/s.
- SP 3 sets the 50VF2/3 speed to approximately 3 ft/s. Refer to *Emergency Fast Operate (EFO) in SlideDriver 50VF-series on page 36.*
- SP 0 and SP 1 are not used. (If you change the setting to 0 or 1, the operator will not run.)

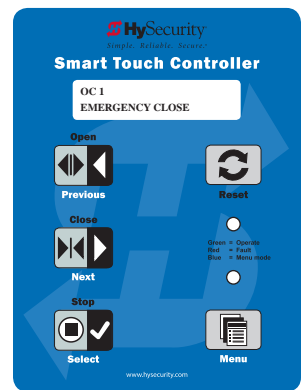
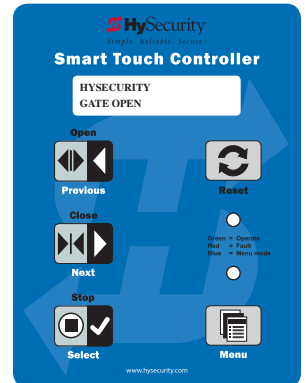


Emergency Fast Operate (EFO) in SlideDriver 50VF-series

To enable the Emergency Fast Operate option on a SlideDriver 50VF-series operator, you need to program the Smart Touch Controller by taking the following steps:

NOTE: When you are in programming mode the buttons on the keypad change from Open, Close, and Stop to Previous, Next, and Select. Refer to *Menu Mode Navigation* on page 55.

1. Make sure the operator is turned ON and a Run mode status (example, GATE OPEN) appears on the Smart Touch Controller, which indicates the machine is operational.
2. Press the Menu button twice to access the User Menu.
3. Press and hold the Reset button and then the Open button. Hold the buttons for two seconds and then release both buttons.
4. Press Next until the Emergency Close (OC 0) appears on the display.
5. Press Select and OC starts blinking, which indicates the display can be changed.
6. Press Next or Previous to change the display to OC 1.
7. Press Select to accept the entry. (The display characters stop blinking.)
8. Press Menu to exit programming mode and return to Run mode. A Run mode gate status appears (example, GATE OPEN).



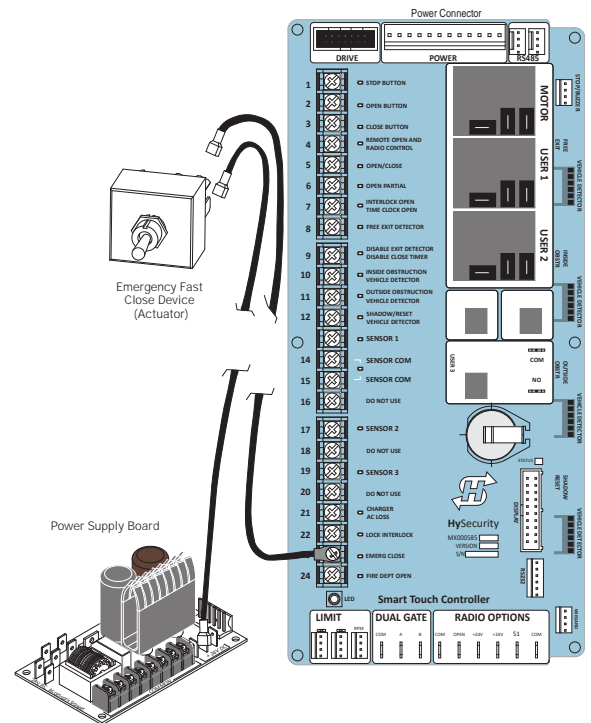
Installing a Push Button Device for Emergency Fast Operate (EFO)

The Emergency Fast Close on the 50VF-series is designed for a constant hold function, such as a push-button device that is held for the duration of gate travel. The device must be connected to Terminal 23 on the Smart Touch Controller and a +24VDC terminal on the Power Supply Board.

When the connections are made, the constant hold signal transmitted to the Smart Touch Controller activates the close function. The gate closes at 3 fps regardless the speed setting. Photo eyes, vehicle loop inputs, and other safety devices (such as external entrapment sensors) are ignored.

Emergency Fast Close Speeds

| Operator | Close Speed | EFO Close |
|-------------------|-------------------------|-----------------|
| SlideDriver 50VF2 | 2.2 fps (26 in per sec) | 3 fps (91 cm/s) |
| SlideDriver 50VF3 | 3 fps (91 cm/s) | 3 fps (91 cm/s) |



Entrapment Protection

As of January 2016, UL325 standard requires gate operators to monitor the presence of all external entrapment sensors, including non-contact (Photo Eyes) and contact (Edge) sensors. For operators built between January 1st, 2016 and July 31st, 2018 only one external entrapment sensor is needed to allow automatic operation, but all potential entrapment zones must be protected or eliminated. After July 31st, 2018, all Slide gate operators will need a minimum of 2 external entrapment sensors (1 open direction and 1 close direction) installed before automatic operation is allowed, but all potential entrapment zones must be protected or eliminated.

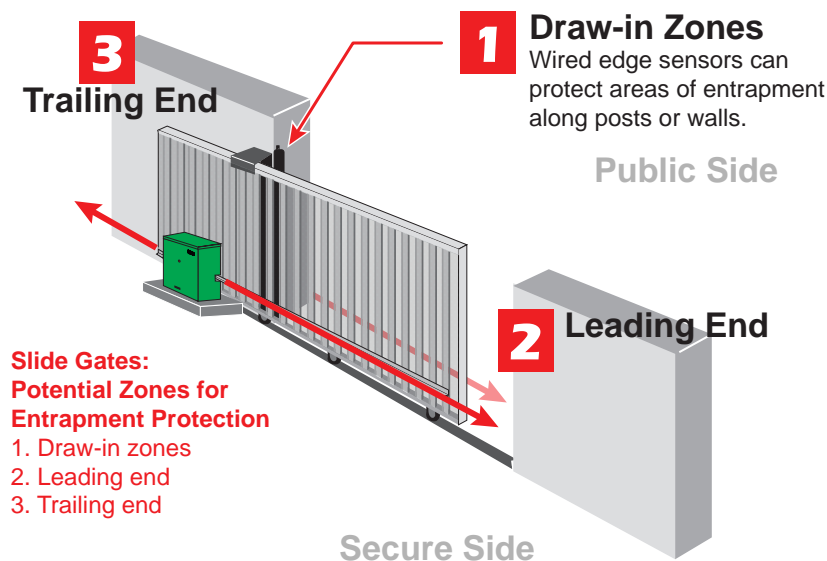
HySecurity monitors all external entrapment sensors installed by looking for NC contacts connected to input terminals. Smart Touch software cycles power to device and looks for a time delay from when device powers on to when the contact closes (sensor input pulled low, meaning the sensor is not blocked/tripped).

Three programmable sensor inputs are available for use and must be programmed to a non-zero number when initial configuration is performed. The three inputs are labeled Sensor 1, Sensor 2, and Sensor 3 and are configurable in the installer menu (S1, S2, or S3) for the following options:

- 1 – Not Used
- 2 – Eye Close
- 3 – Edge Close
- 4 – Eye Open
- 5 – Edge Open
- 6 – Edge Both (Swing Only)
- 7 – Eye Both (Solo Slide Only)

It is the installers responsibility to determine the number of potential entrapment zones that exist and program the Sensor inputs according to which type of external entrapment sensor will be used to protect each zone. If more than three potential entrapment zones exist, then site design may be adjusted to eliminate risks or a Miller Edge MIM- 62 may be used to connect additional sensors.

Potential entrapment zones on a SlideDriver slide gate are shown below. Included in the drawing are examples of potential external entrapment sensor mounting/installation locations.



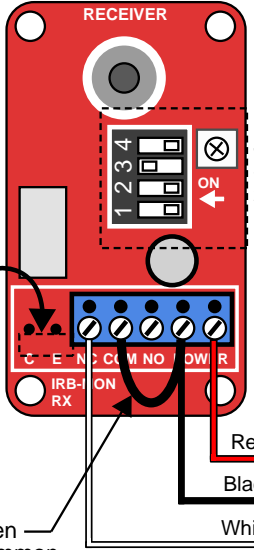
After programming the sensor inputs in the installer menu or during initial startup, the appropriate type and number of sensors will need to be connected. Figure below shows the wiring and dip switch settings of an EMX-MON photo eye (typical thru-beam wiring). A retroreflective photo eye will be similar and only have wiring similar to the receiver of the thru-beam photo eye.

CAUTION
All external entrapment protection sensors must be NC sensor outputs and wired to the **Sensor Com** terminal for monitoring and powering purposes. The sensor is actively powered until the gate reaches the open limit where the monitored check is performed.

CAUTION
Connect all contact and non-contact sensors to same power source. Example, Do NOT connect photo eyes to +24VDC and gate edges to +12VDC. Incompatible power connections result in a **FAULT 2** in the display.

NOTICE
DIP switches must be set as shown, otherwise the photo eye will not operate correctly. Note that older green receiver PCBs are set differently from the newer red PCBs.

EMX IRB MON Photo Eye Receiver

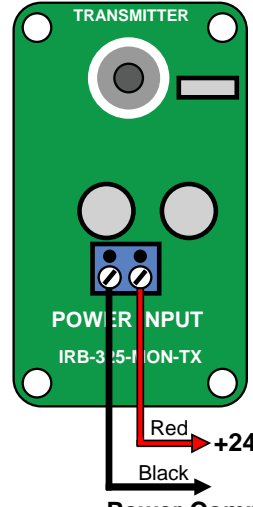


OLDER GREEN RX PCB
For GREEN PCBs (before 06/2020), set DIP switches as shown below.

OLDER GREEN RX PCB
For green RX PCBs, ensure jumper is **removed** from two left 10K pins.

NOTICE
Wire transmitter power input only to power supply common (not Sensor Common).

EMX IRB MON Photo Eye Transmitter



Jumper between COM & Power Common

Red → +24V
Black → Power Common to Sensor Common
White → NC Relay to Sensor 1

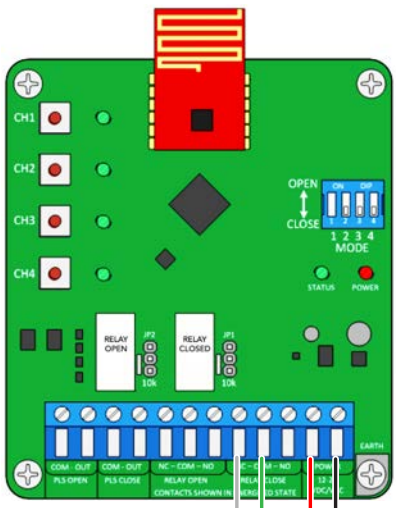
Red → +24V
Black → Power Common to Power Common

CAUTION
If you receive an Alert, "ACTION BLOCKED" "Photo Eye Open" PEO or "Photo Eye Close" PEC, take steps to align the photo eye.

An Edge Sensor can be either hardwired through an adapter module (Hy2NC) or a wireless transmitter receiver combo (WEL-200 or iGAZE RE). Figure below shows the wiring and dip switch settings of a WEL-200. For more information and wiring diagrams of other recommended sensors see the "HySecurity External Entrapment Sensor Wiring Guide".

EMX WEL-200 Wireless Edge Receiver

Dip Switch Settings determine which relay activates when the associated edge is tripped.



SENSOR 1,2, or 3 ←
SENSOR COM ← +24V
SENSOR COM →

Manufacturer's Responsibility

- Build into the gate operator a means of detecting an obstruction or an inherent entrapment detection sensor
- Monitor input from external entrapment detection sensors
- Provide warning signs and an installation manual which, if followed, will result in a UL 325 compliant installation

Pressure Relief Valve – All Hydraulic Operators:

- Limits hydraulic system pressure
- Bypasses fluid to tank when set-point exceeded
- Bypassed fluid triggers the IES

NOTICE: Pressure relief valve adjustments establish the threshold for the Inherent Entrapment Sensor (IES). The optimal pressure setting produces uniform gate travel and trips the IES when the gate encounters an obstruction.

Inherent Entrapment Sensor System – Hydraulic Operators (IES)

The IES sensor:

- Is a normally closed pressure switch on the pump manifold
- Senses fluid flow. High pressure spikes above pressure relief valve setting trigger gate obstruction notification
- Ignores first second of operation to preclude false trips due to starting pressure spike

An open contact:

- During gate movement signals the Smart Touch Controller to place gate operator into SAFE mode
- While the gate is not operating will generate ERROR 2 (ERR2) - disconnected IES

NOTE: A second open contact, in either direction of travel, will lock the gate operator and ENTRAPMENT

MODE (ENTR) appears on the display.

The Inherent Entrapment Sensor (IES)

The IES on HySecurity gate operators is an entrapment sensor that is required by UL 325 as a Type “A” detection sensor. It is tripped through software programming OR hydraulic pressure settings. It does not function solely on its own accord and must be connected to the Smart Touch Controller. The sensitivity and response of the IES when tripped is factory set, but can be adjusted through the Installer Menu items:

- SE (Inherent Sensor sensitivity)
- SS (Inherent Sensor function)
- SR (IES reverse to open)

| Smart Touch Controller™ – Installer Menu Functions for IES | | |
|--|---|--|
| Installer Menu Display Code | Setting Options (Bold – Factory Settings) | Description |
| SE 2 IES SENSITIVITY | 0 = max. sensitivity 2 = Default setting | Adjusts the sensitivity of the internal inherent entrapment sensor (IES). Available settings are 0 to 9 with 0 being the most sensitive. HySecurity strongly recommends that you avoid setting the IES sensitivity higher than 6. Note: Adjust pressure relief valve on hydraulic operators for security and gate impact purposes prior to changing IES sensitivity. Refer to the operator’s manual for steps involved in adjusting the pressure relief valve setting. |
| SS 0 (OFF) IES STOP ONLY | 0 = stop, reverse for 2s 1 = stop only | A setting of 0, stops the gate and then reverses its direction of travel for 2 seconds. To stop gate travel with no reversal, the optional setting 1 can be selected if the gate operator is at a Usage Class IV site and assigned a UC 4 classification. |
| SR 0 (FULL OPEN) REVERSAL LOGIC | 0 = IES reverses full open 1 = 2 second reversal only | The default setting is a 2-second duration reversal if the inherent sensor is triggered. The optional setting of 0 will cause the gate to reopen fully if triggered while closing. |

How Software Handles Monitoring External Entrapment Protection Sensors

HySecurity gate operators use software to control gate movement, contacts, and accessories. The changeover in 2016 to monitoring external entrapment sensors has been a simple process.

- Build Year is a new Installer Menu item in the Smart Touch Controllers versions h4.50 (and higher).
- New labels show where Edge, Photo Eye Open and Photo Eye Closed have changed to “SENSOR” inputs. You can program the type of sensor wired to each of those inputs. See table below.
- Installer Menu items, PC and GC (Photo eye output and edge sensor output) which used to default to Normally Open (NO) have been converted to Normally Closed (NC) contacts so the software can detect the presence and proper operation of external entrapment protection sensors.

Table 3: Changes to Sensor Inputs on the Controller

| Location of Sensor Inputs on Controller | | | Installer Menu Item Codes | |
|--|---------------------------|------------------------|-------------------------------|----------------------|
| Smart Touch Controller (STC): Hydraulic gate operators | | | Smart Touch Display: | |
| Input # | Current Silk Screen Label | 2016 Silk Screen Label | OLED - two line, 32 character | LCD - 7 segment text |
| 13 | EDGE SENSOR | SENSOR 1 | S1 SENSOR 1 | 51 |
| 17 | PHOTO EYE OPEN DIRECTION | SENSOR 2 | S2 SENSOR 2 | 52 |
| 19 | PHOTO EYE CLOSE DIRECTION | SENSOR 3 | S3 SENSOR 3 | 53 |

NOTE: NOTE: Three inputs for external entrapment protection sensors are available on the HySecurity gate operator controller.

Table 3 indicates how the edge and photo eye inputs have been renamed to generic “sensor” inputs. They are interchangeable and configurable. The software must know what type of sensor is wired to SENSOR 1, 2, and 3 **BEFORE** it will allow gate travel.

External Entrapment Protection Sensors: What the Installer Needs to Do

NOTE: NOTE: All HySecurity gate operators built off 2016, will have the Build Year setting.

A Build Year of 2 or 3 (BY 2 or BY 3) indicates that your gate operator is prepared to monitor for external entrapment protection sensors. The Build Year setting appears in the system scroll on the gate operator display. BY 2 is for operators built between January 1, 2016 and July 31, 2018. BY 3 is for operators built after July 31, 2018. **The gate operator will not automatically cycle the gate unless an indication that the appropriate number of external entrapment protection sensors are connected and operational.**

The normally closed (NC) entrapment protection sensors wired to the Controller’s SENSOR inputs are monitored using HySecurity software. Prompts appear in the display requesting specific configurations based on the gate operator type.

Table 4: *Installer Menu Settings for SENSOR Inputs on page 44* illustrates what options are available for the HySecurity Controller’s configurable inputs. Input labeling has changed to:

SENSOR 1 SENSOR 2 SENSOR 3 SENSOR COM

Refer to illustration on page 38.



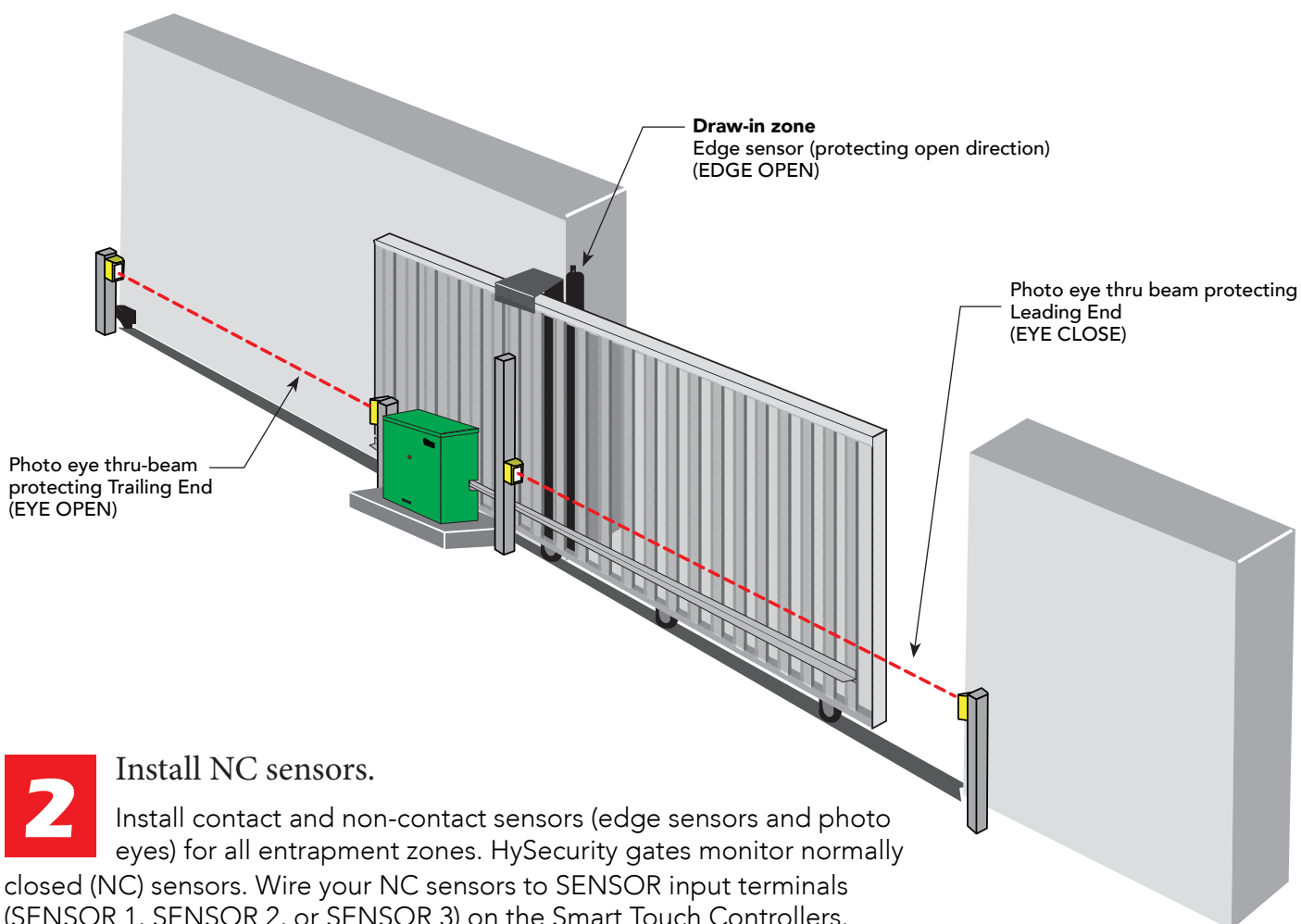
All external entrapment protection sensors must be wired to the SENSOR COM terminal for power and monitoring purposes. The three SENSOR inputs are interchangeable and configurable. For example, it doesn't matter whether you wire a normally closed photo eye sensor or edge sensor to the SENSOR 1, 2, or 3 input. However, due to monitoring requirements, each SENSOR input (1, 2, and 3) can only accept one NC sensor output connection.

1

Assess Your Gate Site.

Design your gate installation so entrapment zones are kept to a minimum, and then install your HySecurity gate operator.

NOTICE: UL 325 Standard of Safety provides the MINIMUM safety standards. Site, gate hardware usage, and other conditions may dictate the use of additional safety designs/components. It is up to the gate system designer and installer to assess appropriate safety design and components above and beyond minimum UL 325 and ASTM F2200 standards. Always check your local area codes and comply with all regulations.



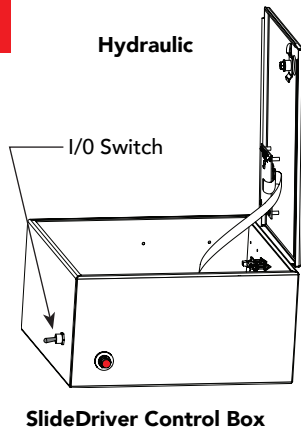
2

Install NC sensors.

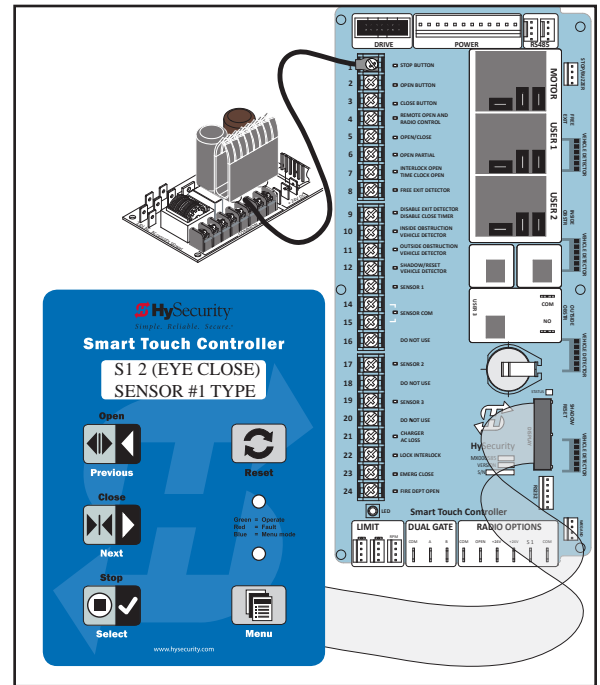
Install contact and non-contact sensors (edge sensors and photo eyes) for all entrapment zones. HySecurity gates monitor normally closed (NC) sensors. Wire your NC sensors to SENSOR input terminals (SENSOR 1, SENSOR 2, or SENSOR 3) on the Smart Touch Controllers.

NOTE: NOTE: When installing wired edge sensors, the wired edge must be connected to an interface module with an NC output. See *Wiring HySecurity Sensors: Smart Touch* on page 138. For wireless edge sensors, no interface module is required. Wireless edge sensors need the wireless gate links which include a transmitter and receiver.

3 Turn Power ON.



NOTE: NOTE: On the next page, review LED function and how to provide temporary power to the sensors.



4 Answer Initial Setup Prompts.

For slide gates you will be prompted for USAGE CLASS, GATE HANDLING, and SENSOR 1, SENSOR 2, and SENSOR 3. Each SENSOR input, whether or not it has a contact or non-contact sensor wired to it, must be programmed to a non-zero setting before the gate will move.

NOTE: NOTE: The gate operator will not automatically cycle unless an indication is received that the appropriate number of external entrapment protection sensors are connected and operational. At minimum, at least one external entrapment protection sensor must be configured for the open direction and one for the close direction.

Smart Touch and Smart DC Controller: Menu Mode Navigation Buttons

| To change data appearing in the display | To navigate through the Selections | To choose what appears on the display | To navigate between menu items |
|---|--|---|---|
| Press Select . Two left characters blink. | Press Next or Previous . Continue pressing Next to view all selections. | Press Select . Blinking characters become static. | Press Next or Previous . Advance - press Next Previous - press Previous |

Table 4: Installer Menu Settings for SENSOR Inputs

| UL 325 HySecurity Gate Operator | Build Year 2016 (BY set) | Installer Menu Settings for STC & SDC Sensors 1, 2, or 3 (solo operators) | | | | | | | |
|---------------------------------|--------------------------|---|-------------|--------------|---------------|-------------|--------------|-------------------------|------------------------|
| | | #0 DISABLED | #1 NOT USED | #2 EYE CLOSE | #3 EDGE CLOSE | #4 EYE OPEN | #5 EDGE OPEN | #6 EDGE BOTH DIRECTIONS | #7 EYE BOTH DIRECTIONS |
| SlideDriver (fixed speed) | 2 | ● | ● | ● | ● | ● | ● | | ● |
| SlideDriver VFD | 2 | ● | ● | ● | ● | ● | ● | | ● |
| SlideSmart DC 15 | 2 | ● | ● | ● | ● | ● | ● | | ● |
| SlideSmart DC 10 | 2 | ● | ● | ● | ● | ● | ● | | ● |
| SwingRiser | 2 | ● | ● | ● | ● | ● | ● | ● | |
| SwingSmart DC | 2 | ● | ● | ● | ● | ● | ● | ● | |
| HydraSwing | 2 | ● | ● | ● | ● | ● | ● | ● | |
| HydraLift | 2 | ● | ● | ● | | | | | |

NOTE: NOTE: HySecurity does not update software for SlideWinder models.

Supply Power to the Sensors



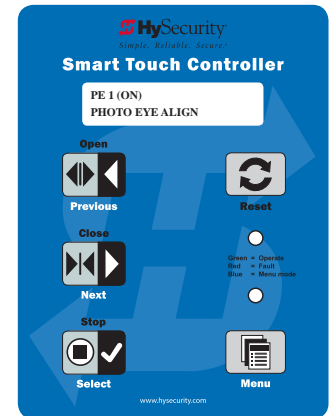
All external entrapment protection sensors must be wired to the SENSOR COM terminal for monitoring purposes.

Review sensor wiring diagrams found in *Wiring HySecurity Sensors: Smart Touch* on page 138.

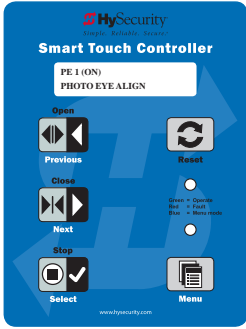

Until the gate operator receives a command to run (open or close command), the sensors are not receiving power (pre-h.4.56 and h.5.57 software). However, to **temporarily** power sensors and check that the gate operator is monitoring the sensors properly, turn on Photo Eye Align mode.

To turn on Photo Eye Align mode, take the following steps:

1. Access the User Menu and select PE. (Press the Menu button twice to access the User Menu. See *Menu Mode Navigation Buttons* chart on the previous page.)
2. Press NEXT and continue to press NEXT until PE 0 (OFF) appears.
3. Press SELECT.
4. To turn ON photo eye alignment and temporarily power the sensors, press NEXT so PE 1 (ON) appears.
5. Press SELECT.
6. Press MENU to exit Menu Mode and return to Run Mode.



NOTE: The Photo Eye Align mode turns OFF with the next limit contact. For more information, see *Photo Eye Alignment Feature* on page 102.

| Controller | Temporarily apply Power to Sensors | LED Status |
|---|---|--|
| Smart Touch (Hydraulic gate operators) | PE 1 (ON) PHOTO EYE ALIGN  | LEDs next to the sensor connections will be lit when no power is being applied. When PE is turned ON, the LEDs turn off. If they do not turn off, check for wiring issues such as a short or misapplied relay COM connections. See CAUTION on page 43. |
| Smart DC (electromechanical gate operators) | PE 1 (ON) PHOTO EYE ALIGN  | When set to 1, operator serves as an aide in photo-eye emitter/receiver alignment. Buzzer chirps once when emitter and receiver are not aligned. When emitter and receiver are aligned, buzzer chirps twice. If they go out of alignment again, buzzer will chirp once. Alignment Mode is reset with a limit input or reset input. |

Control Panel Overview

This section provides an overview of the electrical controls found in your gate operator. The illustrations highlight the various components and describe their function. Each callout explains where to find more information about the component.

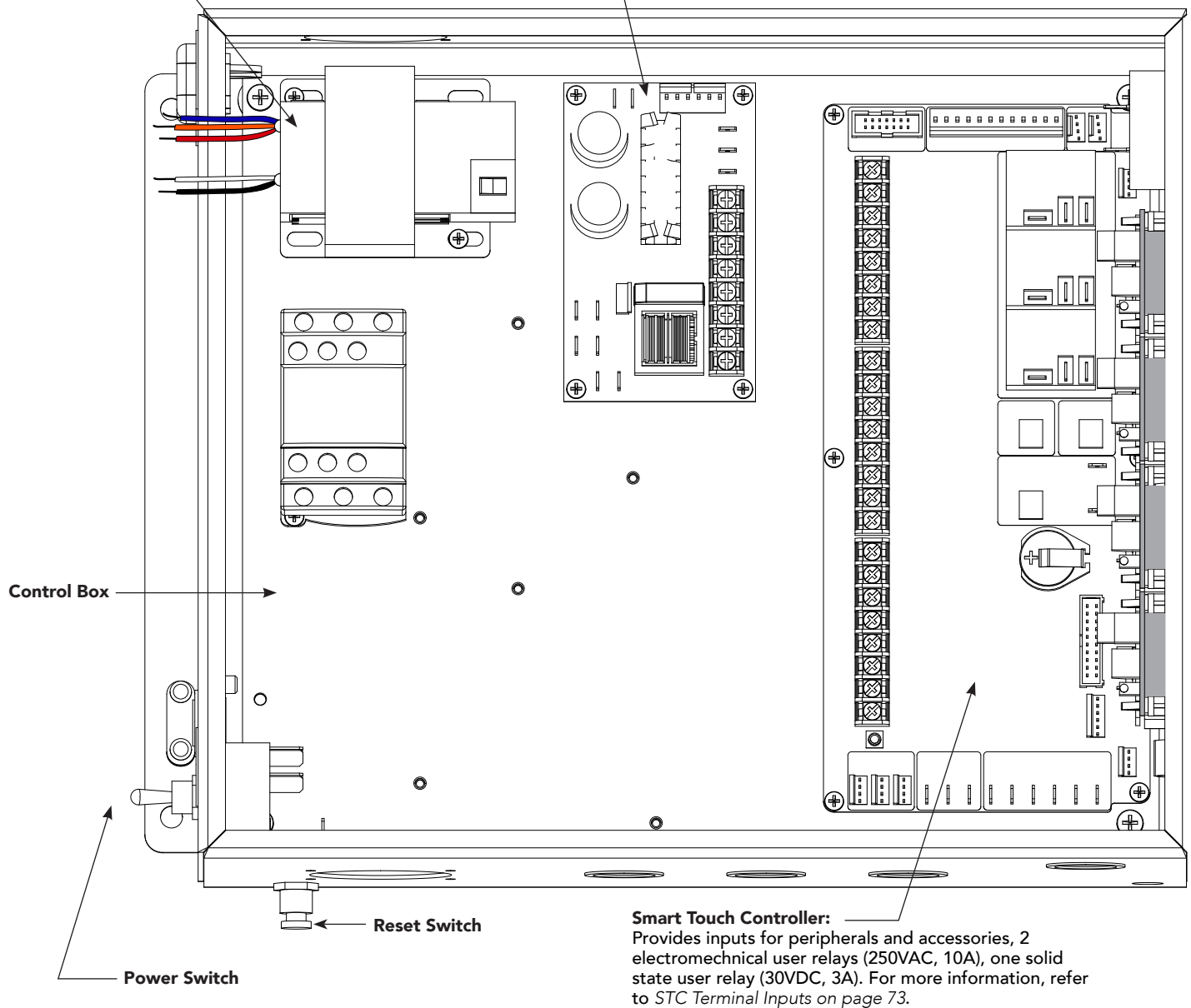
SlideDriver Models: All, except 50VF-series

Transformer:

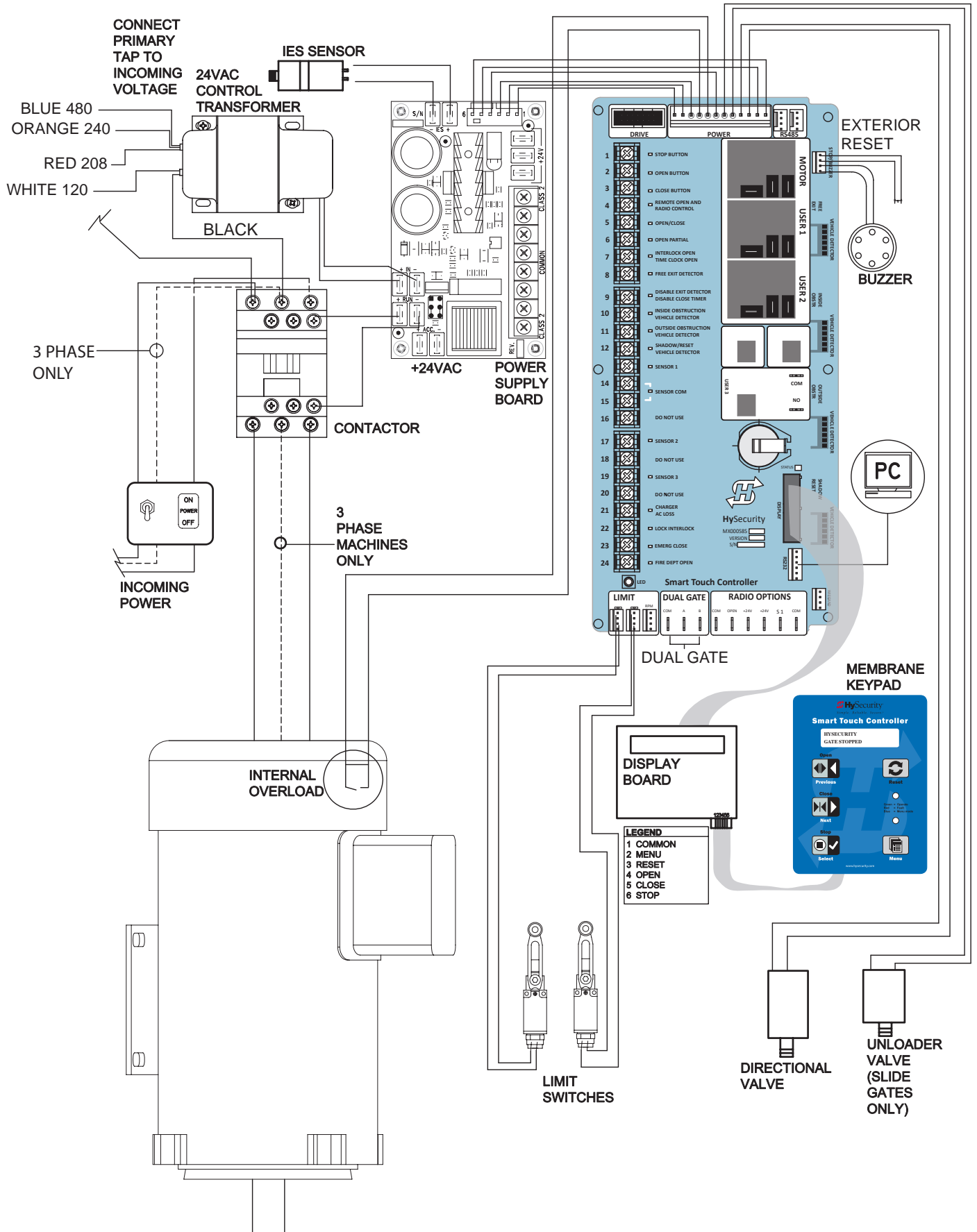
Provides the connections for AC power and steps down the voltage to 24VAC. For more information, refer to *Control Transformer Connections (Non-UPS)* on page 28.

Power Supply Board

Provides common and 24VAC & 24VDC terminals. Refer to *Overview of the STC and Power Supply Board* on page 71.



SlideDriver Wiring Diagram, D0266 REV B



Variable Speed Drive (VFD) Control Box

SlideDriver 50VF Models

Variable Frequency Drive (VFD): Controls motor speed for smooth acceleration & deceleration and connects to the STC through ModBus communication wires for diagnostics and control.

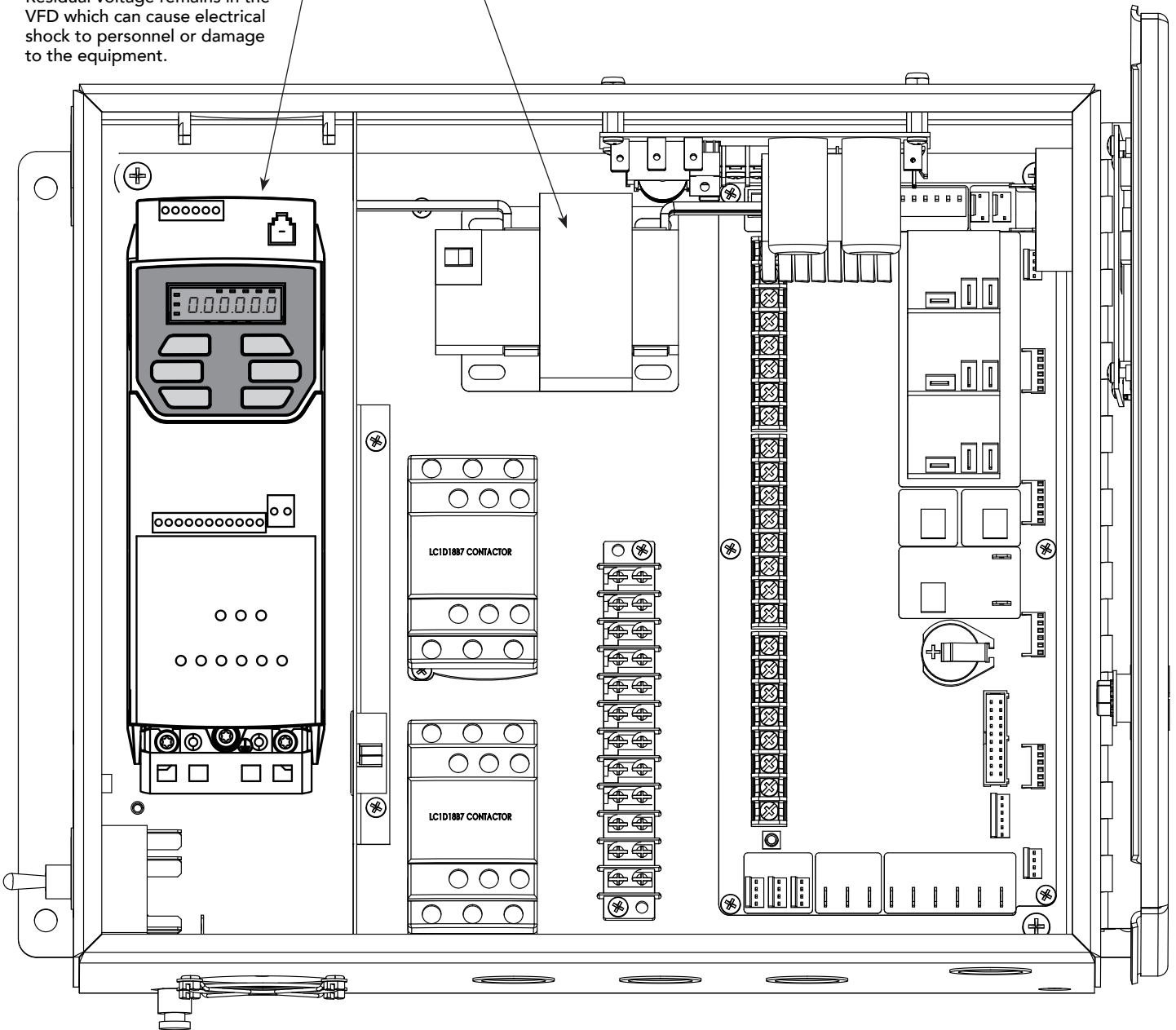


Residual voltage remains in the VFD which can cause electrical shock to personnel or damage to the equipment.

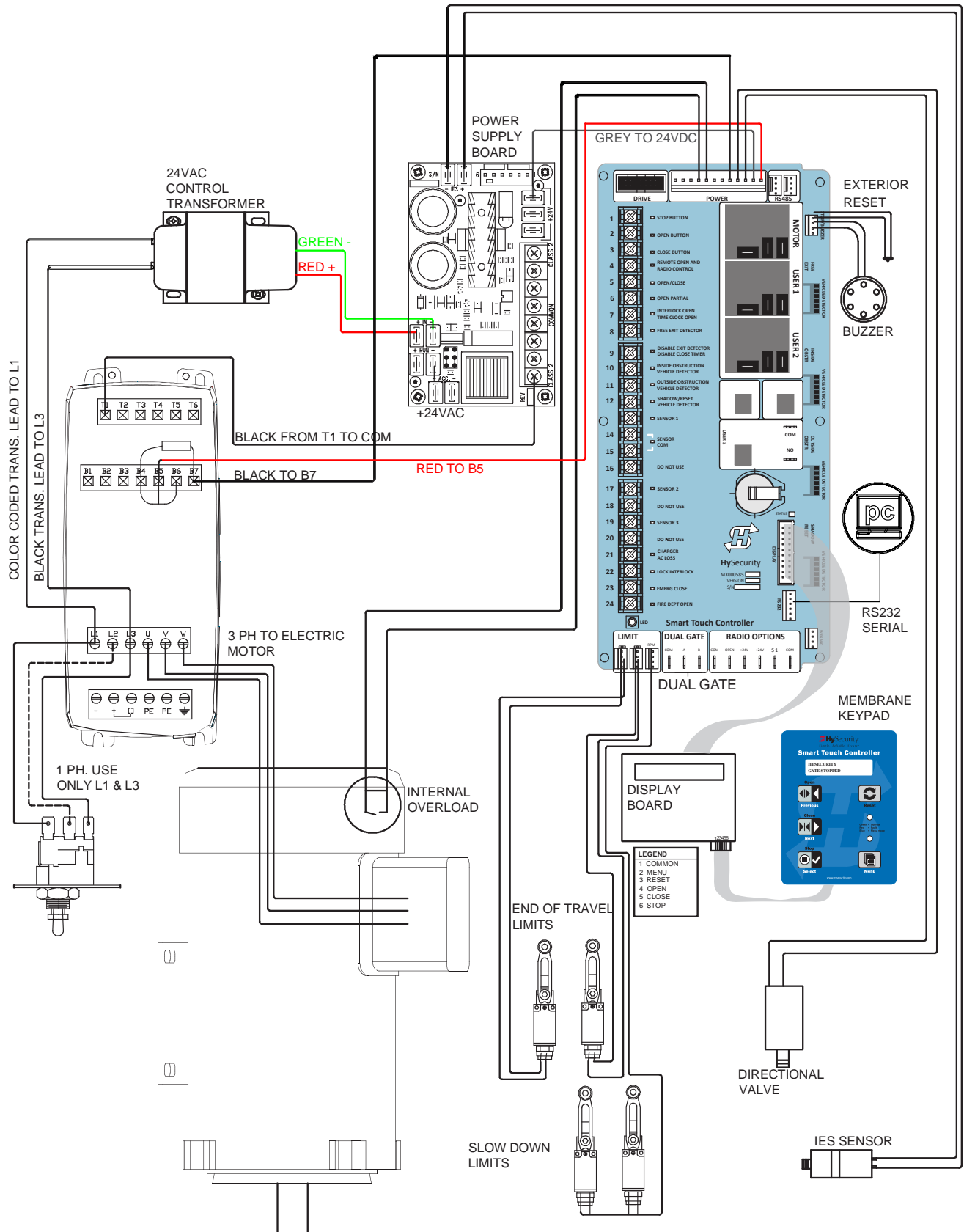
Transformer: Provides the connections for AC power and steps down the voltage to 24 VAC. For more information, refer to *Control Transformer Connections (Non-UPS)* on page 28.



* On VFD operators, never connect to the white 120V wire. Make sure the connection wires match the voltage label found on the operator's name plate.



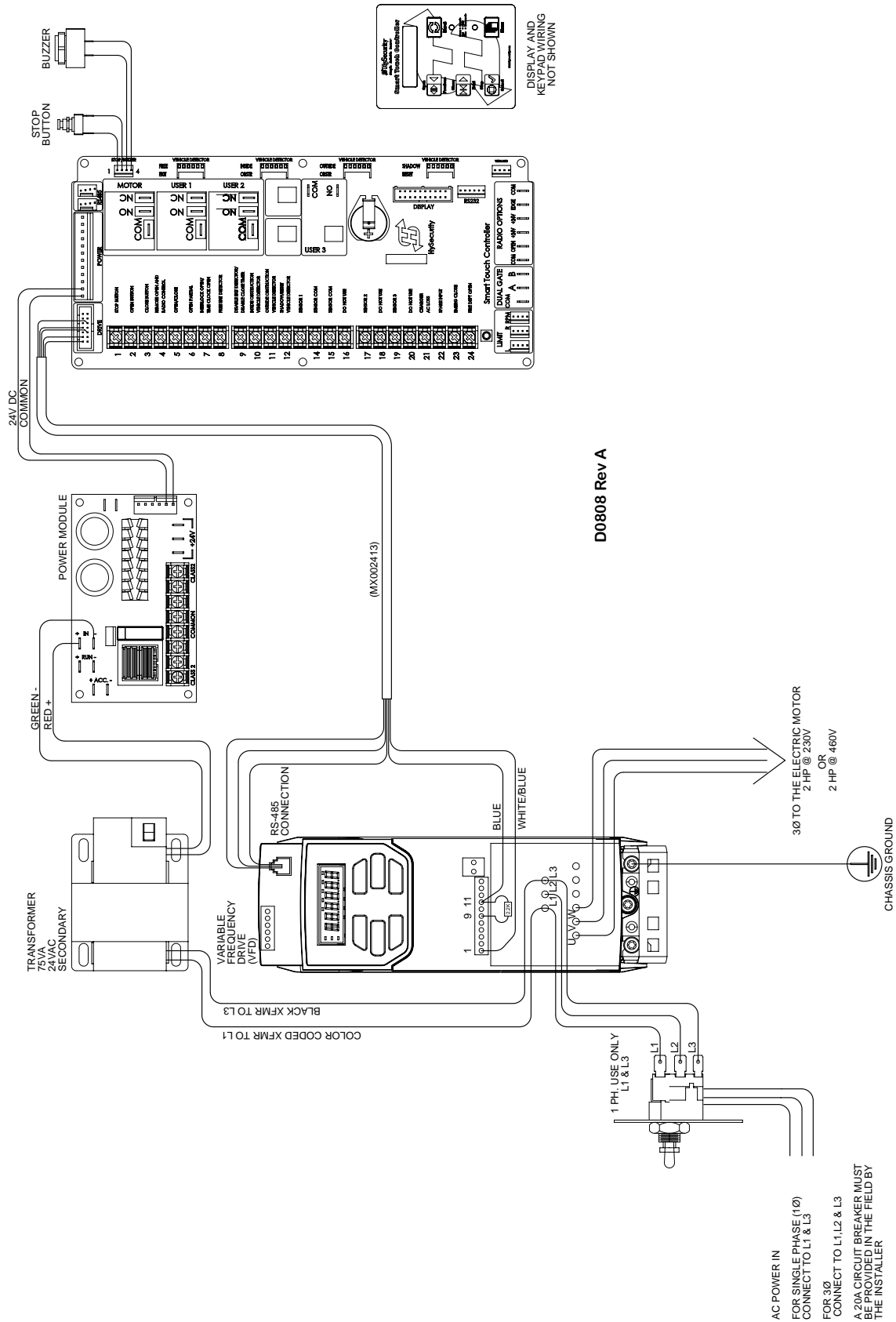
Variable Speed Drive Wiring Diagram, Pre-2012



NOTE: DRAWING IS NOT TO SCALE.

Variable Speed Drive Wiring Diagram, since 2012

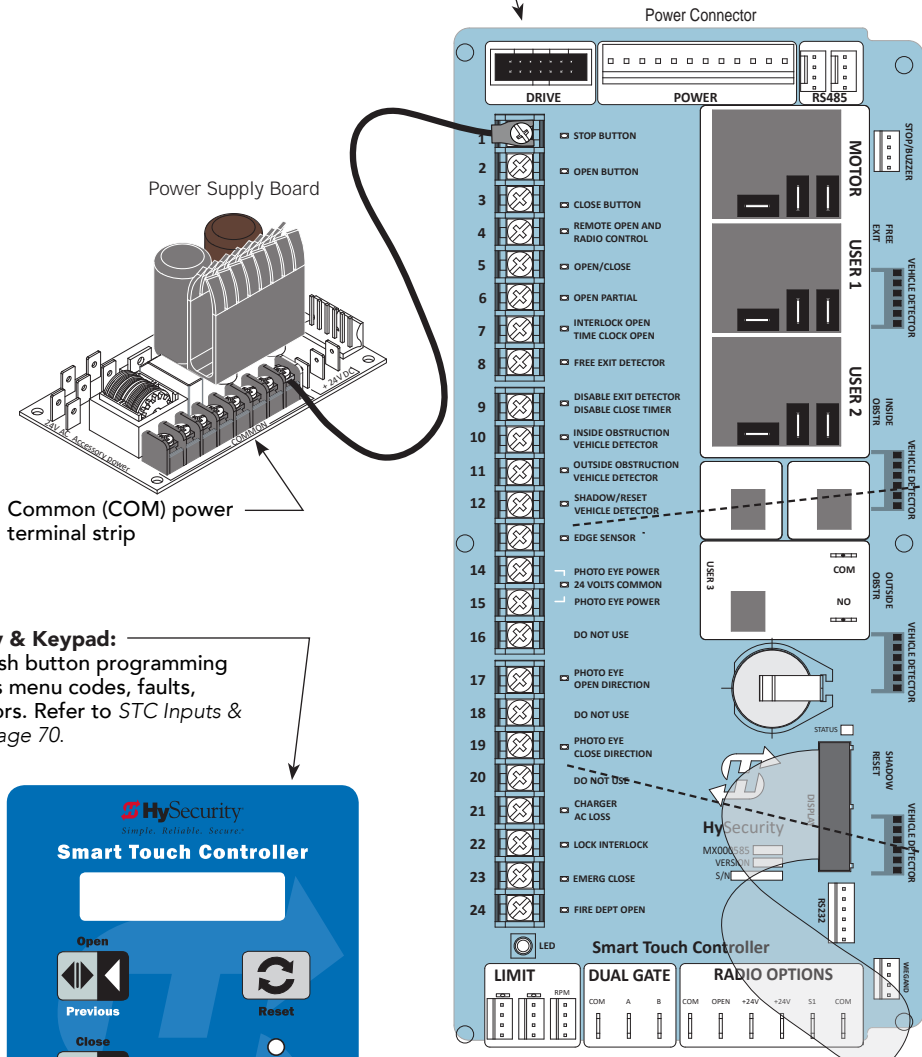
NOTE: The VFD manufacturer released an upgrade in May 2017, and this is shown in the wiring diagram below. Previously, the VFD shown on page 49 was used and wired for ModBus control. Refer to Technical Bulletin located on the [HySecurity website](http://HySecurity.com) for more information.



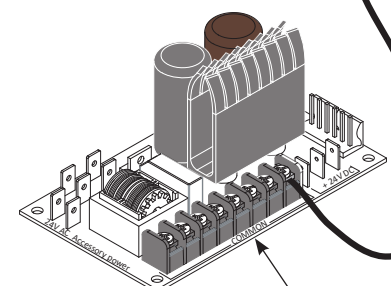
STC Board, Power Supply Board and Display

The Smart Touch Controller provides connections for a multitude of peripherals and accessory devices. The Power Supply Board offers 8 common bus terminals, 4 terminals (24VAC) and 3 terminals (24VDC) with a 3A maximum draw. The touch-sensitive keypad and 32-character display connects to the STC with a waterproof ribbon cable. For more information about STC Inputs and connections, refer to *STC Inputs & Wiring* on page 70. For more information about the display programming, operator modes and keypad navigation, refer to *Display & Menu Options* on page 52.

Smart Touch Controller:
Provides inputs for peripherals & accessories, 2 electro-mechanical user relays (250VAC, 10A), one solid state user relay (30VDC, 3A). For more information, refer to *STC Inputs & Wiring* on page 70.

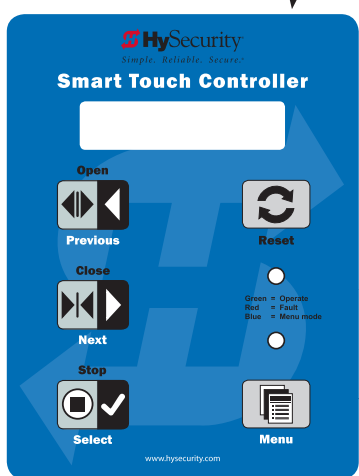


Power Supply Board



Common (COM) power terminal strip

STC Display & Keypad:
Provides push button programming and displays menu codes, faults, alerts & errors. Refer to *STC Inputs & Wiring* on page 70.



| Post - 2016 (UL 325) Label | Pre - 2016 Label |
|----------------------------|---|
| SENSOR 1 | EDGE SENSOR |
| SENSOR COM | PHOTO EYE POWER 24 VOLTS COMMON PHOTO EYE POWER |
| DO NOT USE | DO NOT USE |
| SENSOR 2 | PHOTO EYE OPEN DIRECTION |
| DO NOT USE | DO NOT USE |
| SENSOR 3 | PHOTO EYE CLOSE DIRECTION |

Updated silk screen label incorporated January 2016.

Ribbon cable

Display & Menu Options

Highly sophisticated software provides three different modes of operation: *run*, *program*, and *fault*. How to navigate using the Smart Touch Controller (STC) keypad, interpret status display codes and program the operator is found in this section.



Keep your operator current with the latest software version. If your gate operator was manufactured in 2016 (or later), it must monitor external entrapment protection sensors to be compliant with UL 325 - 2016 Standard of Safety.

Understanding the Display and Keypad

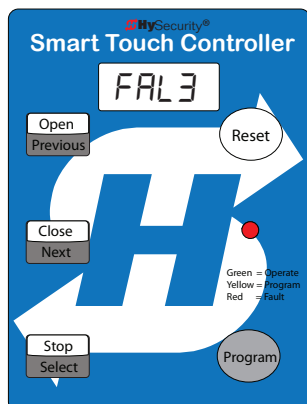
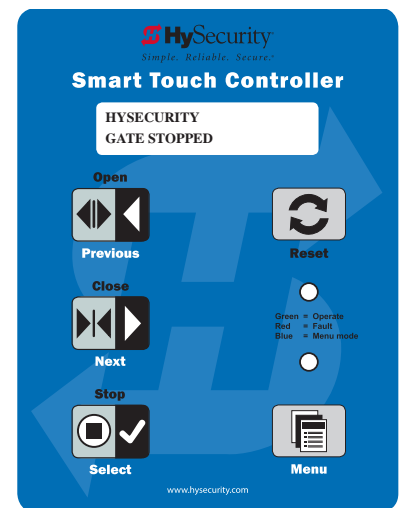
All system settings are performed using just four programming buttons and an easy-to-read 32 character display (OLED). RS-232 and RS-485 ports provide connections for external communication. A real time clock and an EEPROM logs events.

The STC display and keypad provide access to the operator's sophisticated software and functionality.

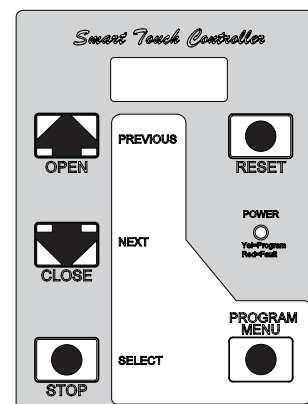
Three different operational modes exist:

- Run Mode – gate is operational, awaiting commands.
- Menu Mode – motor disengages and operator commands are ignored. Data entry, menu navigation, and menu selection can be accomplished via the keypad or through a START software connection using the RS-232 port.
- Fault Mode – alerts, faults, or errors appear on the display. Some errors or faults can be reset with the Reset button while more serious faults require additional troubleshooting. Fault mode indicates a need for diagnosis and resolution. Refer to *Troubleshooting* on page 106.

The keypad lets you navigate, change, or clear the information in the display menus. The singular use of these keys is dependent on the operator mode. The buttons with text above and below have two functions. Use these buttons to enter operating commands or navigate through the User and Installer Menus.



Smart Touch Display/Keypad, pre 2014



Smart Touch Display/Keypad, pre 2009

Initial Setup

Once you have completed the installation of the HySecurity operator and attached the wired accessories, you're ready to program the operator. Two different approaches exist:

- Connect a laptop computer to the serial RS-232 connector and set the operator menu configurations via the S.T.A.R.T. software. Refer to the [START User Guide](#).

NOTICE: Use a laptop computer at your place of business to conveniently download the free START software from www.hysecurity.com before heading out into the field. This makes it easy to adjust and configure operator settings using a laptop in the field.

- Manually navigate through the User and Installer Menus using the four Menu Mode buttons located on the Smart Touch Controller Keypad. The instructions for performing this second option are provided in this section.

After installing a new operator, an initial sequence of set up prompts appears when you first turn ON the Control Box power switch. You need to answer the prompts before the gate operator will run. The operator is in "MENU" mode.

For example:

In the SlideDriver operator, you must set usage class, gate handing, and 3 sensor inputs.

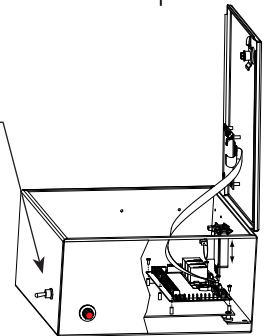
UC = **Usage Class**. Set the usage class to 1, 2, 3, or 4 depending on the site.

Four different vehicular usage classes are defined by UL 325. Information about the classes can be found online through DASMA Technical Data Sheets www.dasma.com or UL 325 www.ul.com

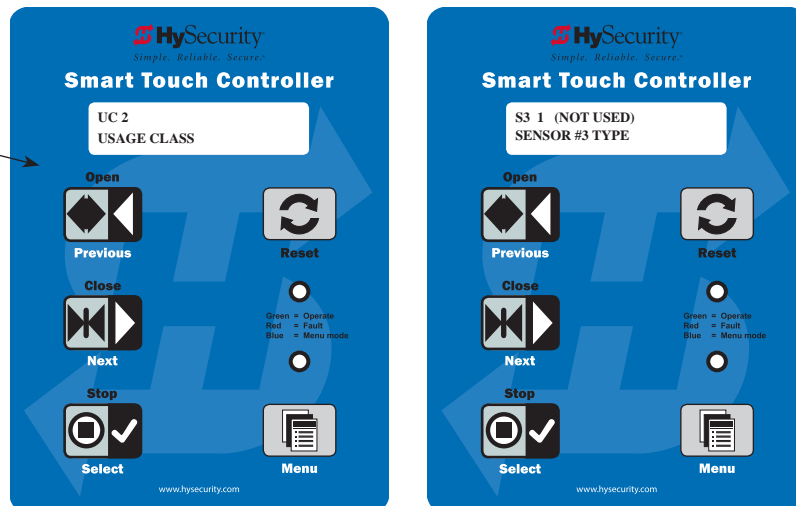
SH = Set Handing to either right or left depending on which way the gate opens when views from the secure side. S1, S2, and S3 = SContact and non-contact external entrapment protection sensor inputs that are monitored and require configuration based on the installation site and UL 325 Standard of Safety requirements.

For more information, refer to [UL 325 - 2016 Monitored Entrapment Wiring Diagrams](#) online.

Power switch on a SlideDriver control box



Selection: Usage Class
Select between: 1,2,3, or 4



Display/Keypad Showing SH Setting

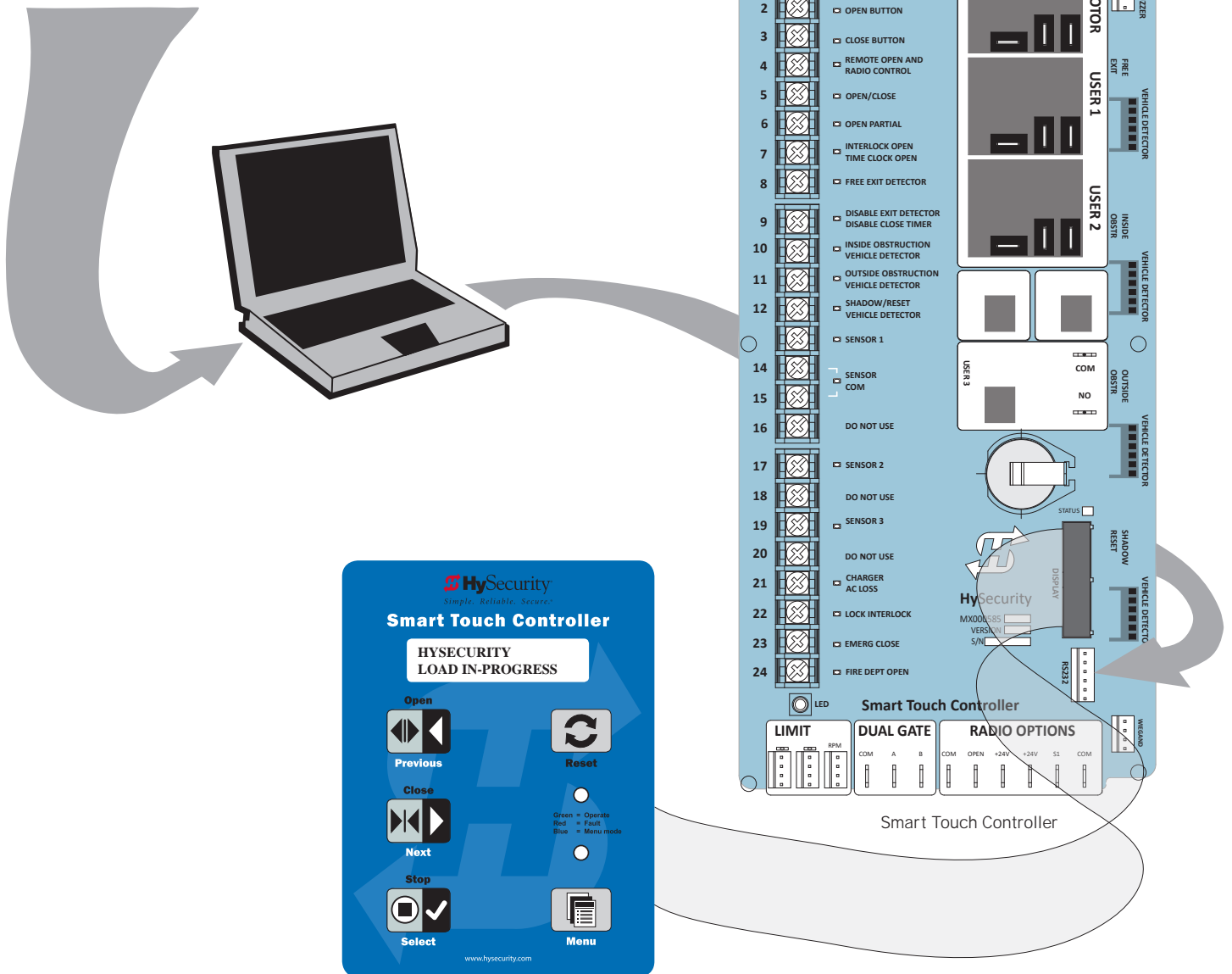
Initial Setup Using S.T.A.R.T.

With the S.T.A.R.T. application installed on your PC laptop, you can choose to set site menu configurations from the comfort of your office. Then, simply bring your PC laptop to the gate operator site, connect to the gate operator using an RS-232 to serial download cable and USB adapter, and download the configured menu settings file from your laptop to the specified gate operator.

Multiple operators can be configured in this way. No switches need to be set.

All the components are securely placed in a Control Box inside the chassis.

1. Bring up your web browser and navigate to support.hysecurity.com.
2. Click the "Software" icon on the support page.
3. Click to Download: S.T.A.R.T. software
4. See "General Maintenance" section for full instructions.



Smart Touch Controller: Downloading S.T.A.R.T. software

Menu Mode and the STC Keypad

In Menu Mode, the motor disengages and operator commands are ignored. Data entry, menu navigation, and menu selection can be accomplished using the buttons on the Smart Touch Controller keypad.

NOTE: Menu Mode automatically returns to Run Mode if no activity (i.e. key presses) occurs for two minutes.

Two blinking characters indicate that the display will accept changes.

Next or Previous Navigational buttons. Pressing Next or Previous scrolls through the selections.

Pressing **Select** causes the left most two characters to blink, (CT in the example), which indicates the display is ready to accept changes to a menu setting. Use the navigational buttons to view selections. Press **Select** a second time to accept what appears on the display. Entry mode is exited, the two characters stop blinking, and Next or Previous must be pressed to move onto a different display. Pressing Menu exits to Run mode.

32-character display provides information about the menu items.

The **Reset** button is disabled while in Menu Mode.

| LED | Function |
|-------|---------------|
| Green | = Run/Operate |
| Red | = Fault Mode |
| Blue | = Menu Mode |

The **Menu** button accesses Menu mode. When the menu item is selected and blinking, the Menu button has no function. However, pressing Menu when the 2 characters are static (not blinking), returns the operator to Run Mode.

Menu Mode Navigation

Navigating within the program menus is easy once you learn how the keypad buttons function. Refer to the following chart.

| Smart Touch Controller: Menu Mode Navigation Buttons | | | | |
|--|--|---|---|--|
| To access Menu mode | To change menu item appearing in the display | To navigate through the menu item selections | To choose what item appears on the display | To navigate between menu items |
| Press the Menu button twice. | Press Select. Two left characters blink. | Press Next or Previous. Continue pressing Next to view all selections. | Press Select. Blinking characters become static. | Press Next or Previous. Advance - press Next Previous - press Previous |

Run Mode and the STC Keypad

The Run Mode displays appear static when the operator is ready and waiting for a run command. When the display is flashing GATE OPENING or GATE CLOSING, a command has been received and the barrier gate is in motion. The command may come from a variety of sources: a card reader, push-button remote, or recognition of a vehicle passing over a loop detector. In all cases, the operator “runs” the motor when it receives an operational command.

Three displays indicate the position or status of the gate. The keypad entry used to access the User or Installer menus, begins at one of these Run Mode displays.

32-character display identifies operator status.

Pressing Open, Close, or Stop causes the gate to perform the command.

Pressing Reset clears alerts or faults and returns to Run Mode. **NOTE:** Press Reset at any Run mode status display to view the software version. For example: **h4.61**

Pressing **Menu** scrolls through operator status displays and accesses the User Menu. **NOTE:** Pressing the Menu button twice, bypasses the operator status displays.

Run Mode Displays

NOTE: To access the User or Installer menus, the motor cannot be engaged and the gate cannot be moving.

Viewing Gate Operator Scrolling Status

Press the Menu button once and the operator status displays scroll past in two second intervals. Pertinent information appears to provide a quick overview of the operator’s status or configurations.

The type of information that may scroll across the display includes: interlocked or sequenced gate (if applicable), operator type (OT), gate handing (SH), Usage Class (UC), buss voltage, and life cycle counter.

| LED | Function |
|-------|---------------|
| Green | = Run/Operate |
| Red | = Fault Mode |
| Blue | = Menu Mode |

The following chart describes a few of the scrolling status displays that may appear in your gate operator.

| Operator Status Display | Variables | Description |
|---|--|--|
| Build Year (BY) | Indicates whether the gate operator was manufactured before or after UL 325 - 2016 Safety of Standard changes that require monitoring of external entrapment sensors. | All gate operators manufactured in 2016 or later will show Build Year - Post 2016 because it contains software version h4.50. If you plan to upload 4.50 software (or later) into your gate operator, you will need to set the appropriate build year according to the date of manufacture. In h4.60 software, or later, BY 2 is for operators built between January 1, 2016 and July 31, 2018. BY 3 is for operators built after July 31, 2018. |
| Dual Gate or Sequenced Gate (Primary and Secondary) | This display only appears when the operator is used in interlocked or sequenced gate systems and indicates the function of the operator. See <i>Bi-Parting & Dual Gate Systems on page 80</i> and <i>Table 5: User Menu on page 59</i> . | Indicates, in an interlocked or dual gate setting, whether the operator is set to Primary or Secondary or Sequenced Gate Configuration). The setting is assigned in the Installer Menu. |
| Operator Type (OT) | <p>1 = SlideDriver (HSG) all models except 50VF series</p> <p>2 = SwingRiser (HRG)</p> <p>3 = HydraLift (HVG)</p> <p>4 = StrongArm (HTG)</p> <p>5 = N/U</p> <p>6 = N/U</p> <p>7 = SlideDriver 50VF</p> <p>8 = StrongArm CRASH</p> <p>9 = HydraSwing</p> <p>10 = HydraSupply XL</p> | Indicates and identifies the operator type. |
| Set Handing (SH) | L = Left and R = Right | Indicates gate handing, which determines in which direction the gate opens. |
| Usage Class (UC) | 1, 2, 3, or 4 | Displays the operator's Usage Class designation per UL 325 standards. |
| Input Voltage VDC | The number varies depending on the voltage that the power board is providing. | Input voltage (DC Buss voltage) to the STC is shown. Helps to determine proper power connections. |
| Cycle Count (CC) | One cycle equals a full open and close sequence. Partial cycles are not counted | Displays the number of cycles the gate operator has incurred. Similar to an odometer, it resets to zero after 999,999 cycles. |
| Close Timer (CT) | The first menu item in the User Menu. NOTE: You can also access the Installer Menu from this display. | Displays the number of seconds before the open gate initiates. |

Stop the Status Display Scrolling

To stop the operator status display scroll and focus on one item, press Select. Press Select a second time, to resume the scrolling display.

Change the Contrast on 7 Segment Displays

NOTE: Since sunlight does not affect readability on the OLED display, changing the display contrast is not available on models shipped with the 32 character display.

While the operator status displays are scrolling, you can change the contrast by pressing the up or down arrow keys. The display's contrast changes accordingly.

Display Power Saving Mode

To conserve energy, the display dims after a period of time if no keypress, run command or fault occurs. When an event (keypress, run command, or error/alert/fault notification) occurs, the display returns to full brightness.

Check the Software Version

Press Reset. The display indicates the software version loaded on the gate operator. To upload software, you will need a PC laptop. For more information, see *Smart Touch Analyze and Retrieve Tool (S.T.A.R.T.)* on page 122.

Check Time and Date

An easy way to determine if your operator is set for the correct date and time zone can be accomplished by taking the following steps:

1. While in Run mode (gate status appears in the display), press and hold the STOP button.
The date appears DD/MM, and then the time HH:MM.
2. If you need to change the time zone, refer to the Set Clock "CL" item in the User Menu. Refer to *Table 5: User Menu* on page 59.

User Menu

The User Menu consists of several items which can be modified using the Smart Touch Controller keypad.

NOTE: To access the User Menu, the operator must be in Run Mode. To bypass the operator status displays, press the Menu button twice.

Access:

Pressing the Menu button, while the gate status is being displayed initiates the gate operator status to scroll. When the scrolling display stop, the first user menu item appears.

The Close Timer (or HC, Hold to Close) display is the first in a cyclical series of User Menu displays.

The LED on the keypad appears blue to indicate Menu Mode.

Use the navigational buttons, Select, Next, and Previous to change or view the menu functions. Refer to the chart, *Smart Touch Controller: Menu Mode Navigation Buttons* on page 55.

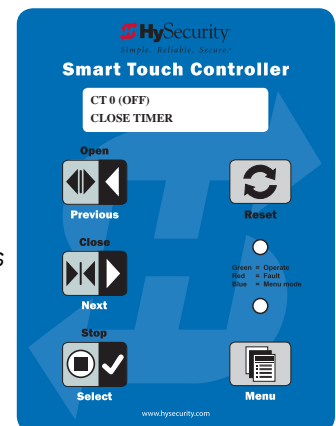


Table 5: User Menu on page 59 describes the User Menu items and supplies the factory defaults. (Factory default settings shown in bold.)

Table 5: User Menu

| User Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|-------------------------------------|---|--|--|
| CT 0 (OFF) CLOSE TIMER | 0 = (OFF) Timer disabled 1 second to 99 seconds | Assign how many seconds before an open gate initiates automatic closure. Keep setting at 0 if a hardwired, push-button control device is being used. NOTE: CLOSE TIMER display does not appear when HOLD TO CLOSE is set to 1. | Not applicable (N/A) |
| HC 0 (OFF) HOLD TO CLOSE | 0 = off 1 = on | Set to 0 produces a gate closure when a momentary signal is transmitted. Set to 1 if a constant hold to close signal, such as a push button control, is being used. A setting of 1 also deactivates automatic close timer and causes its menu to disappear. Setting HC to 1 allows compliance with UL 325 Type D protection requirements. Refer to Table Notes. | COM Close |
| HO (OFF) HOLD TO OPEN | 0 = off 1 = on | Similar to Hold to Close, but configures the Open inputs for a constant-hold function. 0 = Momentary open signal 1 = Constant hold open push button required To comply with UL 325 Type D protection, you must set HO to 1. | COM Open |
| AP 0 AC LOSS UPS FAIL OPEN | 0 = UPS FAIL OPEN 1 = UPS FAIL CLOSE 2 = AUTO OPEN 3 = NO CLOSE TIMER | This menu item only appears if the operator is DC powered. The setting configures how the gate functions when AC power fails. For more information, refer to the supplemental documentation. | COM Terminal #21 UPS Terminal strip 24 VDC to control box power disconnect switch - and + |
| RO 0 (OFF) RADIO OPEN/CLOSE | 0 = off 1 = on | Configures radio input for open only (0). If changed to setting 1 then adds capability for radio input to close gate, but only when gate is fully open. | COM RADIO Open |
| BF 2 (ON 2 SEC) WARN BEFORE OPER | 0 = off 1 = warning buzzer on throughout gate travel 2 = warning buzzer on for 2 seconds of gate travel 3 = warning buzzer on during gate travel (option 3 only on barrier arm operators) | Controls warn-before-operate buzzer and can be configured three ways: Set to 0: Buzzer is disabled. Set at 0, buzzer will still beep when alerts, faults, errors, or entrapment are detected. Set to 1: Buzzer beeps for 3 seconds before gate motion begins and continues through entire gate travel. Set to 2: Buzzer beeps for 3 seconds before gate motion begins and continues for 2 seconds of gate travel. | Not applicable (N/A) |
| FA 0 (OFF) FORCE OPEN ALERT | 0 = off 1 = on | Intended for highly secure facilities. Set to 1, the operator sounds the 3-second "warn before operate" buzzer alarm and initiates a closure if the gate is forced open and the closed limit switch disengages. The motor starts to secure the gate. If the gate does not fully close within 4s, the motor turns off and the buzzer sounds for 30 seconds. The display shows ALERT 1 - FORCED OPEN. | N/A |

| User Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|--------------------------------|--|---|--|
| DA 0 (OFF) DRIFT CLOS ALERT | 0 = off (standard) 1 = on (detailed) | Set to 1, the operator sounds the 3-second "warn before operate" buzzer alarm and initiates an open command if the gate is forced, or drifts, off the open limit switch. The motor starts to reopen the gate. The motor runs for a maximum of 4s and, if the gate is not fully open at the end of this period, the buzzer sounds for 10s. The display shows ALERT 2 - DRIFT CLOSED. | N/A |
| PE 0 (OFF) PHOTO EYE ALIGN | 0 = off 1 = on | When set to 1, operator serves as an aide in photo-eye emitter/receiver alignment. Buzzer chirps once when emitter and receiver are not aligned. When emitter and receiver are aligned, buzzer chirps twice. If they go out of alignment again, buzzer will chirp once. Alignment Mode is reset with a limit input or reset input. | Sensor 1, 2 or 3 Sensor COM |
| CL 0 SET CLOCK | 0 = off 1 = on | To set or adjust minute, hour, day, month or year, select 1. Once clock is set, display automatically returns to 0 setting. Significant gate events are logged and stamped with time and date. This feature is useful to read historical operation data, which can be accessed with a computer via USB or RS232 port or the LG setting in User Menu. | N/A |
| LD 5 LCD CONTRAST | 5 0 through 9 | Under some extreme high or low temperature conditions, it may be necessary to adjust LCD contrast. Display is adjustable from 0-9 with a factory default setting of 5. Not available with OLED display | N/A |
| LG 0 (OFF) VIEW EVENT LOG | 0 = off 1 = on | With v5.53 (or later) software, you can set LG to 1 and view abbreviated event logs on the display. These messages are helpful for diagnostic purposes and reviewing the gate operator's event history. Over 300 events can be logged before the software begins overwriting the existing history. | N/A |
| DS 0 (OFF) DIAGNOSTIC LOGS | 0 = off (standard) 1 = on (detailed) | Set this item to 1 to record all gate operator open and close events, in addition to normal alert, fault and error logs. This parameter automatically resets to the default 0 (off) after 24 hours, which is useful when experiencing intermittent problems. Set to 0, DC Controller logs pertinent gate operator events such as faults, errors, or menu manipulation. | To read the log file, an RS-232 cable and PC laptop loaded with HySecurity free S.T.A.R.T. software is required. Visit https://support.hysecurity.com |

| User Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|----------------------|---|--|--|
| PD 0 SET PASSWORD | 0 = Off 1 = On (Set Password) | NOTE: A System Address (SA) value in the installer Menu must be set before the Set Password display appears in the User Menu. To enter a password (up to 26 characters) for network connectivity, select 1. You can use the menu navigation buttons to enter the password. When the password is set, the display returns to the 0 setting. | Network: Ethernet or RS-485 HyNet configuration |

Installer Menu

The Installer Menu options provide more advanced configurations for the gate operators. Access to the Installer Menu is through the User Menu. The navigational buttons are the same in both menu modes. Refer to *Menu Mode Navigation* on page 55.

Access:

While a static gate status is being displayed, press the Menu button twice. (Bypasses the operator status displays.)

When the Close Timer display appears (Hold to Close, if the Close Timer display is hidden):

1. **Access the Installer Menu** by simultaneously pressing and holding the Reset and Open buttons.
2. Release both buttons and the display changes, indicating you have arrived at the first item in the Installer Menu.

NOTE: Installer Menu options can also be configured through the use of a laptop computer and S.T.A.R.T. software. See *Smart Touch Analyze and Retrieve Tool* information found on the HySecurity website: www.hysecurity.com

Table 6: *Installer Menu* on page 62 describes the Installer Menu items and supplies the factory defaults. (Factory settings shown in bold.)

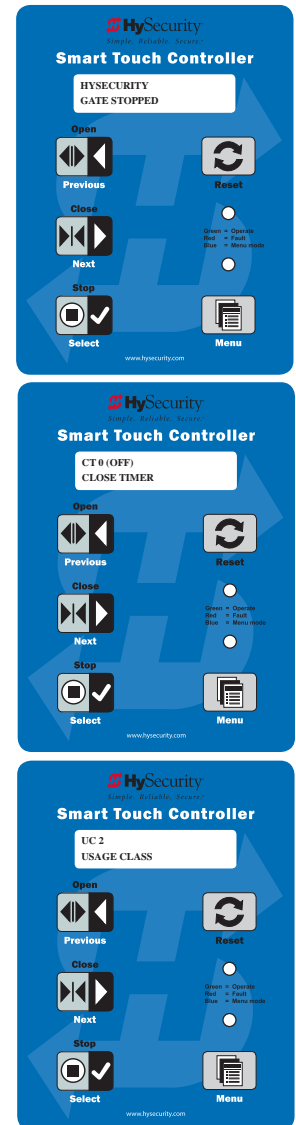


Table 6: Installer Menu

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|---|--|---|----------------------|
| OT 0 <model name> | 0 = Operator Type 1 = SlideDriver (HSG) all models except 50VF series 2 = SwingRiser (HRG) 3 = HydraLift (HVG) 4 = StrongArm (HTG) 5 = N/U 6 = N/U 7 = SlideDriver 50VF 8 = StrongArm CRASH 9 = HydraSwing 10 = HydraSupply XL | Select the appropriate number for the operator. NOTE: options 5 and 6 are not available in new firmware. NOTE: This menu item only appears if the Smart Touch Controller is being replaced. CAUTION: If you are replacing an STC board, remember to transfer the operator's menu settings from the existing board to the replacement board. Refer to the installation instructions that accompany the replacement STC board. | Not applicable (N/A) |
| AD 0 AC/DC GATE | 0 = gate disabled 1 = AC (alternating current) 2 = DC battery-power 3 = HyInverterAC – Power Supply | Usually, power type (AC or DC) is factory set. Select the type of power that the gate operator uses and is appropriately wired for. | Not applicable (N/A) |
| SP 0 SET SPEED (or indicate Modbus control) | 0 = gate disabled 1 = No ModBus communication** 2 = 2 ft/s 3 = 3 ft/s **NOTE: A setting of 1 indicates no ModBus communication or wiring is present. The VFD uses its factory settings to control speed. This setting is used in pre 2012 operators. | NOTE: This menu item only appears if the SlideDriver operator is part of the 50VF series. It does not appear with any other operator type. Set the maximum speed for the gate. CAUTION: Slow Down extended limit ramps must be installed on the drive rails! <i>See SlideDriver Standard and Slow Down Limit Ramps on page 33.</i> | N/A |
| LL 0 LEARN LIMITS | 0 = Normal operation 1 = Reset limits | A setting of 1 places operator into its learn limits mode which allows you to reset gate's open & close positions (OT8 and OT9 only). | |
| UC 0 USAGE CLASS | 0 = gate disabled 1 = single family dwelling 2 = multi-family 3 = industrial * 4 = guarded location * *not serving the general public | Assign operator's Usage Class designation per UL 325 standards. See "Identifying Gate Operator Category and Usage Class" on page 10. The installer must designate a usage class before operator will function. | N/A |
| SH 0 GATE HANDING | 0 = gate disabled R = Right hand L = Left Hand | Handing determines which way gate opens as you view it from operator side. | N/A |
| BU 0 LOUDEST BUZZER | 0 = buzzer not set 1 = Frequency 1 * (on) 2 = Frequency 2 * (on) *Select the loudest buzzer | Usually, set at the factory. If menu item appears, select either buzzer 1 or 2. Make sure to choose the loudest audible buzzer sound for your operator type. | N/A |
| FD 0 (OFF) FACTORY DEFAULTS | 0 = user settings (custom) 1 = reload factory settings | Globally restores all menu settings back to new operator status. Select setting 1 to return operator to factory defaults. NOTE: If factory defaults are restored, the UL usage class, handing, and any other modified menu settings will need to be reprogrammed. | N/A |

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|---------------------------------------|---|---|---|
| DG 0 (OFF) DUAL GATE | 0 = solo operator (off) 1 = Secondary unit 2 = Primary unit 3 = Sally Port A 4 = Sally Port B | Configures gate operator as a Primary or as a Secondary in a dual-gate installation. When you assign one unit as Primary, you must configure other as Secondary through Installer Menu. This menu is also used to configure a Sally Port system by setting one operator to Sally Port A and the other to Sally Port B. | Dual Gate COM (Gate 1) to Dual Gate COM (Gate 2) A to A B to B |
| SG 0 (OFF) SEQUENCED GATE | 0 = off 1 = Loop View #1 2 = Loop View #2 3 = Loop View #3 4 = Loop View #4 | Establishes communication after wiring two gate operators as sequential gates. This SG menu item only appears if the Dual Gate menu item (DG) is set to 0 (solo operator). NOTE: After selecting SG settings, consider accessing the User Menu in each gate operator to address the Close Timer (CT) setting. | Connect Dual Gate COM (Traffic Gate) to Dual Gate COM (Security Gate) A to A B to B |
| CH 0 (AC) CHARGER TYPE | 0 = AC powered charger 1 = Solar powered charger | Assigns charger type usually set at factory. If set to solar at factory then this menu item is hidden. | |
| FO 0 (DISABLED) FIRE DEPT OPEN | 0 = disabled 1 = enabled | Provides the Fire Dept. Open input. When set to 1, the open signal received by the operator overrides all photoelectric eyes and edge sensors, and opens the gate. Pressing the Open or Reset button is required before the gate can be closed. | +24V Fire Dept Open (#24) |
| OC 0 (DISABLED) EMERGENCY CLOSE | 0 = disabled 1 = enabled | Enables the Emergency Close input. When set to 1, the constant hold close overrides vehicle detectors, photo eyes and edge sensors, and closes the gate. Gate stops on the close limit in Entrapment Mode. Pressing the Reset button once or the Open button twice is required before the gate will open. | +24V EMERG CLOSE (#23) |
| SE 2 IES SENSITIVITY | 0 = maximum sensitivity 6 = recommended minimum sensitivity 9 = minimum sensitivity 2 = default sensitivity | Adjusts the sensitivity of the inherent entrapment sensor. Available settings are 0-9 with 0 being the most sensitive. HySecurity strongly recommends that you avoid setting IES sensitivity higher than 6. NOTE: Before changing IES sensitivity, make sure that gate rolls smoothly without obstruction. Fix any issues with gate hardware. | N/A |
| SS 0 IES STOP ONLY | 0 = (off) Stop and reverse for 2s 1 = (on) stop only | A setting of 0, stops the gate and then reverses its direction of travel for 2 seconds. To stop gate travel with no reversal, the optional setting 1 can be selected if the gate operator is at a Usage Class IV site and assigned a UC 4 classification. | N/A |

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|------------------------------------|---|---|--|
| LC 0 LEAF DELAY CLOSE | 0 = none 1 through 20 in ½ second increments For example: 1 = ½ second 10 = 5 seconds 20 = 10 seconds | Only appears if gate operator is set up as a Primary or a Secondary. Available settings are 1 through 20. Each increment adds ½ second time delay following a command to close before operator begins closing. Provides up to a 10 second time delay. | |
| LO 0 LEAF DELAY OPEN | 0 = none 1 through 20 in ½ second increments For example: 1 = ½ second 10 = 5 seconds 20 = 10 seconds | Only appears if gate operator is set up as a Primary or a Secondary. Available settings are 1 through 20. Each increment adds ½ second time delay following a command to open before operator activates. Provides up to a 10 second time delay. | |
| RT 0 (60 SECS) MAXIMUM RUN TIME | 0 = 60 Seconds max run 1 = 300 Seconds max run | Assigns a motor run time of 60 or 300 seconds. If the gate opening or closure takes longer than 60 seconds, you'll need to set the run timer to 1. | N/A |
| PO 0 (OFF) PARTIAL OPEN | 0 = none 7 to 99 seconds | Sets distance (from closed gate position) where gate stops if the partial open input is activated. When a number is entered in PO display, open partial input becomes operational. | Open Partial #6 COM |
| EC 0 STOP ONLY EYE CLOSE LOGIC | 0 = Close eye stops only 1 = Two second reversal to open 2 = Reverse to full open. | Default setting is non-reversal if close photo eye is triggered while closing. A setting of 1 causes gate to reverse toward open for two seconds if triggered while closing. A setting of 2 reverses the gate to full open. | .Sensor 1, 2, or 3 Sensor COM COM +24V |
| EO 0 STOP ONLY EYE OPEN LOGIC | 0 = Open eye stops only 1 = Two second reverse to close | Default setting is non-reversal if open photo eye is triggered while opening. A setting of 1 causes gate to reverse travel and close for two seconds if triggered while opening. | Sensor 1, 2, or 3 Sensor COM COM +24V |
| GR 0 FULL OPEN GATE EDGE LOGIC | 0 = Edge reverses fully open 1 = Two second reversal only | Default setting is a full-open reversal if gate edge is triggered while closing. Optional setting of 1 causes gate to reverse for two seconds if triggered while closing. Gate Edge Open always reverses to full close when all loops and close direction sensors are clear to prevent a gate from being stuck in mid-travel. | Sensor 1, 2, or 3 Sensor COM +24V 10K resistor (Edge) |
| SR 1 REVERSE 25 REVERSAL LOGIC | 0 = IES reverses fully open 1 = Two second reversal only | Default setting is a two-second duration reversal if inherent sensor is triggered. Optional setting of 0 will cause gate to reopen fully if triggered while closing. | N/A |
| S1 0 SENSOR #1 TYPE | 0 disabled 1 (NOT USED) 2 (EYE CLOSE) 3 (EDGE CLOSE) 4 (EYE OPEN) 5 (EDGE OPEN) 6 (EDGE BOTH) 7 (EYE BOTH) | UL 325 - 2018 sensor input setting for external entrapment protection sensor monitoring. All three sensor types must be configured to a non-zero number before the gate operator will move the gate. Edge Both is only available in Swing Gate operator types. Eye Both is only available in Slide Gate operator types. | SENSOR 1 COM +24V SENSOR COM |

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|--|--|--|---|
| S2 0 SENSOR #2 TYPE | Same as Sensor 1 | Same as Sensor 1 | SENSOR 2 COM +24V SENSOR COM |
| S3 0 SENSOR #3 TYPE | Same as Sensor 1 | Same as Sensor 1 | SENSOR 3 COM +24V SENSOR COM |
| PC 1 NO CONTACT PHOTO EYE OUTPUT | 0 = Normally Open NO input 1 = Normally Closed NC input (monitored) | This menu item only appears when UC is set to 4. Default setting is photo eyes with Normally Close outputs. Optional setting 0 requires a Normally Open (NO) output. When set for NC, connection is monitored and any short circuit fault will generate a FAULT 2 alert which requires a STOP or RESET button press to re-enable gate operation. | COM +24V COM PHOTO EYE CLOSE DIRECTION |
| GC 0 NO INPUT GATE EDGE OUTPUT | 0 = Normally Open NO input 1 = Normally Closed NC input (monitored) | This menu item only appears when UC is set to 4. Default setting is edge sensor with Normally Closed (NC) output. Optional setting of 0 requires an (NO) output. | COM +24V COM EDGE SENSOR |
| TC 1 (INTLOCK) TIME CLK/INTLOCK | 0 = TIME CLK (Select Time Clock) 1 = INTLOCK (Select Open Interlock) | Configures the input at Terminal No. 7 on the STC to be either for the gate interlock function, or for an external time clock to open input. The default setting is (TC_1) for the interlock function. | INTERLOCK OPEN (#7) COM |
| DT 0 FREE EXIT DISABLE FUNCTION | 0 = Disable Free Exit 1 = Disable Close Timer | Configures BLOCK EXIT input to disable either Free Exit Detector function or, alternately, Close Timer function. Default setting disables free exit detector. NOTE: Free exit is disabled when gate is at its closed limit. If closed limit is not tripped, free exit continues to work normally. | DISABLE EXIT DETECTOR (#9) COM |
| OR 1 REVERSE OUTSIDE OBS LOOP | 0 = Pause closing only 1 = Enable reversing to open 2 = Ignore and continue closing | Default is for full reversal when Outside Obstruction Loop is triggered while closing. A setting of 0 causes gate to only pause when triggered. Gate closure continues as soon as loop is clear again. | OUTSIDE OBS LOOP (#11) COM or connection to Hy5B detector |
| IR 1 REVERSE INSIDE OBS LOOP | 0 = Pause closing only 1 = Enable reversing to open 2 = Ignore and continue closing | Default is for full reversal when Inside Obstruction Loop is triggered while closing. A setting of 0 causes gate to only pause when triggered. Closure begins as soon as loop is clear again. | INSIDE OBS LOOP (#10) COM or connection to Hy5B detector |

NOTE: The shaded Installer Menu items do not appear when Build Year is set to 2 (BY 2). Exceptions exist for barrier arms, CRASH products, operators set to pre-2016 and Usage Class IV provisions.

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|-------------------------------------|--|--|---|
| HD 1 HOLD CLOSE Center Loop Hold | 0 = Hold Open only 1 = Hold Close and hold Open | Swing gates: Configures the function of the Center Loop (Shadow Loop) when triggered: Setting 1 - holds the gate from starting open and from starting close. This setting prevents opening and closing of the gate when the Center Loop is tripped if the gate is on either (opened or closed) limit switches. Setting 0 - holds the gate from starting closed. This setting prevents closing when on the open limit switch. | CENTER LOOP (#10) COM or connection to Hy5B detector |
| DL 1 STANDARD DETECTOR LOGIC | 1 = Standard 2 = Quick Close 3 = Fore Time Outt 4 = Full anti-tailgate | This selection determines whether close timer begins to count down after vehicles have departed detector loops or whether close timer will count down while the loops are occupied. Gate can only close when all loop detectors are clear. Used to prevent second vehicle from entering/exiting. Default settings causes Close Timer to start when all loops are clear. A setting of 2 causes Close Timer to start when open limit is reached. A setting of 3 forces the Close Timer to 0 when the OOLD and IOLD are tripped simultaneously. A setting of 4 stops the gate when OOLD and IOLD are tripped simultaneously and closes from that point when the loops clear. | |
| RL 1 1 CLOSE LIM RELAY 1 LOGIC | 1 = Default 1 to 33 available | Configures function of the user 1 output relay, which is an electromechanical relay. It has capacity to switch, both AC and DC and can be used for high voltage and/or high current loads. Connect devices directly to the top of relay: COM plus NO and NC contacts. Up to 33 optional relay functions exist. Refer to <i>User Relays – Programming Procedure on page 77</i> . | User 1 Relay |
| RL 2 6 Lock Output RELAY 2 LOGIC | 6 = Default 1 to 33 available | Configures function of the user 2 output relay, which is an electromechanical relay. It has capacity to switch, both AC and DC and can be used for high voltage and/or high current loads. Connect devices directly to the top of relay: COM plus NO and NC contacts. Up to 33 optional relay functions exist. Refer to <i>User Relays – Programming Procedure on page 77</i> . | User 2 Relay |
| R3 1 CLOSE LIM RELAY 3 LOGIC | 1 = Disabled 1 to 33 available | Configures the function of the User 3 output relay, which is an electronic relay with the capacity for switching a DC load only. In the StrongArm M30/M50, Relay 3 is connected to the gate LED lighting and does not appear as an option in the Installer Menu. | User 3 Relay |

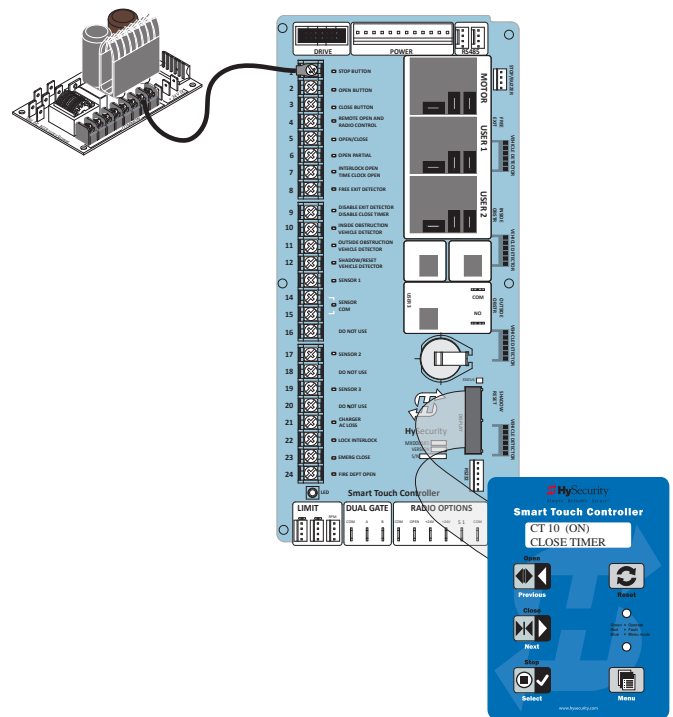
| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|-----------------------------------|---|---|---|
| R4 through R11 RELAY <n> LOGIC | 0 = Disabled 1 to 33 available | Similar to Relay 1 Logic except only NO contacts are available. NOTE: The Hy8Relay™ module option can be purchased to provide an additional 8 relay terminals. | COM NOTE: R4 through RB user relays appear on 7-segment display |
| TL 2 (45 SECS) OPEN TIME ALERT | 0 = 0s delay 1 = 15s 2 = 45 second delay 3 = 75s 4 = 105s 5 = 135s | Adjusts time delay before activating a user relay when a gate is not on the close limit. Maximum time setting is 135 seconds. NOTE: This menu controls a user relay set to Function No. 8 | User Relay 8 |
| LT 3 (75 SECS) LOITERING ALERT | 0 = 0s delay 1 = 15s 2 = 45s 3 = 75 second delay 4 = 105s 5 = 135s | This function monitors activation of Outside Obstruction Loop when the gate is closed and not running. When adjustable period of time is exceeded, User Relay option 13 triggers and reports loitering in diagnostics log. Adjust time delay before activating user relay. Maximum time setting is 135 seconds. NOTE: This menu controls a user relay set to Function No. 13 | User Relay 13 |
| SA 0 (OFF) STC ADDRESS | 0 = No network 1 to 99 Network "drop" address | Set system address for network communication: 0 = no network communication 1 - 99 sets individual polling addresses. Use addresses 1-4 when connecting to HyNet. | RS-485. Involves additional hardware & software. |
| NE 0 (OFF) NETWORK SETUP | 0 = No network (off) 1 = Network address (on) | Menu item appears when SA is not set to zero (0). If a system address exists a setting of 1 opens the network configuration menu. 0 = no network communication 1 = allows configuration of network addresses. Used with HyNet™. | RS-485. Involves HyNet™ & software. |
| ID 0 HYINVERTER DIAGNOSTICS | 0 = no diagnostics displayed 1 = view diagnostics displays HYINVERTER INPUT - LINE xxx.x VAC HYINVERTER TEMP - xxx.xF / xxx.x C HYINVERTER VOLTS - BATTERY xx.x VDC HYINVERTER - BATTERY xxx.x % | Controls which system diagnostics appear on the display. With a setting of 1, you can access the AC Power Supply with HyInverter AC diagnostic mode. Use the Next or Previous buttons, on the gate operator's keypad, to view the diagnostics on the STC display. AD setting must be set to 3 for the menu to appear. NOTE: These same diagnostics appear on the AC Power Supply with HyInverter AC display in a constant scrolling format. | AC Power Supply with HyInverter AC to STC (Modbus RTU communication protocol via RS-485.) |

| Installer Menu | Setting Options | Menu Tasks & Explanations | STC Wire Connections |
|--|---|--|----------------------|
| ELD0 RUN MODE EXIT LOOP SET | 0 = Run mode 1 = Show frequency 2 = Show call level 0-7 3 = Set Frequency | Controls Hy5A or Hy5B Free Exit detector. If an Hy5B is used, additional settings of 4-8 are available. | Hy5B |
| ILD0 RUN MODE IND OBS LOOP SET | 0 = Run mode 1 = Show frequency 2 = Show call level 0-7 3 = Set Frequency | Controls Hy5A or Hy5B Free Exit detector. If an Hy5B is used, additional settings of 4-8 are available. | Hy5B |
| OLD0 RUN MODE OUT OBS LOOP SET | 0 = Run mode 1 = Show frequency 2 = Show call level 0-7 3 = Set Frequency | Controls Hy5A or Hy5B Free Exit detector. If an Hy5B is used, additional settings of 4-8 are available. | Hy5B |
| SLD0 RUN MODE SHADOW LOOP SET (Reset Loop Set) | 0 = Run mode 1 = Show frequency 2 = Show call level 0-7 3 = Set Frequency | Controls Hy5A or Hy5B Free Exit detector. If an Hy5B is used, additional settings of 4-8 are available. | Hy5B |

Setting the Close Timer

The Close Timer assigns how many seconds will pass before the gate operator initiates closure of a fully opened gate after all open commands and reversing sensor inputs have ceased and loops cleared. It is recommended that every gate operator have the close timer set to a specific number of seconds (for example, 5 seconds) unless a hard-wired closing device is connected to the gate operator, such as a "hold to close" push button station.

To adjust the time (1 to 99 seconds) it takes before the operator initiates gate closure, take the following



steps:

1. At a gate status display, press the Menu button twice. This accesses the User Menu and the Close Timer display appears.
NOTE: If you want gate personnel to operate the gate with the Hold to Close feature found in some push button stations, then set the Hold to Close menu item to 1. When the Hold to Close menu item is active (set to 1), the Close Timer menu item is unavailable.
2. Use the Select, and then Next or Previous buttons to navigate and change the number of seconds appearing on the display. Refer to *Menu Mode Navigation on page 55*.
3. To exit the User Menu, press the Menu button. The gate status appears in the display indicating you have returned to Run Mode.

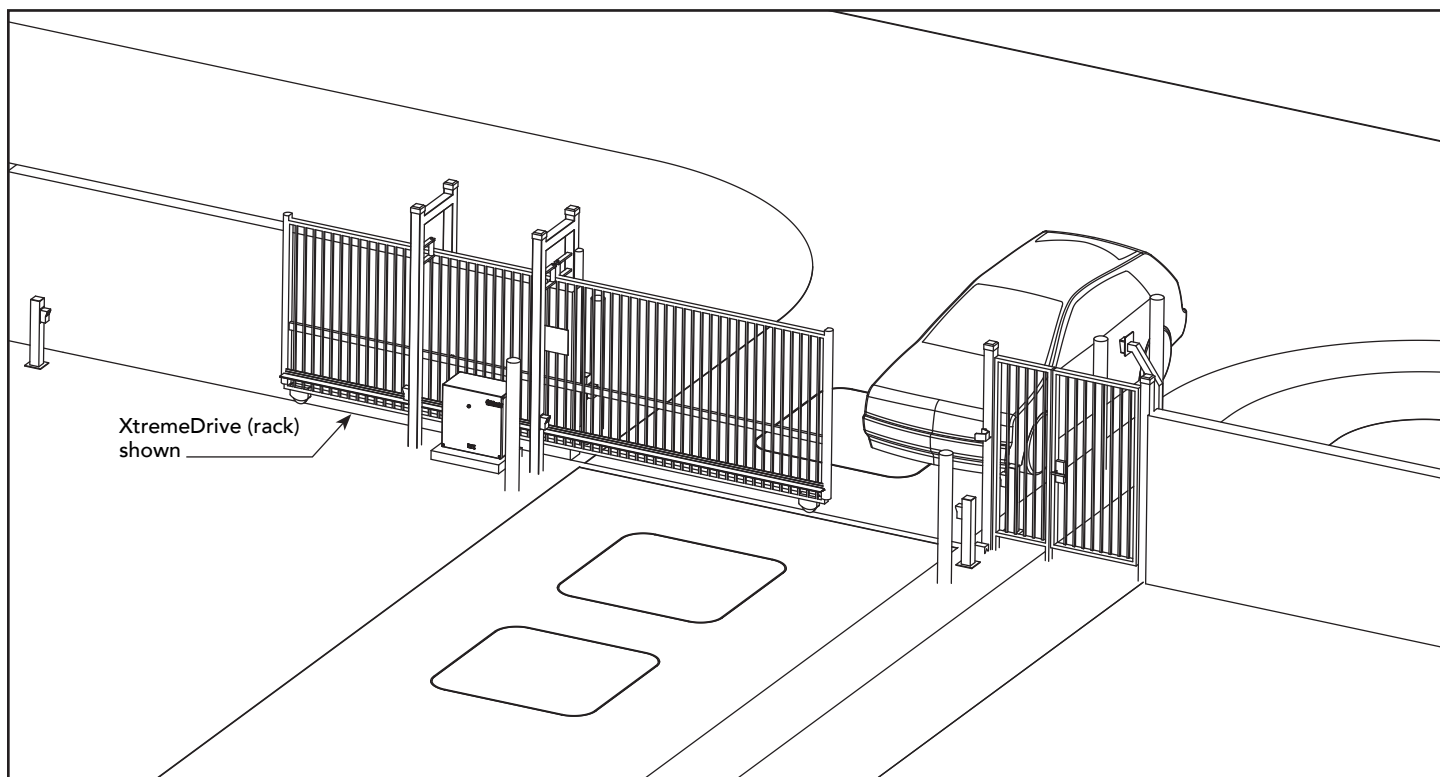
Test the Operator

Complete the installation by testing the operation of the gate.

NOTE: The operator must be turned on and in Run mode. A Run mode display appears on the STC. If a Run mode status does not appear on the display, press Reset. If an error, alert, or fault appears on the display, refer to the *Troubleshooting* section to learn how to clear the display and return to Run mode.

1. Press Open to open the gate.
2. Test the operator.
 - Cycle the gate a few times by pressing the Close and Open buttons.
 - If installed for emergency fast operation, test the EMERGENCY CLOSE using the constant hold device. Observe the travel speed of the gate when you press and hold the Emergency Close button. It will close a second or two faster than normal operation and ignore any photo eye, vehicle loop, or other safety sensor inputs.

NOTE: If additional accessories are to be added, read about *STC Inputs & Wiring on page 70*.

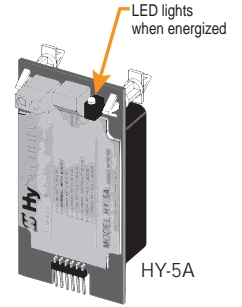
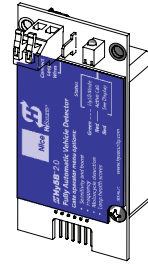


STC Inputs & Wiring

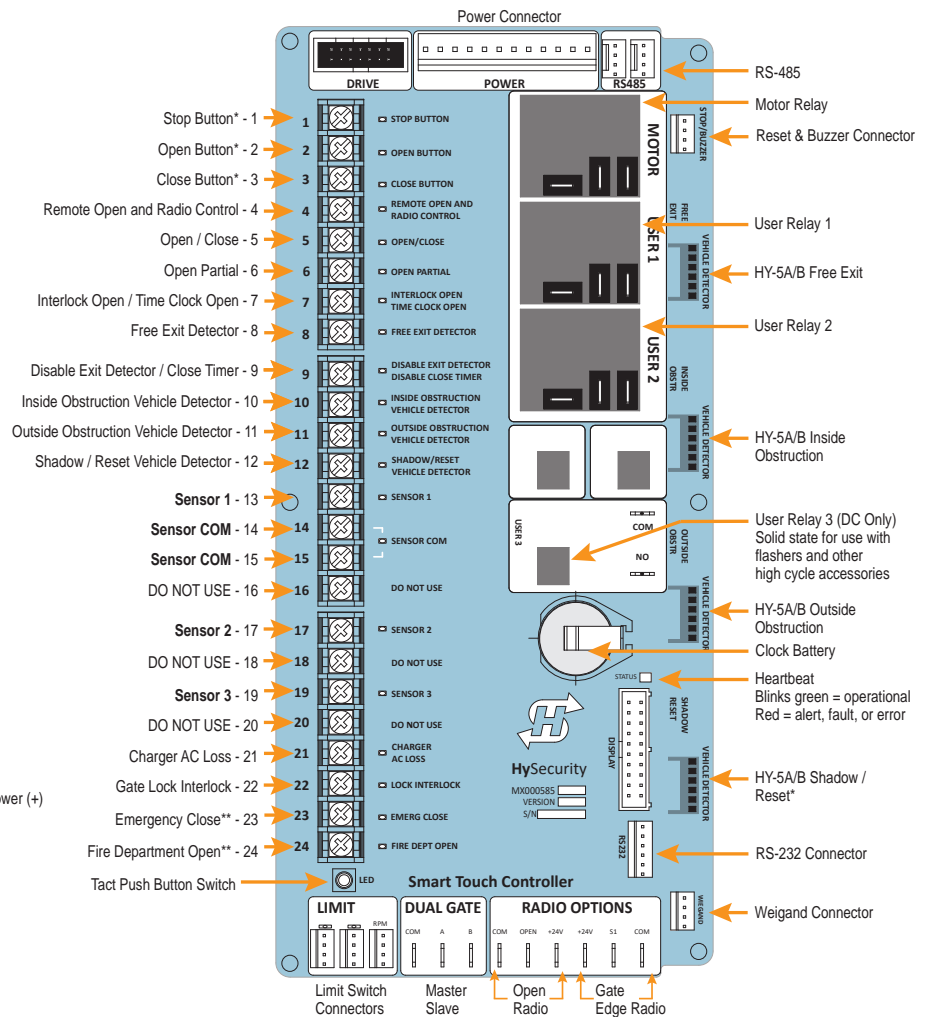
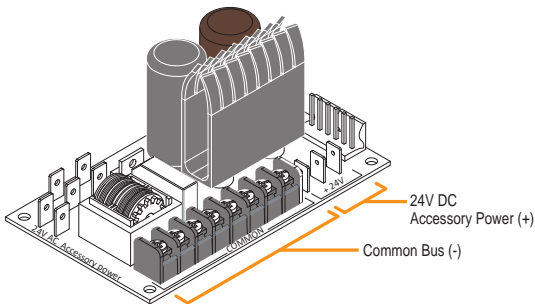
This section provides information about the Smart Touch Controller, its inputs for peripheral connections, and its monitoring capabilities. This section explains how to:

- Make Connections on the Smart Touch Controller
- Integrate with Security Systems
- Adapt User Relays for your Gate Site

Hy5B
Refer to the [HySecurity website](http://www.hysecurity.com) for more information about Hy5B installation and use.



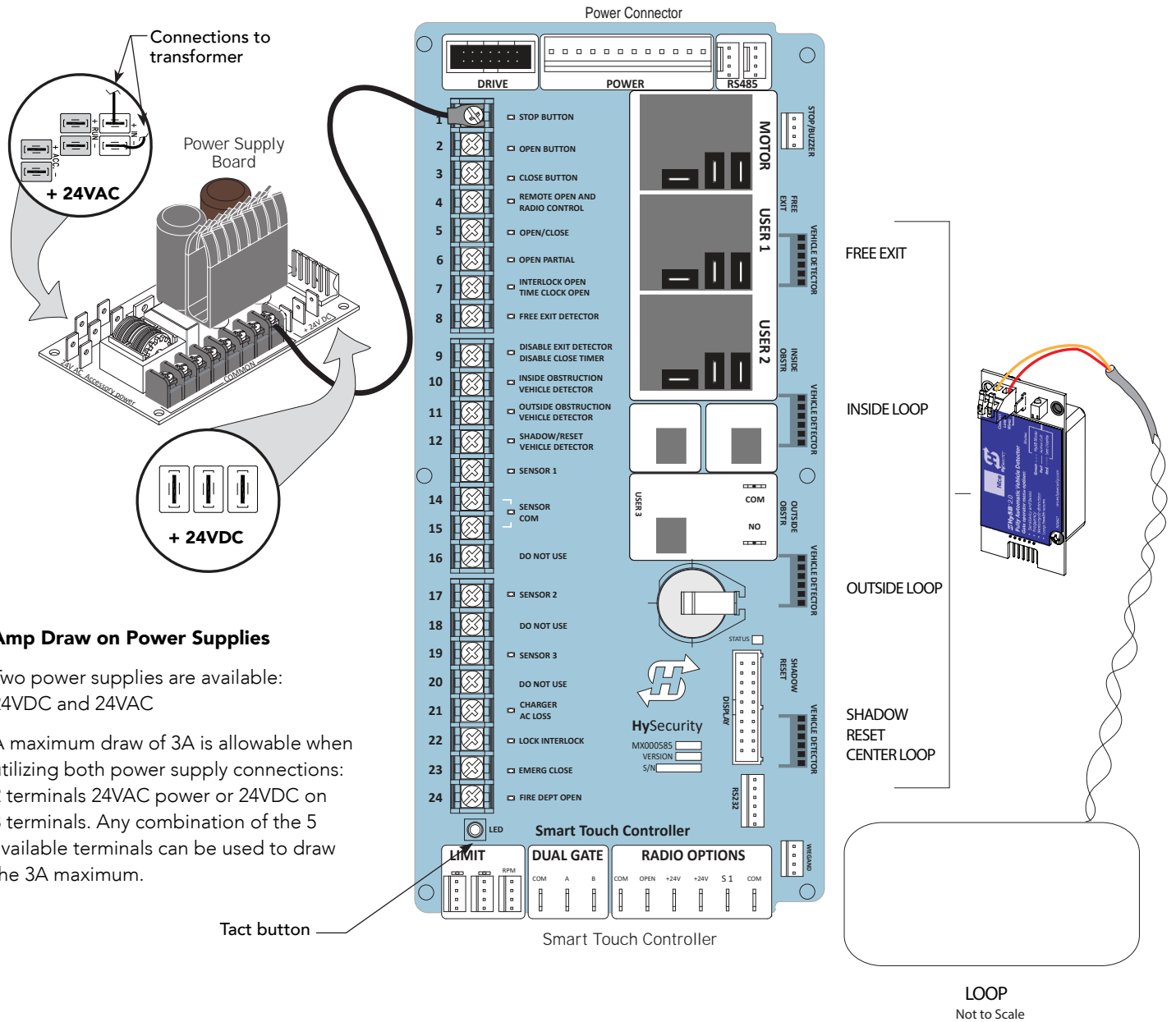
Power Supply Board



Overview of the STC and Power Supply Board

The Smart Touch Controller uses LED's to indicate active inputs when AC power is present. For operators that use only DC power, you can push a Tact push button to show the active inputs. This Tact push button is at the bottom left corner beneath the #24 terminal input.

On a new operator, no active inputs should appear until external accessories and wiring are attached. If any inputs are active before connecting external wiring, refer to *Troubleshooting on page 106*.



Amp Draw on Power Supplies

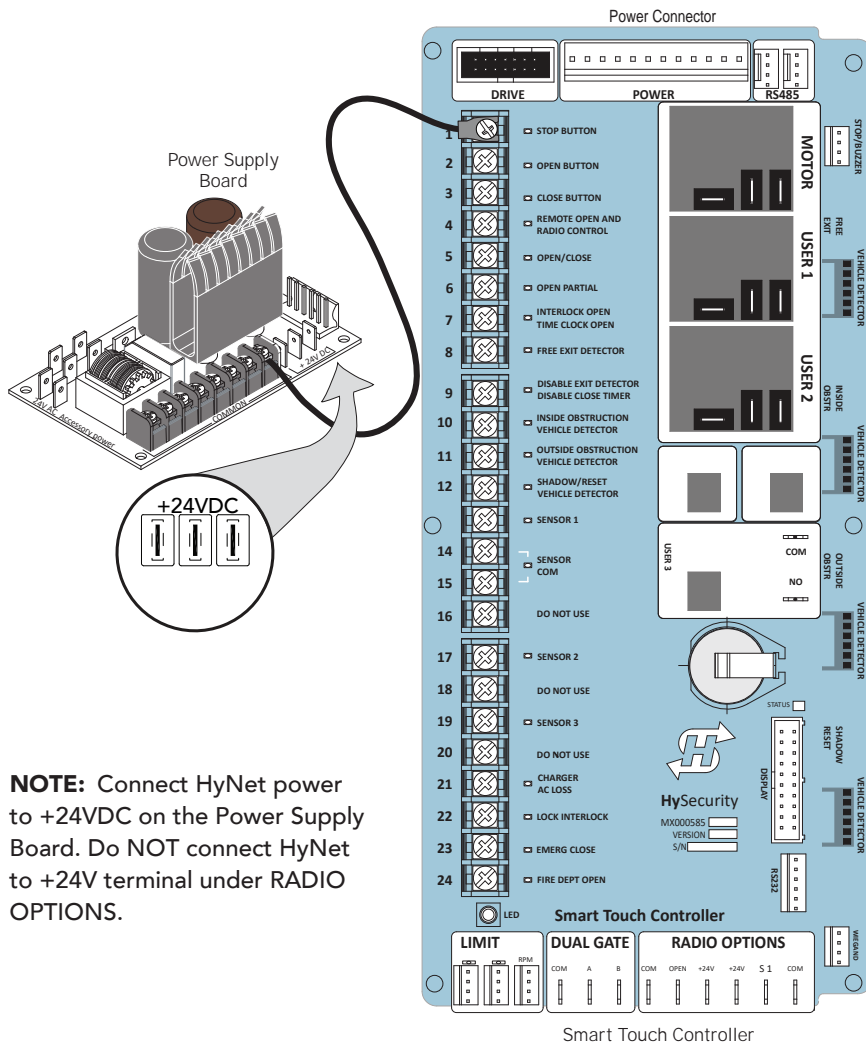
Two power supplies are available: 24VDC and 24VAC

A maximum draw of 3A is allowable when utilizing both power supply connections: 2 terminals 24VAC power or 24VDC on 3 terminals. Any combination of the 5 available terminals can be used to draw the 3A maximum.

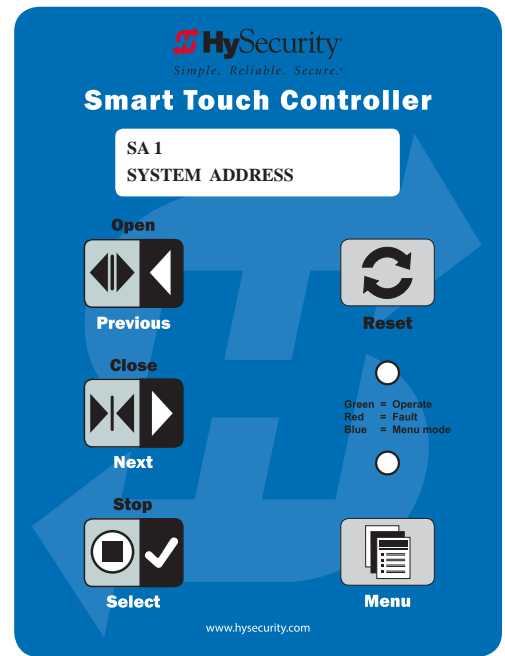
Integrating with Security Systems and HyNet™ Gateway

HySecurity hydraulic gate operators provides a 2-wire, serial interface (RS-485 connection) which allows remote access to one or more operators. With software protocols provided by HySecurity, bi-directional status updates and control commands are easily integrated with a central controller (computer or server), which becomes the primary (master) to the connected operators. Up to 4 physical operators can be polled from the central master command station. Reset requests, gate control, gate status, and gate faults can be monitored and information can be retrieved from the central command station.

The RS-485 interface is also used to communicate with the HyNet Gateway, a web-enabled interface. To view the user guide and quick start information regarding HyNet Gateway SFP 4/1, go to the HySecurity website, [Technical Support Installation Manuals](#).



NOTE: Connect HyNet power to +24VDC on the Power Supply Board. Do NOT connect HyNet to +24V terminal under RADIO OPTIONS.



SA Display in the Installer Menu

Once the physical connection is made and protocols are established, an SA (System Address) must be assigned for each operator through its Installer Menu. For network communication, choosing a "SA" of 1 to 99 establishes individual network polling addresses. A "SA" of zero means no network communication is desired.

If you plan to connect operators to a networked central master command station, contact HySecurity for software protocols and additional information. Refer to *Contact Information* on page 10.

Smart Touch Controller Inputs

When using AC power, an LED lights next to any active input.

1. Test the open and close function of the gate before connecting any accessory devices (external control inputs). This makes it easier to troubleshoot if an unexpected functionality arises.

NOTE: If you are using the operator strictly in a DC capacity, the Smart Touch Controller has a tact button you can push which lights an LED next to the active inputs. This button is in the bottom left corner of the STC board. Press the SHOW LEDs push button switch to verify the status of the terminal inputs.

2. All the Smart Touch Controller inputs listed below are shown as a single input. The second wire is connected to the Common Terminal Bus on the Power Supply Board.

NOTE: The Emergency Close and Fire Dept. Open inputs are an exception and require a +24V input. The +24V is located on Power Supply Board next to the Common Bus. See illustration on previous page.

STC Terminal Inputs



Use Terminal Inputs 4, 5, 6, and 7 for external control devices. DO NOT connect an external control device to Input Terminals, 1, 2, or 3 unless the controls are located in clear view of the entire gate area and are being constantly monitored and supervised.

NOTE: UL 325 2016 sensor input label changes shown in **Bold**.

Smart Touch Controller Inputs Chart

| No. | Smart Touch Terminal UL 325 - 2016 | Smart Touch Terminal pre-2016 | Wire Connections | Commonly used for... |
|-----|---|--------------------------------------|--|--|
| 1 | Stop Button | Stop Button | Normally Closed input. Jumper to Common if external control input is not being used. | Line of sight, external stop button or 3-button station. Activation of this input will clear Entrapment Mode (into Safe Mode) and some errors and faults. |
| 2 | Open Button | Open Button | Do not use for radio or remote access controls. Normally Open Input | Line of sight, external open button or 3-button station. Activation of this input will clear Entrapment Mode (into Safe Mode) and some errors and faults. |
| 3 | Close Button | Close Button | N.O. input. Connection for a close push-button. | Line of sight, external close button or 3-button station. |
| 4 | Remote Open & Radio Control | Remote Open & Radio Control | N.O. input. For radio/remote open device - Program to also Close in User Menu (RO 1). | Remote access control or radio controls |
| 5 | Open/Close Button | Open/Close Button | Connection for push button or radio controls. | Singular button device (multi-function). First activation opens gate, next activation stops gate, next activation closes gate, next activation opens gate. |
| 6 | Open Partial | Open Partial | N.O. input. This input will cause the gate to open to the Partial Open position programmed in the Installer Menu (7-32ft). | Supervised access controls |

| No. | Smart Touch Terminal UL 325 - 2016 | Smart Touch Terminal pre-2016 | Wire Connections | Commonly used for... |
|-----|---|---|--|---|
| 7 | Interlock Open/Time Clock Open LED | Interlock Open/Time Clock Open LED | The default is Interlock Open (TC 1) but can be configured as the Time Clock Open (TC 0) input. | When set to TC1, terminal acts as sequenced or interlocked gate input and when active with the gate closed, all open inputs will be blocked.. Set to TC0, this input provides a connection to a timer to open device This input will disable the Sally Port communication when triggered in a dual gate system configured for sally port (DG 3 and DG 4). |
| 8 | Free Exit Vehicle Detector | Free Exit Vehicle | N.O. input. Free Exit Vehicle Detector connection. | Vehicle detector, box type connections for free exit loop. Opens a stopped gate and reverses a closing gate. |
| 9 | Block Free Exit vehicle detector or Close Timer | Block Free Exit vehicle detector or Close Timer | N.O. input. Free Exit is only disabled if Close Limit Switch is tripped. If the gate is partially opened, the Free Exit detector will trigger the gate to open fully. The input can be converted in the Installer Menu to alternately disable the Close Timer. | If gate is partially opened, Free Exit detector will trigger gate to open fully. Input can be converted in Installer Menu to alternately disable Close Timer. |
| 10 | Inside Obstruction Vehicle Detector | Inside Obstruction Vehicle Detector | N.O. input. Inside obstruction loop. | Vehicle detector, box type connections that will stop a closing gate and reverse to full open by default. Also configurable to only pause the gate. |
| 11 | Outside Obstruction Vehicle Detector | Outside Obstruction Vehicle Detector | N.O. input. Outside obstruction loop. | Vehicle detector, box type connections that will stop a closing gate and reverse to full open by default. Also configurable to only pause the gate. |
| 12 | Center Loop (Shadow) Vehicle Detector | Center Loop (Shadow) Vehicle Detector | N.O. input. Shadow function used for swing gates or Reset Loop for barrier arms only. However, User Relay 20 can be used in combination with a detector to perform an "arming loop" or "annunciation loop" function because there is no associated gate control logic in a slide gate. | Vehicle detector, box type connections. Shadow function for swing gates, reset function for barrier arm. |
| 13 | SENSOR 1 | Edge Sensor | N.C. input. Connection of a Monitored External Entrapment sensor. Type of sensor used is programmable in Installer Menu (S1). Refer to How Software Handles Monitoring External Entrapment Protection Sensors on page 42. | Connection to external entrapment protection sensors. (Example: photo eyes or gate edges.) |
| 14 | Sensor COM | Photo Eye Power - 24 Volts Common | All devices used as entrapment sensors that require monitoring must be connected (wired) to SENSOR COM. | Sensor common power. |
| 15 | Sensor COM | Photo Eye Power - 24 Volts Common | Refer to <i>How Software Handles Monitoring External Entrapment Protection Sensors on page 41</i> and <i>Wiring HySecurity Sensors: Smart Touch on page 138</i> . | Connect external entrapment sensors to these terminals. The sensors power down when the gate operator reaches the open limit or after a reset command. Use these terminals to preserve battery power. NOTE: For pre-2016 gate operators, inputs are labeled as Photo Eye Power and 24 Volts Common. |

| No. | Smart Touch Terminal UL 325 - 2016 | Smart Touch Terminal pre-2016 | Wire Connections | Commonly used for... |
|-----|---------------------------------------|----------------------------------|--|---|
| 16 | DO NOT USE | DO NOT USE | | |
| 17 | SENSOR 2 | Photo Eye Open direction | N.C. input. Connection of a Monitored External Entrapment sensor. Type of sensor used is programmable in Installer Menu (S2). Refer to <i>How Software Handles Monitoring External Entrapment Protection Sensors</i> on page 41. | Connection to external entrapment sensors. (Example: photo eyes or gate edges.) |
| 18 | DO NOT USE | DO NOT USE | | |
| 19 | SENSOR 3 | Photo Eye Close direction | N.C. input. Connection of a Monitored External Entrapment sensor. Type of sensor used is programmable in Installer Menu (S3). Refer to <i>How Software Handles Monitoring External Entrapment Protection Sensors</i> on page 41. | Connection to external entrapment protection sensors. (Example: photo eyes or gate edges.) |
| 20 | DO NOT USE | DO NOT USE | | |
| 21 | Charger AC Loss | Charger AC Loss | Connection from battery cabinet. | DC battery gate operators only. |
| 22 | Lock Interlock | Lock Interlock | Refer to user relay option 23. | Locking mechanisms. |
| 23 | Emergency Close | Emergency Close | Activate with +24. Refer to OC setting in the <i>Table 6: Installer Menu</i> on page 62. | Enable in Installer menu input +24V to trigger. Requires constant hold activation. Overrides photo eyes, gate edges & vehicle detectors. Stops in entrapment mode |
| 24 | Fire Dept Open | Fire Dept Open | Activate with +24. See the <i>Table 6: Installer Menu</i> on page 62. | Enable Installer Menu FO & input +24V to trigger. Overrides photo eyes and gates edges. Stops in entrapment mode. |

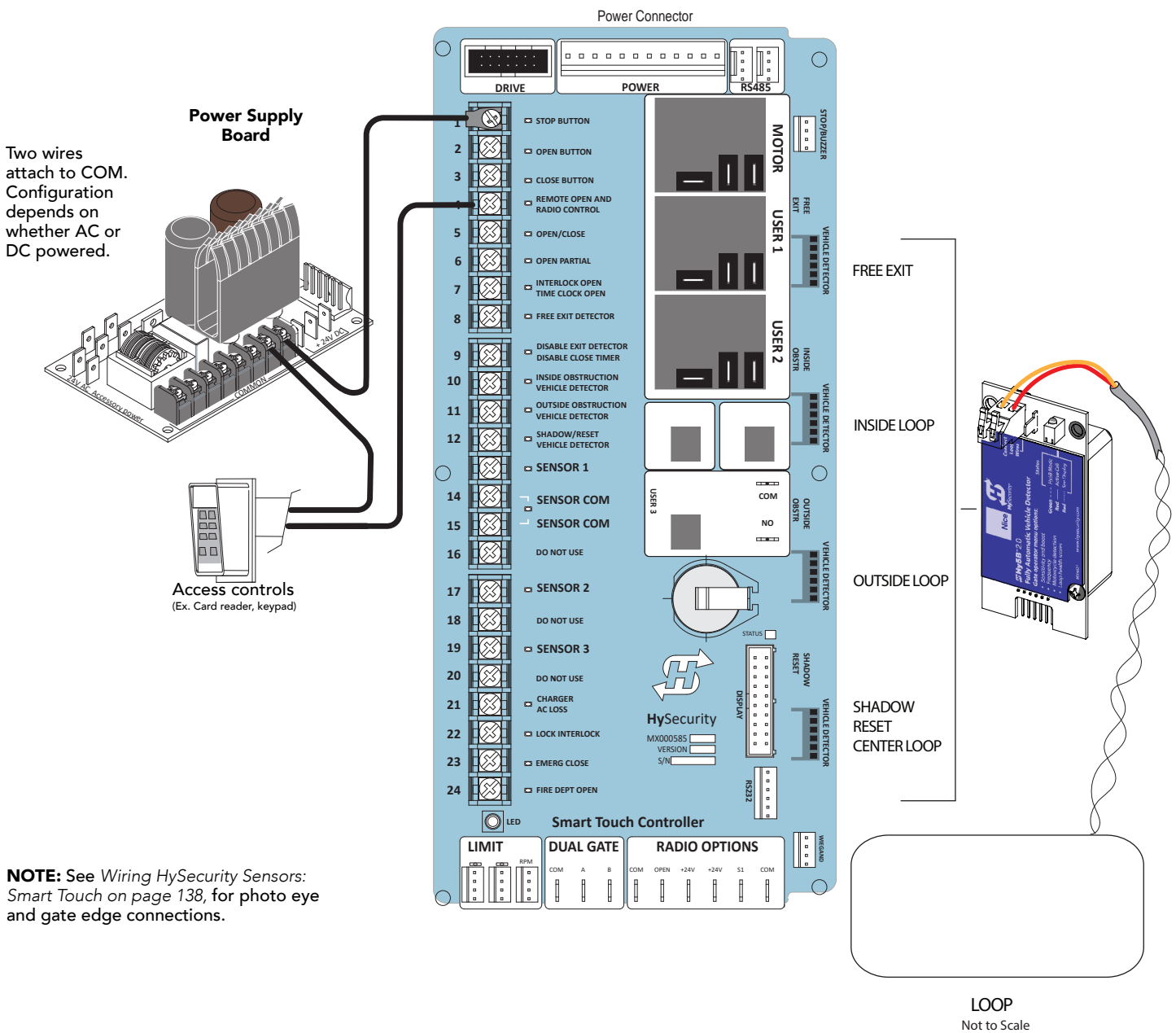
Connecting Accessory Devices

Sensors, such as gate edges and photoelectric beams, protect against potential entrapment. These external entrapment protection sensors must be monitored for the gate installation to be in compliance with the 2016 and later revisions of UL 325 Standard of Safety.

NOTE: Always check your local area codes and comply with all regulations.

Other types of accessory connections are shown in the following illustration. All accessories require a minimum of two connections:

- a device input
- a Common Bus Terminal (COM)



NOTE: See *Wiring HySecurity Sensors: Smart Touch* on page 138, for photo eye and gate edge connections.

User Relays – Programming Procedure

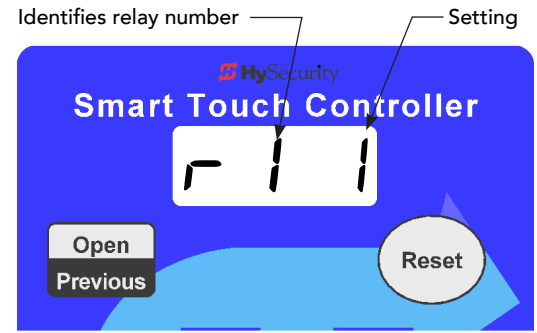
The Smart Touch Controller is able to interface with many types of external devices through the use of three user programmable output relays: two electro-mechanical relays (User Relay 1 and User Relay 2), and one solid state relay (User 3) which is used most often for connection to flashing devices.

Most of the user relay functions identified and described in the table below are accessible in the Installer Menu (R1 x, R2 x, R3 x) selections.

NOTE: A setting of zero disables a User Relay. The User Relays will operate normally to 18VDC. Below 18VDC, alert notification occurs. On Crash products User 3 relay is unavailable. It is pre-wired for the LED lights.

Use the STC buttons to program the user relays according to the following steps:

1. Select the relay you wish to use through the Installer Menu. See *Table 6: Installer Menu on page 62*. For example:
R1 13 (RELAY LOGIC 1) or R2 15 (RELAY LOGIC 2).
2. Select the appropriate function (1 through 33) by changing the display to the associated number listed in the table. Use the Select, Next and Previous buttons to make your selection. Refer to *Menu Mode Navigation on page 55*.



STC display (7-segment)

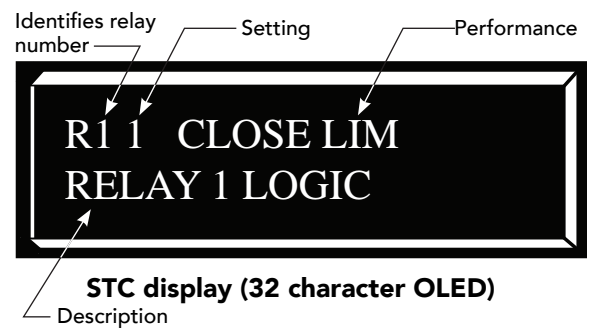


Table 7: Programmable User Relays

| Setting | Performance | Description | Wire Connection |
|---------|-----------------------------------|---|-----------------|
| 1 | Close limit output | Creates an interlock signal to another operator's interlock input, or simply to indicate that gate is secure or not. Relay is released when fully-closed limit switch is tripped. Relay is energized when fully-closed limit is released. (Any open command energizes relay.) | Relay 1, 2 or 3 |
| 2 | Close limit pulse output | Used in a sequenced system to command a second machine to close. Generates a brief pulsed output that occurs when close limit is triggered. | Relay 1, 2 or 3 |
| 3 | Open limit output | Indicates gate is at full-open position. Output becomes active when an open-limit is triggered and deactivates when open-limit is released or a close command is received. Use this output for a traffic light. | Relay 1, 2 or 3 |
| 4 | Open limit pulse output | Triggers a sequenced barrier arm gate operator to open. Generates a brief pulsed-output when open-limit is triggered. An additional pulse is also generated with any new open command even when gate is already fully-opened. | Relay 1, 2 or 3 |
| 5 | Warn before/during operate output | Controls an external warning device. This output is active whenever internal warn before operate buzzer is sounding but the relay output is constant on. Activation timing of this relay is controlled by setting User Menu for Warn Before Operate [bF]. | Relay 1, 2 or 3 |

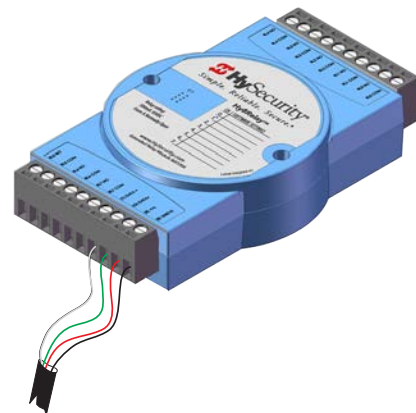
| Setting | Performance | Description | Wire Connection |
|---------|--|--|----------------------------|
| 6 | Gate Lock output | Controls external solenoid locks or magnetic locks. In both directions of travel, this output is activated about 7/10ths of a second before operator starts moving the gate. | Relay 1, 2 or 3 |
| 7 | Gate forced open output | Activated if gate is forced off closed limit switch and operator is not able to restore gate to full closed position within four seconds. The buzzer resets itself in 30 seconds but relay stays active until gate receives a run command. | Relay 1, 2 or 3 |
| 8 | Gate open too long output | Activates when gate is open longer than the user-selected period of time. Adjustable from a 0 second to 135 seconds delay in 15-second increments. NOTE: TL - OPEN TIME ALERT adjustments can be made in Installer\ Menu. | Relay 1, 2 or 3 |
| 9 | Safety Mode Alert output | Activated when system is in Safety Mode or Entrapment Mode. Safety Mode occurs upon an impact with an obstruction. Entrapment Mode means gate is stopped and occurs if inherent entrapment sensor triggers while system is in Safety Mode. Entrapment mode also occurs with activation of Fire open or Emergency Close inputs. | Relay 1, 2 or 3 |
| 10 | Entrapment Mode Alert output | Activated only when system is in Entrapment Mode. | Relay 1, 2 or 3 |
| 11 | Unauthorized Vehicle Entry output (Tail gate alert) | Activated when a second vehicle enters from outside without a valid input from an access control device. The OOLD and IOLD loops must be capable of being triggered at the same time for this relay to ever activate. This output releases when an access control input signals open or gate reaches the close limit position. | Relay 1, 2 or 3 |
| 12 | Outside Obstruction Vehicle Detector output | This output is active whenever Outside Obstruction Loop Detector is tripped. Interlocks an entry device to prevent pedestrian use. | Relay 1, 2 or 3 |
| 13 | Loitering Alert | Indicates vehicle is loitering on Outside Obstruction Loop with the gate closed. Adjustable from a 0 second to 135 second delay in 15-second intervals. NOTE: LT LOITERING ALERT adjustments can be made in the Installer Menu. | Relay 1, 2 or 3 |
| 14 | Gate nearing full travel output (Nearing Limit) | Activated when gate is approaching full open or full closed. Relay activates three feet from where software expects limit switch to be triggered whether moving toward full open, full close, or in a reverse travel mode. | Relay 1, 2 or 3 |
| 15 | Gate failure output (Fault mode alert) | Activated to report occurrence of problem. Indicates the system is in an Error, Fault, Alert, or Entrapment Mode. If active, gate is disabled. | Relay 1, 2 or 3 |
| 16 | Motor Running output | Active when motor is running and gate is in motion. | Relay 1, 2 or 3 |
| 17 | AC Power Failure output | This relay is normally energized and drops with loss of AC power. | Relay 1, 2 or 3 |
| 18 | DC Power Failure output (Low battery alert) | Activated when battery power is very low, but output ceases when battery is dead (18 volts). Relay is triggered when battery is less than 21 volts. | Relay 1, 2 or 3 |
| 19 | Flasher Relay | Controls flashing lights to pulse once per second. Relay is constantly pulsing except when open limit switch is triggered. Recommended to use User Relay 3 since it is an electronic relay | Relay 1 or 2* (Relay 3) |

| Setting | Performance | Description | Wire Connection |
|---------|--|--|-----------------|
| 20 | Free Exit Loop Vehicle Detector output | Active when the Free Exit Loop is tripped. | Relay 1, 2 or 3 |
| 21 | Inside Obstruction Vehicle Detector output | Active whenever Inside Obstruction Vehicle Detector is tripped. | Relay 1, 2 or 3 |
| 22 | Center Loop Detector output | Active whenever Center (Shadow) loop detector is tripped. | Relay 1, 2 or 3 |
| 23 | External Latching gate Lock Output (Prison Lock) | Activates when the Lock Interlock Input (Terminal No. 22) is active at the start of an Open cycle and remains on until the Lock Interlock releases or 10 seconds elapse, whichever happens sooner. Also, activates a Close cycle and releases 1 second after reaching the Close limit. | Relay 1, 2 or 3 |
| 24 | Gate at Partial Open Position | Active when partial open position is reached or exceeded. | Relay 1, 2 or 3 |
| 25 | DC Power OK Alert (Battery OK Alert) | Active when on AC power or the battery voltage is above 21V. When used with User Relay 3, this option can shed electrical loads to conserve battery energy. | Relay 3 |
| 26 | Free Exit Vehicle Detector Pulse | Activates when the Exit Loop Detector is tripped and causes a 250mS pulse output to occur. | Relay 1, 2 or 3 |
| 27 | Not Open (requires AC power) | Activated when gate is not on open limit and AC power is present. Deactivated when AC power fails or gate is on open limit. | Relay 1, 2 or 3 |
| 28 | Flasher (requires AC power) | Output identical to relay #19 and pulses relay 500 ms/sec when gate not on open limit and AC power is present. Deactivated when AC power fails or gate is on open limit. | Relay 1, 2 or 3 |
| 29 | Set aside for Factory Use | HySecurity Testing Only | Do not use |
| 30 | Arm Break | Does not appear. Displayed only used on StrongArm and StrongArmPark DC and activates if the breakaway arm switch is tripped. | |
| 31 | Warn Operate Run | Relay is active while warn before and motor running. | Relay 1, 2 or 3 |
| 32 | Partial Open Pulse | Relay pulses when partial open activated and when partial open limit reached. Often used at a sequential gate site. | Relay 1, 2 or 3 |
| 33 | Outside Obstruction/ Arming Loop Detector | Activated when OOLD/OALD detector input tripped and gate closed. Used for testing purposes. | Relay 1, 2 or 3 |

Hy8Relay Module Option

The Hy8Relay (extended relay module) provides 8 additional mechanical relays. R 4, RELAY 4 LOGIC through RB, RELAY 11 LOGIC can be accessed through the Installer Menu. Set the number for the relay based on the information found in *Table 7: Programmable User Relays* on page 77.

Wire communication cable connections between the DUAL GATE ports, at the base of the STC, and the extended mechanical relay module. Refer to instructions that accompany the Hy8Relay Module.



Bi-Parting & Dual Gate Systems

Configuring two operators to work together as an interlocked pair (Primary/Secondary or Sally Port) or sequenced gate system is easy to do with the Smart Touch Controller. There is no need to order a special model or any adapters. The area of the board marked Dual Gate employs a 3-wire, RS-485 serial port for communication between the operators.

NOTE: RS-485 communication is available for networked security systems. For additional information, refer to *Connecting Sequenced Gates* on page 83.

Connecting an Interlocked Pair (Dual Gate)

The Smart Touch Controller (STC) provides dual gate connections and programming features to connect a pair of gate operators in a Primary/Secondary or interlocked Sally Port configuration. The software establishes the communication protocols when wiring the two gate operators. A Primary/Secondary pair of operators can be set for different open/close timing sequences and Sally Port gates are often used at correctional facilities. In Sally Port configurations, one operator cannot open unless the other is fully closed. To learn how to connect the wiring between operators, review the wire diagram on the next page.

NOTE: Both SlideDriver gate systems need to have compatible software versions installed on their Smart Touch Controllers.



Bi-parting SlideDrivers

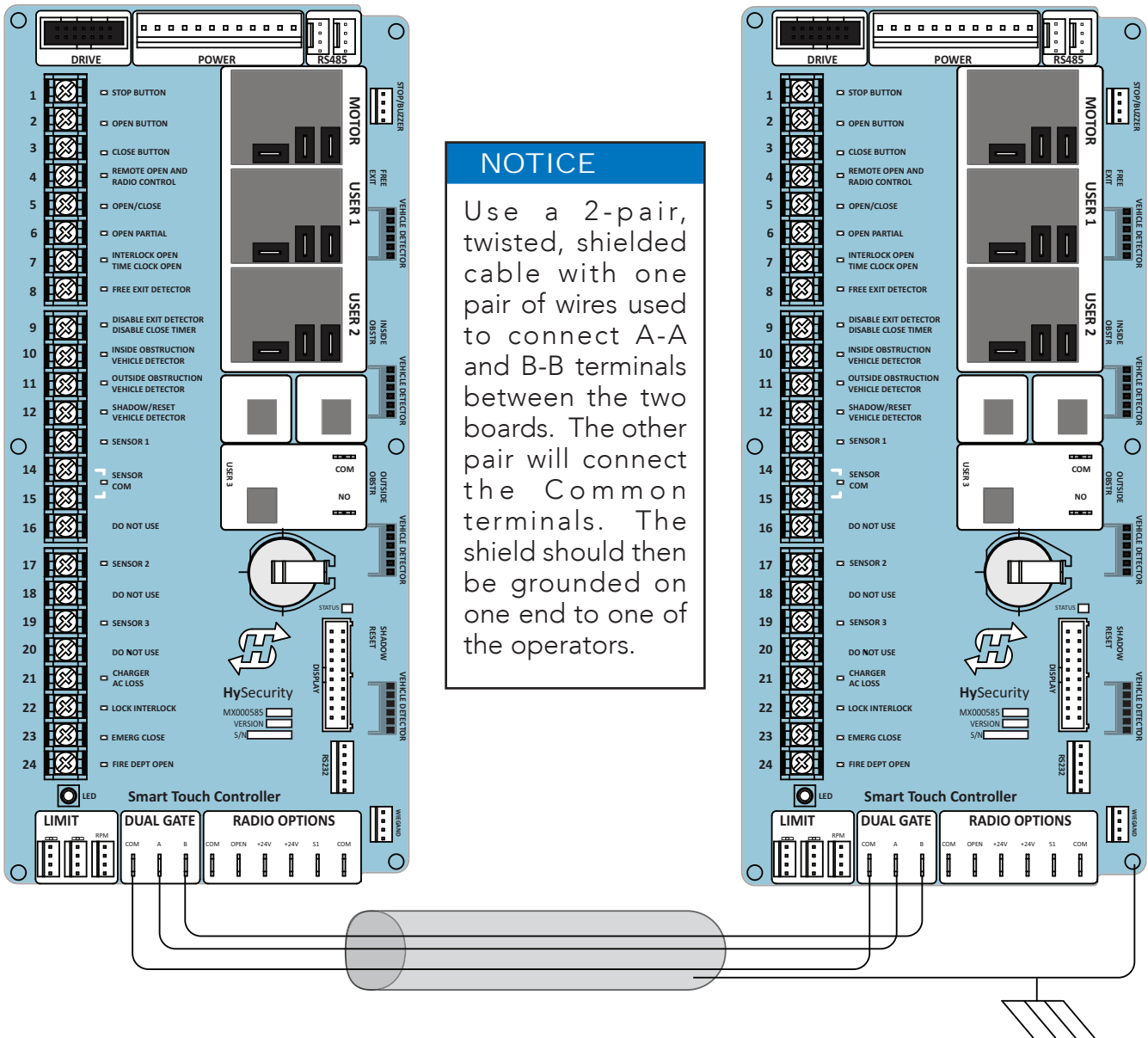
Dual Gate Wiring Connections

To connect an interlocked pair of gate operators, simply follow the steps below.

1. As shown in the Wire Diagram, connect a shielded communications cable to the DUAL GATE inputs in each operator. The inputs are located near the base of the Smart Touch Controller. Be sure to connect the wires in pairs to the same terminal ports (A-A, B-B, COM-COM) on both operators.
2. Attach a ring terminal to the shield wire and connect it to the Smart Touch Controller's convenient ground screw.



Connect the ground shield wire to only one operator, not both. Use 18-20 gauge 2 - pair, twisted, shielded wire cable. To operate properly, both Smart Touch Controllers must be using the same software version.



Wire Diagram: Interlocked Pair of Operators wired to DUAL GATE Inputs

Dual or Sequenced Gates: Power, Software & Accessory Requirements

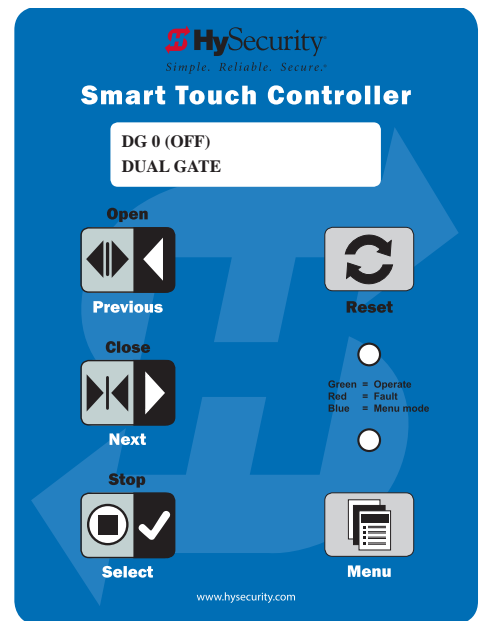
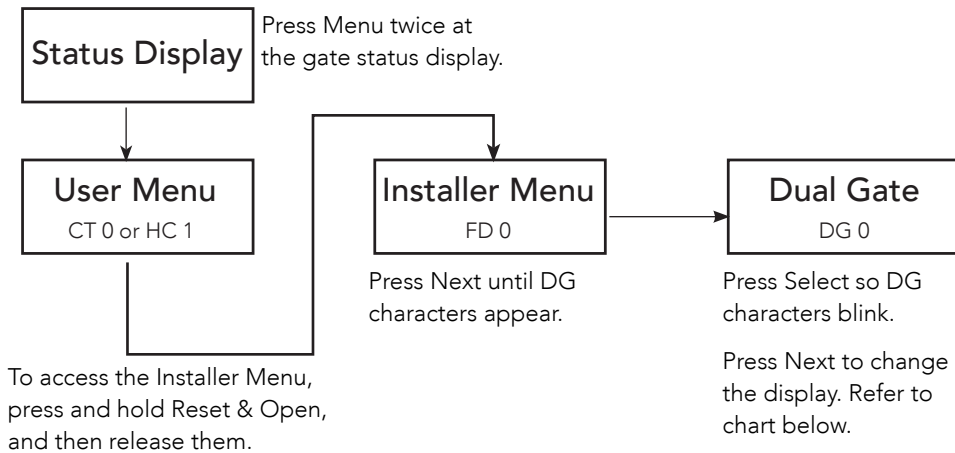
When installing an interlocked pair, the following must be adhered to:

- An electrical conduit for interconnecting wires must span between the two operators. The interlock (dual gate) communication wires and any low voltage control wires must be installed in a conduit that is separate from the high voltage power cables.
- Both operators must have their own dedicated 20A circuit breaker in the main panel. The incoming power wire size affects operator performance.
- Complete the installation of both operators as separate machines and verify that their basic functions are correct as solo operators before interconnecting them.
- Be sure both operators are running the same software version. The software version is viewable on the display by pressing the RESET button on the operator. The software version appears beneath the word HYSECURITY. Keep the most current software loaded. It is available at www.hysecurity.com. Make it part of your maintenance routine to check for software upgrades on a regular basis.
- External control inputs (vehicle detectors and external entrapment sensors) may be connected to either gate operator in a Primary/Secondary configuration, but in a Sally Port configuration, the external control inputs must be connected to each controller as only one gate is allowed to be off the open limit at a time.

NOTE: If using the Hy8Relay, connect it to the dual gate spades on the Primary controller.

Programming a Dual Gate (Interlocked Pair)

Both gate operators must be programmed so they know what function they are to perform as Primary and Secondary or Sally Port A and Sally Port B. (Sally Port A being the first gate to open for incoming traffic.) The Installer Menu provides the Dual Gate (DG) menu item that sets up the functionality of the gate operators. Access this menu item by taking the following steps:



Refer to the table below to set the operator's functionality.**

| **Interlocked Gate type | Operator 1 (Primary) | Operator 2 (Secondary) |
|----------------------------|--|--|
| Sally Port | 1. Press Next until DG 3 appears on the display. 2. Press Select to establish the operator as Sally Port A. | 1. Press Next until DG 4 appears on the display. 2. Press Select to establish the operator as Sally Port B. |
| Primary / Secondary | 1. Press Next until DG 2 appears on the display. 2. Press Select to establish the operator as Primary. | 1. Press Next until DG 1 appears on the display. 2. Press Select to establish the operator as Secondary. |

Connecting Sequenced Gates

Sequenced gates are slightly different than dual or interlocked gates. When two gate operators are connected as sequenced gates, a faster “Traffic Control Gate” operator (i.e. barrier arm or crash wedge) and a slower “Security Gate” operator (slide, swing, or vertical lift gate) operate in sequence to help prevent tailgating or unauthorized entry. Both operators open (Security Gate first followed by the Traffic Control Gate) and allow a vehicle through, but the faster moving Traffic Control Gate closes quickly once its reset/center loop and all obstruction loops are cleared. Upon reaching its closed limit, the Traffic Control Gate signals the Security Gate to close. Note that all shared vehicle detector loops must be cleared before the Security Gate closes.

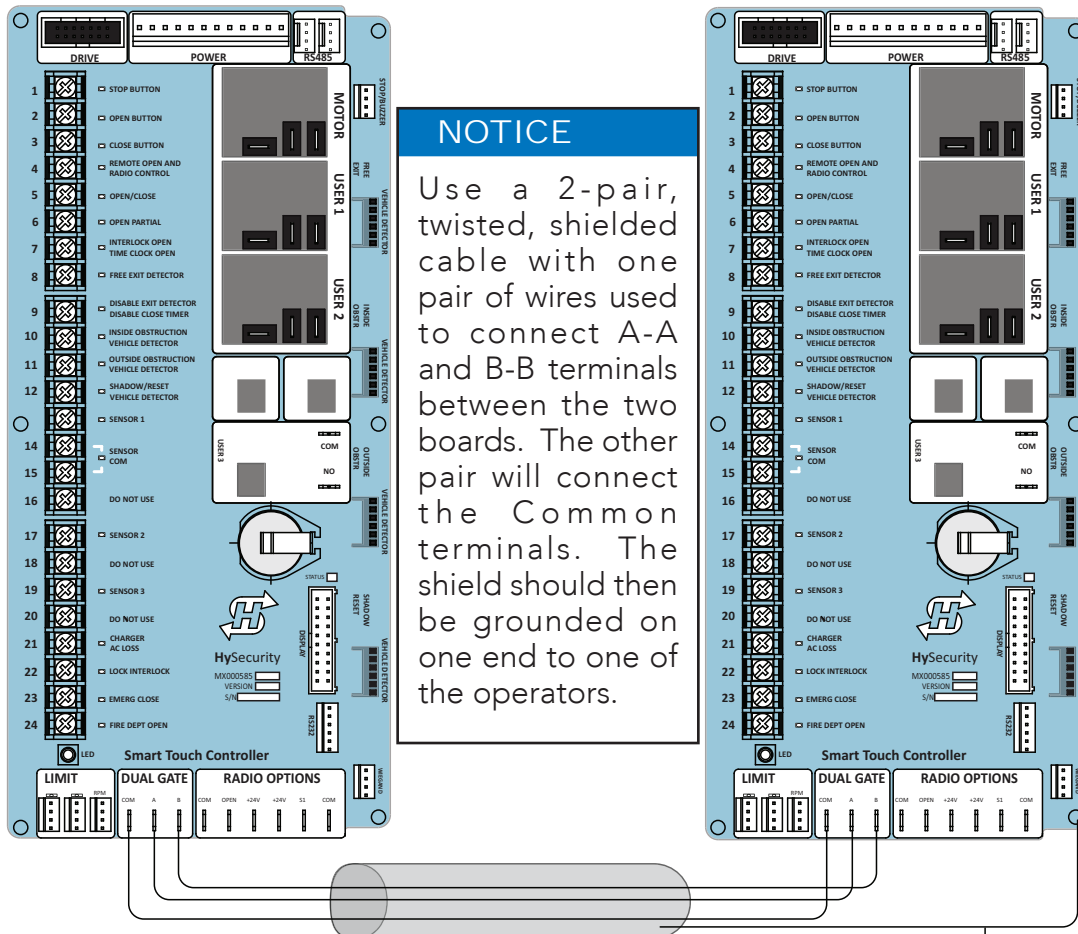
NOTE: An emergency open or close overrides the gate sequencing and acts upon both gates simultaneously.

The Smart Touch Controller (STC) provides the sequenced gate connections and programming features, and the STC software establishes the communication protocols when wiring the sequenced gate operators. To learn how to connect the wiring between operators, review the Wire Diagram below.



The operators do not have to be of the same type, but both need to have up-to-date software versions installed on the Smart Touch Controller. For example, a StrongArmCrash M30 can be sequenced with a security gate to provide both personnel security and crash provisions. The inherent STC software integrates seamlessly between operators and software protocols and allows RS-485 communication for networked security systems. Refer to *Integrating with Security Systems and HyNet™ Gateway on page 72* for additional information.

To connect a sequenced pair of gate operators, follow the steps on the next page.

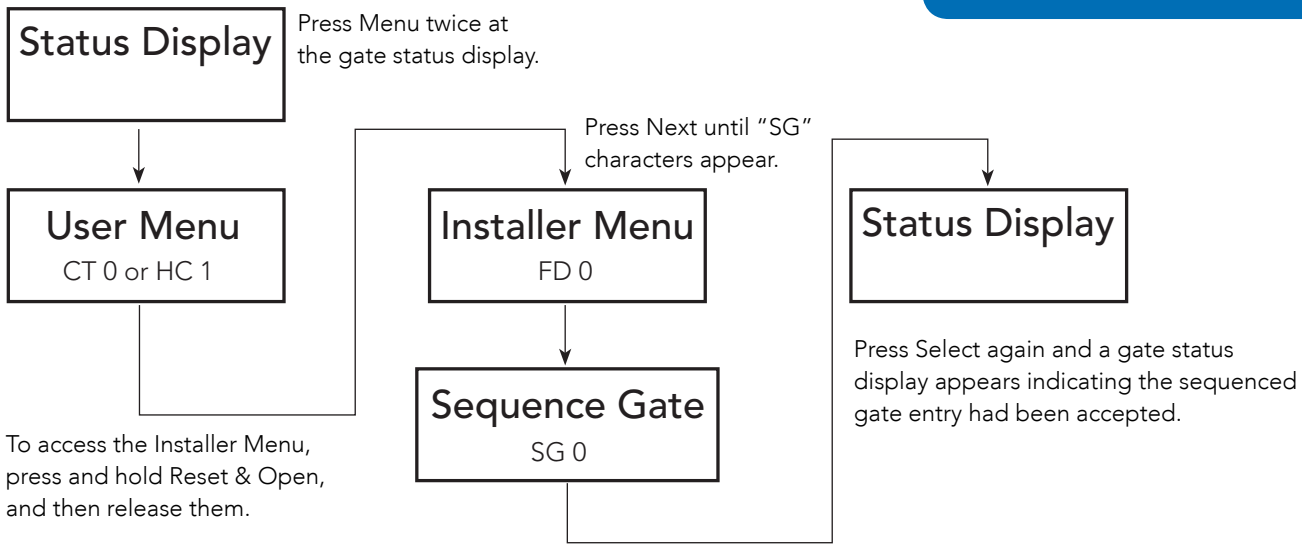
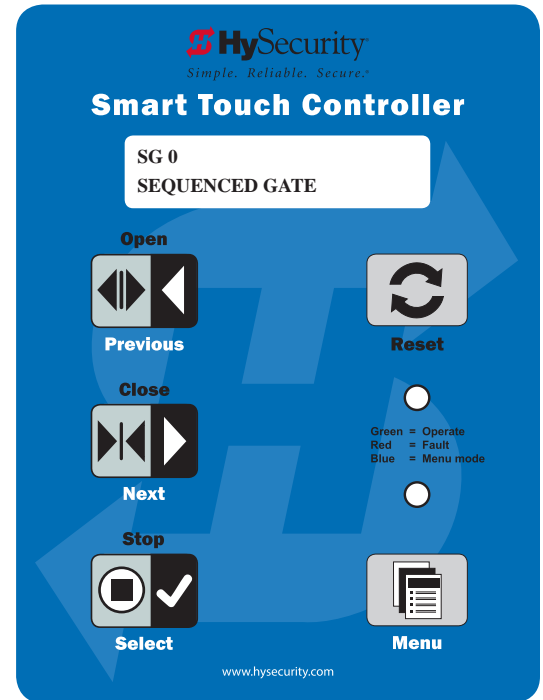


Wire Diagram: Sequenced Pair of Operators wired to DUAL GATE Inputs

1. As shown in the wire diagram on page 83, connect a shielded communications cable to the DUAL GATE inputs in each operator. The inputs are located near the base of the Smart Touch Controller. Be sure to connect the wires in pairs to the same terminal ports (A-A, B-B, COM-COM) on both operators.
2. Attach a ring terminal to the shield wire and connect it to the Smart Touch Controller's convenient ground screw.

NOTE: Connect the ground shield wire to only one operator, not both. Use 18-20 gauge 2-pair, twisted, shielded cable .

Sequenced gates are very similar to dual gates (interlocked pair) in their Power, Software, and Accessory Requirements. To review the installation site requirements, refer to *Dual or Sequenced Gates: Power, Software & Accessory Requirements on page 82.*



To access the Installer Menu, press and hold Reset & Open, and then release them.

Press Select so "SG" characters blink.

Press Next to change the display:

SG 1 = Sequenced Gate #1 configuration

SG 2 = Sequenced Gate #2 configuration

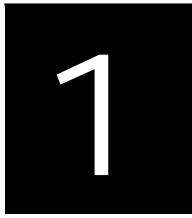
SG 3 = Sequenced Gate #3 configuration (only used with HydraSupply XL)

SG 4 = Sequenced Gate #4 configuration (only used with HydraSupply XL)

NOTE: Set gate operators on the site to the uniquely paired number. Refer to the site designs on the following pages.

Sequenced Gate: Configuration #1

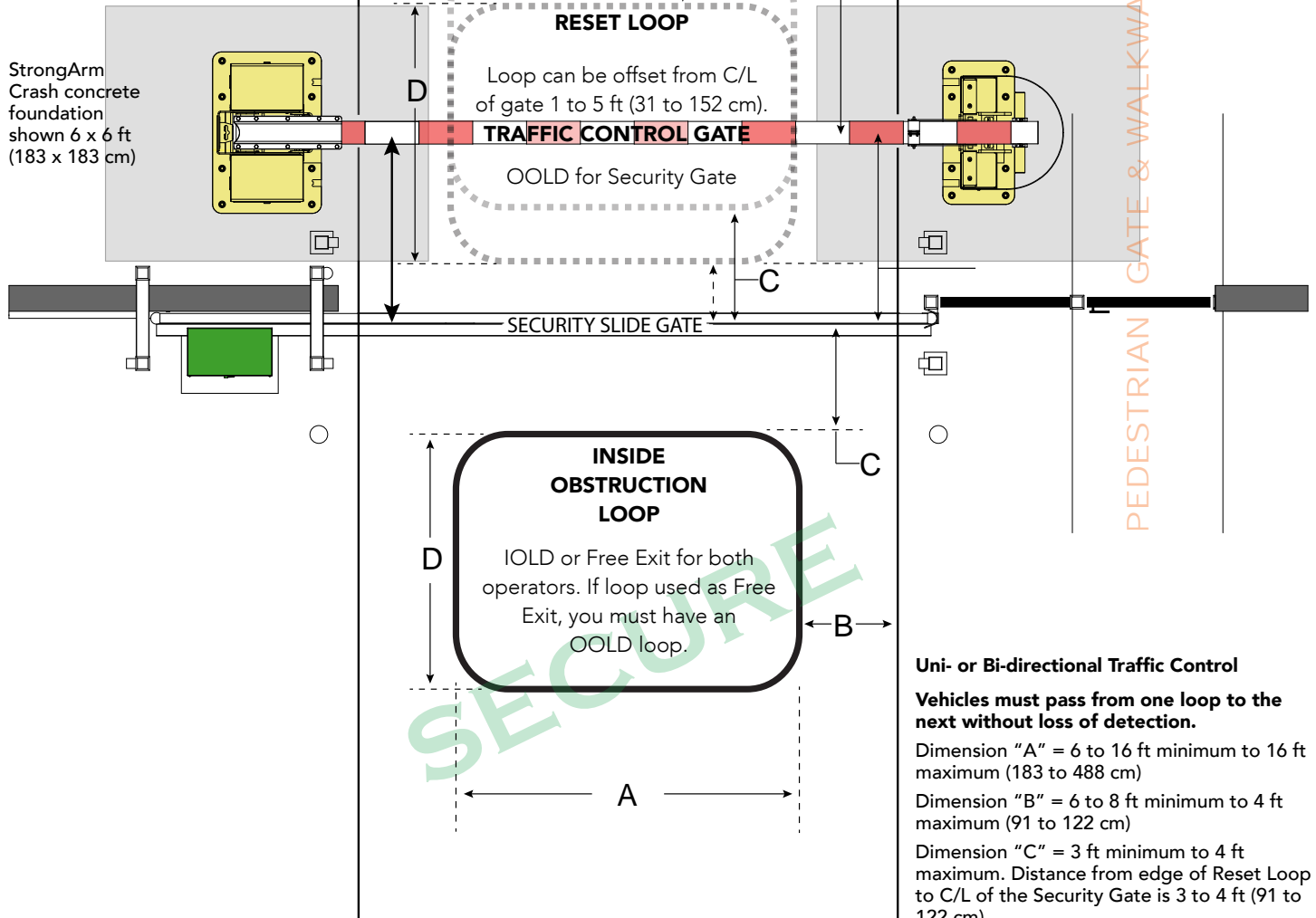
Vehicle Loop Layout



To sequence the gates, set the Installer Menu item SG to "1" in both gate operators.*

Operator & Loops**

As traffic control and security gates are separated farther apart, Reset Loop moves toward center.



Uni- or Bi-directional Traffic Control

Vehicles must pass from one loop to the next without loss of detection.

Dimension "A" = 6 to 16 ft minimum to 16 ft maximum (183 to 488 cm)

Dimension "B" = 6 to 8 ft minimum to 4 ft maximum (91 to 122 cm)

Dimension "C" = 3 ft minimum to 4 ft maximum. Distance from edge of Reset Loop to C/L of the Security Gate is 3 to 4 ft (91 to 122 cm).

Dimension "D" = 6 ft (183 cm)

Dimension "E" = 4 ft minimum to 8 ft maximum. Reset Loop can be offset from C/L gate 1 to 5 ft (31 to 152 cm).

Dimension "F" = 10 to 15 ft (3 to 3.6 m)

*NOTICE

For sequenced gates to operate properly, all vehicle detectors must be wired to the Traffic Control Gate.

If a communication failure occurs, an ALERT 22 (RL 22) appears and the buzzer sounds.

The Traffic Control Gate maintains functionality while the Security Gate defaults to open until communication is restored (or the Security Gate is manually closed).

Drawings not to scale.

Sequenced Gate: Configuration #2

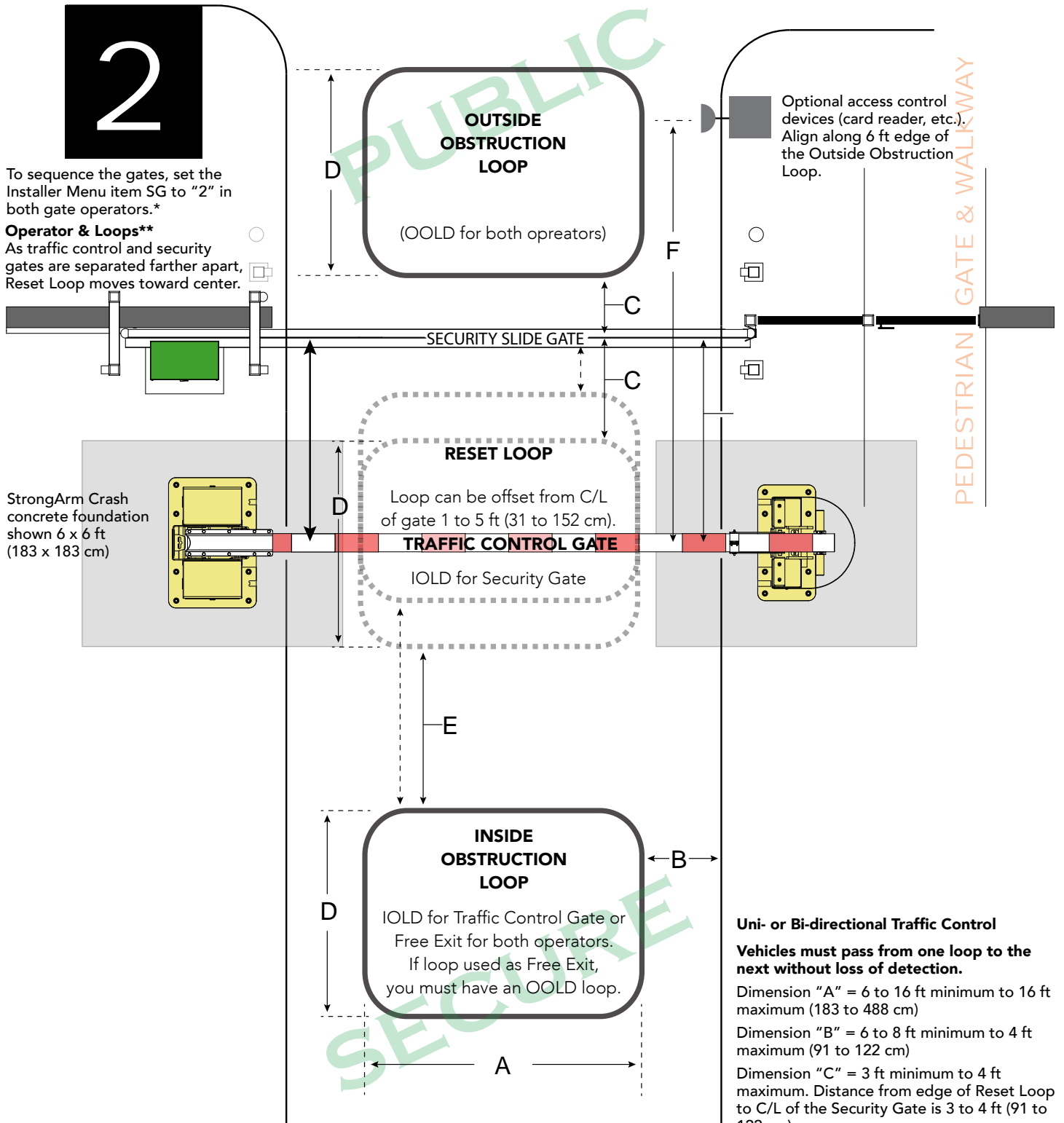
Vehicle Loop Layout

2

To sequence the gates, set the Installer Menu item SG to "2" in both gate operators.*

Operator & Loops**

As traffic control and security gates are separated farther apart, Reset Loop moves toward center.



StrongArm Crash concrete foundation shown 6 x 6 ft (183 x 183 cm)

Optional access control devices (card reader, etc.). Align along 6 ft edge of the Outside Obstruction Loop.

Uni- or Bi-directional Traffic Control

Vehicles must pass from one loop to the next without loss of detection.

Dimension "A" = 6 to 16 ft minimum to 16 ft maximum (183 to 488 cm)

Dimension "B" = 6 to 8 ft minimum to 4 ft maximum (91 to 122 cm)

Dimension "C" = 3 ft minimum to 4 ft maximum. Distance from edge of Reset Loop to C/L of the Security Gate is 3 to 4 ft (91 to 122 cm).

Dimension "D" = 6 ft (183 cm)

Dimension "E" = 4 ft minimum to 8 ft maximum. Reset Loop can be offset from C/L gate 1 to 5 ft (31 to 152 cm).

Dimension "F" = 10 to 15 ft (3 to 3.6 m)

*NOTICE

For sequenced gates to operate properly, all vehicle detectors must be wired to the Traffic Control Gate.

If a communication failure occurs, an ALERT 22 (RL 22) appears and the buzzer sounds.

The Traffic Control Gate maintains functionality while the Security Gate defaults to open until communication is restored (or the Security Gate is manually closed).

Drawings not to scale.

Vehicle Detector Installation and Loop Layouts

HySecurity recommends that vehicle detectors be used for free exit and obstruction sensing logic only. The exception is in parking or barrier arm applications where detectors may also be used to close the gate. In applications employing our swing, vertical lift, or sliding gate operators, closing logic cannot be used except when the anti-tailgate logic is employed.

Vehicle detector functions (OR, IR, HD, DL) are configurable through the *Table 6: Installer Menu on page 62*.

NOTE: For in-depth information regarding Hy5B vehicle detectors, click [Tech Support on the HySecurity website](#) and follow the link to [Installation Manuals](#).

Anti-TailGate Mode (Closing Logic)

The Detector Logic (DL) installer menu item lets you set the anti-tailgate mode. This menu item works in conjunction with the Close Timer (CT) when the vehicle detector is triggered. If you plan to use the anti-tailgate feature, check the time delay aspect of the Close Timer (CL) setting.

The four selectable modes for DL are as follows:

Mode 1 (Default): An input from either the Free Exit, Outside Obstruction Loop (OOLD), Inside Obstruction Loop (IOLD), or the Center Loop (CLD/RESET/Shadow) will hold the gate open, reset the close timer, and ignore all close inputs. The close timer begins to count down only after all vehicle detectors are clear and no other open command is present.

Mode 2: The close timer does not wait for vehicle detectors to clear, but instead it starts counting down as soon as the open limit is reached.

Mode 3: When both inside and outside obstruction loops are simultaneously active, the gate will close immediately (unless another open command is present) once all vehicle detectors are no longer sensing active loops (i.e. vehicle loops are clear).

Mode 4: Full anti-tailgate logic includes Mode 3 functions. In addition, the gate will stop during the opening cycle when both OOLD & IOLD (reversing loops) are tripped simultaneously. When the OOLD & IOLD loops are cleared, the gate closes immediately. The OOLD & IOLD can be individually set so that, if tripped while closing, the gate may either, pause only or reverse to reopen. The free exit detector input is ignored while the gate is closing.

NOTICE: Using any vehicle detector logic mode other than Mode 1 (default) requires that all the loops be placed with the geometry and spacing as shown in the loop layout drawings. The detector Modes 3 and 4 require use of separate inner and outer obstruction detectors. Mode 4 is not available in HydraWedge SM50 or gate operators functioning with HydraSupply XL.

TailGate Alert

User Relay 11 is available for notification devices. If a vehicle is tailgating, and a flasher or audio device is connected to User Relay 11, the relay will be triggered by the tailgating vehicle crossing the loops. See *User Relays – Programming Procedure on page 77*.

Vehicle Detectors and the Smart Touch Controller

The Smart Touch Controller provides an interface for up to four different vehicle detector functions.

NOTE: Standard box type 11 pin (24 VDC or 24 VAC) vehicle detectors may be connected in the traditional manner to the controller, but HySecurity Hy5B mini-detector modules plug directly into the board, making field installation much faster and enhancing performance.

The Hy5B detector communicates with the Smart Touch Controller microprocessor to achieve the following benefits:

- **Automatic Sensitivity** – The Hy5B monitors vehicle traffic over the loop and automatically adjusts the loop sensitivity based on vehicle type and volume.
- **Automatic Gate Compensation** – The Hy5B discerns gate travel over the loop and automatically compensates for its effect. The compensation allows the Hy5B to operate with a higher sensitivity which provides better detection capability.
- **No Loop Crosstalk** – Exclusive use of Hy5B vehicle detectors in HySecurity gate operators, completely eliminates crosstalk and the need to set frequency levels.
- **Vehicle Counting** – Hy5B detects passenger vehicles and motorcycles.
- **Automatic Lightning Suppression** - Where lightning strikes occur often, connecting to the ground terminal minimizes the chance of activation or lock-up.
- **Health Scores for Loop** – Hy5B monitors the loop for changes that are indicative of possible problems. A score is accessible through the event log, LG menu item.
- **Automatic Hy5A emulation mode** for backward compatibility.

Hy5B Installation

To install an Hy5B vehicle detector, you will need to take the following steps:

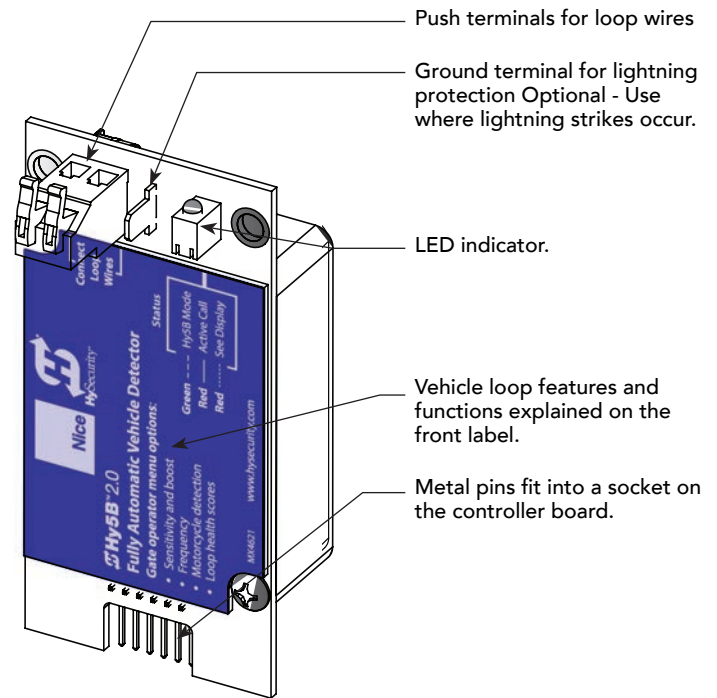
- Test the vehicle loop
- To use all the features of Hy5B, update the software version on the gate operator to the latest version using S.T.A.R.T. and a PC laptop. Access free software updates from the HySecurity website: www.hysecurity.com
- Install the Hy5B vehicle detector
- Fully cycle the gate at least 2 times to allow the detector to adjust to the effects of the gate during travel. Drive a test vehicle over the loops.

Test the Vehicle Loop

Run diagnostic tests on the vehicle loops before installing Hy5B vehicle detectors to ensure the loops are in good working condition. The following tests cannot guarantee a functioning loop, but failure of either test means that the loop may be damaged or need to be replaced.

1. Test – Measure the resistance of the loop and lead-in wire. It should not exceed 4.0 ohms.
2. Test – Measure the resistance to earth ground with a Megohmmeter (Megger). It should be 100 Megohms or more. Below 50 mega-ohms, install a new loop.

NOTE: Loops may function at 100 Megohms or less, but will not be reliable (for example, when the ground is wet from rainfall). A low megohm reading on the resistance to earth ground usually occurs due to broken or moisture saturated insulation. Be sure to use wire with a direct burial jacket such as XLPE or XHHW wire. Do NOT use THHN wire.



Hy5B Vehicle Detector – front view

Check the Version of Software

1. In the field, open the gate operator's Control Box.
2. To view the software version, press the RESET key. use Hy5B features, the software version must be h4.55 or h5.56 later). Otherwise, the Hy5B reverts to Hy5A emulation mode.
3. If you wish to update the software, download the current S.T.A.R.T. software to your PC laptop, and then load the gate operator code to the controller board before installing Hy5B vehicle detectors. See www.hysecurity.com for updates.



To
(or

NOTE: Hy5A emulation mode does not include all the features of Hy5B. If you are replacing Hy5A detectors and updating the gate operator software, be aware Build Year 1 (BY1) or Build Year 2 (BY2) will need to be addressed. BY2 requires monitoring of external entrapment protection sensors per UL 325 - 2016 Standard of Safety. If the gate operator was installed prior to 2016, BY1 may be used. For more information, refer to the gate operator's product manual.

Install Hy5B Vehicle Detectors

Install one Hy5B detector at a time. Each vehicle detector socket is labeled.

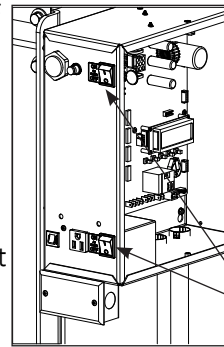
1. Turn power OFF in control box.
2. Insert the squared-off end of the plastic standoff through the hole in the Hy5B detector.

NOTE: The plastic standoff "squared-off end" does not fit into the mounting holes of the control box. Double check the orientation of squared-off ends.

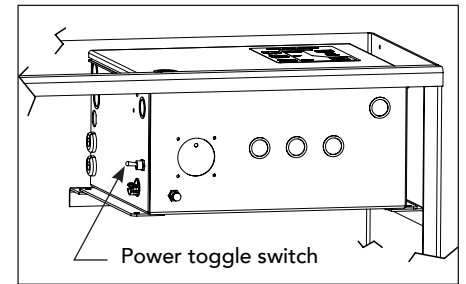
3. To minimize excessive flexing, keep each Hy5B perpendicular to the control board as you plug it into the Hy5B socket.
4. Secure the Hy5B by inserting each plastic standoff into the chassis.
5. Place the two wires from the loop into the push terminals of the Hy5B. For ease of installation, the wire gauge should be 20 - 14 AWG. Refer to *Vehicle Loop Sets* on page 90.

NOTE: If you have more Hy5B detectors, repeat the steps 2 through 4 for each additional Hy5B detector.

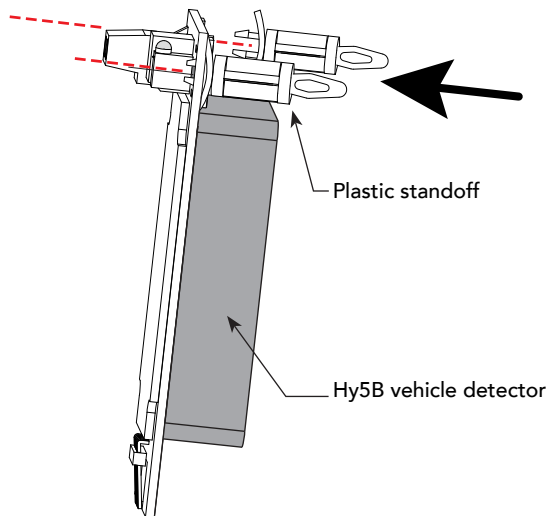
SmartDC Control Box



Smart Touch Control Box



Power switches
Turn off both the DC and AC switches.



| LED Display Status | | |
|--------------------|---|---|
| LED Activity | Indicates | Condition & Resolution |
| OFF | Hy5A mode | Emulation mode. Some Hy5B features are unavailable. |
| GREEN PULSING | Heart beat | Normal operation. |
| RED ON | Call Mode | Status indicates loop activation in process. |
| RED FLASHING | View display for more information: <i>Initializing</i> or <i>Faulty loop</i> | If initializing, wait until initialization is complete. If flashing during loop operation, take following steps: 1. Check loop wiring. See <i>Test the Vehicle Loop</i> on page 88. 2. Replace loop. 3. If loop is not at issue, swap out Hy5B vehicle detector with a known operational Hy5B. 4. If necessary, replace Hy5B. |

| Vehicle Loop Sets | | | | |
|------------------------|----------------|---------------------|-------------------|---|
| Loop Type | Installer Menu | Loops Smart DC | Loops Smart Touch | Description |
| Exit Loop | ELD | EXIT LOOP | FREE EXIT | Opens a fully-closed gate. |
| Inside Reversing Loop | ILD | INSIDE OBSTRUCTION | INSIDE OBSTR | Connects to the inside reversing loop. |
| Outside Reversing Loop | OLD | OUTSIDE OBSTRUCTION | OUTSIDE OBSTR | Connects to the outside reversing loop. |
| Reset/Shadow/Center | SLD/CLD | CENTER LOOP | SHADOW / RESET | Prevents a gate from starting open or closed when a vehicle is in the path of the gate. |

- Turn power to the gate operator back ON.
- The Hy5B indicator light flashes red and the following appears.

| Smart Touch 7-segment Display | STC (OLED) and Smart DC Displays |
|-------------------------------|----------------------------------|
| in It | INITIALIZING |

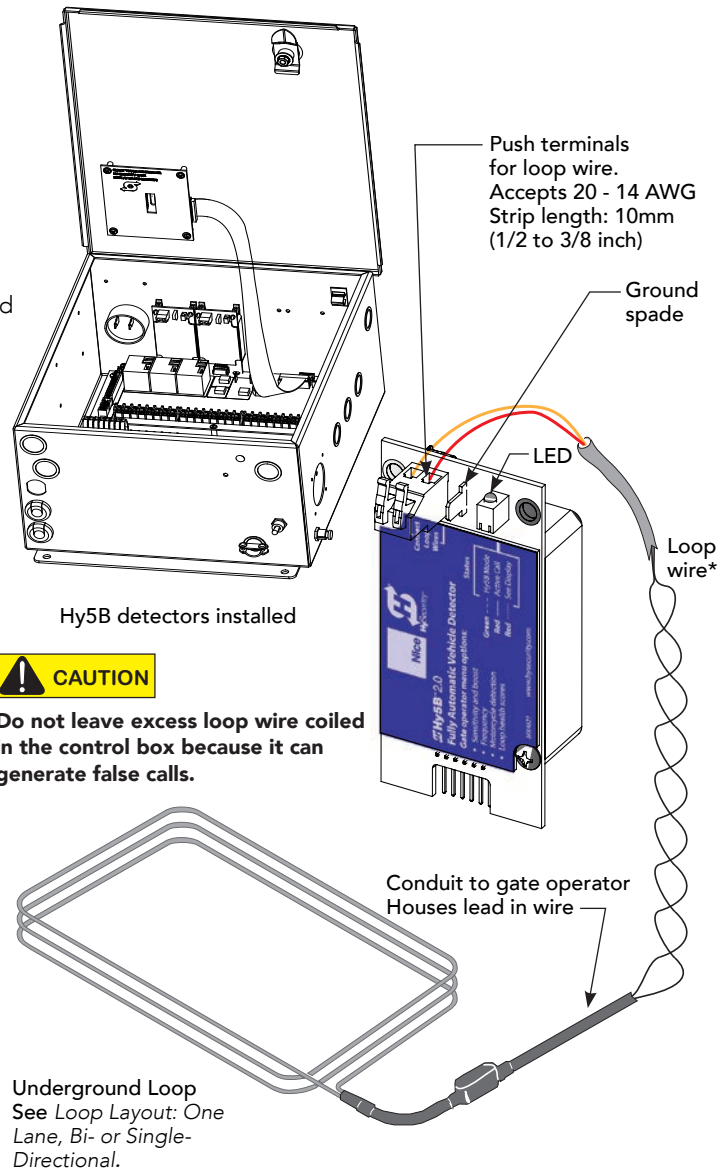
- When the LED on the Hy5B detector stops flashing red, it begins pulsing green which indicates **initialization is complete** and the detector is **ready for use**.

NOTE: If using Hy5A emulation mode, the LED does not flash green, it goes dark. Refer to *LED Display Status on page 89*.

- Press the Reset button. *
When you press Reset, the following occurs:
 - Checks Hy5B loop connections and re-tunes Hy5B to prevent crosstalk
 - Un-installs memory of vehicle detectors physically removed
 - Clears alerts

NOTE: If the Hy5B is unplugged after it is initialized, an alert appears on the display, ALERT 10. If the issue is not resolved, ERROR 3 appears. When faults of this nature occur, the gate operator functions as if the Hy5B is triggered.

* **Best Practice:** When "re-tuning" Hy5B vehicle detectors, verify that the loops are clear before pressing the Reset button.



CAUTION

Do not connect Free Exit loop wires to the same Hy5B detector containing obstruction loop wires (reversing loops). You cannot combine Free Exit vehicle detection with reversing loop detection. If you attempt to do so, vehicles crossing over the Free Exit will not be detected.

CAUTION

Do not leave excess loop wire coiled in the control box because it can generate false calls.

For more information, refer to the Hy5B User Guide and additional instructional material found online [HySecurity website / Tech Support](http://HySecurity.com).

Loops and Hy5B

Vehicle Detector and Loop Fault Diagnostics

If HySecurity Hy5B vehicle detector modules are used, the Smart DC Controller has the ability to store and report detector and loop fault information for performance diagnostics.

If the Smart DC Controller senses a loop or detector problem:

- The LCD display flashes the name of the affected detector or error and the appropriate alert code.
- The buzzer chirps continuously at regular intervals until the issue is resolved.

| Hy5B Vehicle Detector Faults and Errors | | | |
|---|------------------|--|--|
| Alert or Error # | LCD Description | Advisory | Resolution |
| ALERT 7 | FREQ SHIFT FAULT | Hy5B vehicle detector - Abnormal frequency change alert. | Alert indicates an unstable loop frequency. Check loop and lead in wires for problems. Replace them, if necessary. |
| ALERT 8 | LOOP SHORTENED | Hy5B vehicle detector - Loop is shorted. | Alert indicates that loop and lead in wires are shorting out. Check wires for problems. Replace them, if necessary. |
| ALERT 9 | LOOP OPEN | Hy5B vehicle detector - Disconnected loop alert. | Alert indicates loop wires are loose or disconnected. Check wires for problems. Replace them, if necessary. |
| ALERT 10 | I2C BUS ERROR | Hy5B vehicle detector - Communications alert. | Alert indicates detector is not communicating properly with Smart DC Controller. Alert occurs if detector is unplugged or connection is unstable. If communication is not reestablished within 30 seconds, controller will reset and message changes to ERROR 3. |
| ALERT 11 | DETECTOR FAULT | Hy5B vehicle detector - Malfunction alert. | Display indicates Hy5B detector malfunction. Check detector for problems. Replace it, if necessary. |
| ALERT 12 | ON TOO LONG | Detector input triggered too long - More than five minutes. | Display indicates Hy5B detector malfunction. It alert also works for any input connected to terminal strip for standard box detectors. Check that a vehicle is not parked on loop. Also, determine if loop is stable. An unstable loop can hold detector in a triggered state. |
| ERROR 3 | DETECTOR FAILED | Hy5B vehicle detector - Communication failed. Smart DC Controller will behave as if detector is triggered, usually holding gate fully open | Alert indicates detector is not communicating properly with Smart DC Controller. Alert occurs if detector is unplugged or detector has failed. To replace detector, press RESET button to clear error and re-seat detector or install a new one. |

Even if the loop problem self heals, historical data about detector/loop performance and a log of Alerts, Faults and Errors can be retrieved from the Smart DC Controller by downloading from the RS232 communications port or the USB port. HySecurity's free START software, a laptop computer, and a special download cable or USB cable are required to retrieve and read this data.

Loop Health:

The Hy5B monitors loop health which is comprised of loop noise, loop step changes and loop reference changes. Loop health readings accumulate throughout a 24 hour period and the accrued readings are posted to the Event Log each day at midnight. After midnight, the loop health baseline resets to its highest value of 777.

Example of an Event Log posting:

```
Event log:
02/09 EVENT - CLD Loop Health: noise 5, step 6, ref 7
```

Loop Presence:

Loop presence is dependent on “disturbance effect” of the entire vehicle. Presence determines how long to hold the “memory” of a stationary vehicle on a loop before it is forgotten and ignored. Set the presence of the loop:

- LONG (default) lasts about 20 hours dependent on call strength and sensitivity setting. The Hy5B tunes out the “disturbance effect” when a vehicle is stationary on a portion of the loop, but keeps the undisturbed (unaffected) portion of the loop operational.
- INFINITE never drops the call. The INFINITE setting requires a certain amount of signal strength. A “threshold” is maintained and it will hold the call forever. The loop connected to an Hy5B with this setting may become nonfunctioning.

| Setting Loop Presence | | |
|-----------------------|------------|--|
| Sub-menu Item | Display | Example Site Scenario |
| PR 0 | (LONG) | With sensitivity set to A (AUTO) and a large sedan stationary on loop, LONG presence may hold call for many hours before vehicle's presence is tuned out. Then, stationary vehicle is ignored and unaffected portion of loop becomes operational. In contrast, with sensitivity set to M (MOTORCYCLE), default threshold only lasts about 1 hour before presence of motorcycle on loop is tuned out. |
| PR 1 | (INFINITE) | A site where standing or parked vehicular traffic (on large area loops) is a daily or consistent basis, INFINITE presence setting is a viable option. When loop may have vehicles parked on it for more than several hours and it must hold the call, set presence to INFINITE. |

NOTICE: Hy5B has ability to continue counting vehicles passing over loop even though a stationary vehicle may be on a portion of loop. Controller and Hy5B detector also exchange pertinent information, so if a power failure were to occur, controller can determine if a vehicle is on loop when power returns.

Frequency:

Knowing the exact frequency of a loop can be useful as a diagnostic tool, and verifying the stability of the loop frequency is valuable information. To view the actual loop frequency of a specific vehicle detector, go to the setting for that detector in the Installer Menu, switch the selection from 0 to 1, and press the Select button. The display will show the loop frequency. The frequency is usually between 20,000 to 80,000 Hertz.

Changing the Loop Frequency:

Hy5B detectors can never crosstalk. If for any reason, you want to manually change the loop frequency, change the Installer Menu option for the desired loop from 0 to 3, and then press the Select button. Each detector

has a choice of four frequencies. Press the Select button when the desired frequency setting is found, and the controller will perform a reset and tune to the new frequency setting.

Call Strength Level:

Knowing the call strength of a detector is valuable because it provides information about how well the loop is actually “seeing” a specific vehicle. For example, it may be useful to check to see if the loop is easily detecting the middle of a high bed semi-truck. The strength of a detector call can be displayed in real time, on a scale of 0 to 7. As indicated in the table below, when the Installer Menu setting for a given detector is set to 2, and the Menu button is pressed, the LCD display will read Level 0 - 7 Call Level. If the call strength on the display appears as a level 4 or less, consider increasing the sensitivity level by adjusting the rotary switch on the Hy5B detector.

| Hy5B Vehicle Detector Call Level Display | | | |
|---|--|--|----------------------|
| Installer Menu | LCD Description | Setting Options (Bold = Factory Settings) | |
| ELD 0 | EXIT LOOP SET | 0 = Run mode | 5 = Set Sensitivity |
| ILD 0 | IN OBS LOOP SET | 1 = Show frequency | 6 = Show Inductance |
| OLD 0 | OUT OBS LOOP SET | 2 = Show call level 0-7 | 7 = Show Loop Health |
| CLD 0 | CENTER LOOP SET (Can be used as an arming loop with User Relay 22.) | 3 = Set Frequency | 8 = Set Presence |
| | | 4 = Show Sensitivity | |

Automatic Gate Compensation (AGC):

The Hy5Bs have built in compensation to ignore a moving gate over time. This Automatic Gate Compensation is normally enabled when the Hy5B is installed. The AGC can be turned on and off for each individual Hy5B installed. To enable or disable AGC, access the applicable Hy5B menu in the installer menu. While in the menu, press and hold the Reset button until the AGC menu shows on display. Use the select and arrow buttons to change the setting.

Installing Standard 11-Pin Box Type Vehicle Detectors

If standard 11-pin box type vehicle detectors are to be used, perform the following procedure.

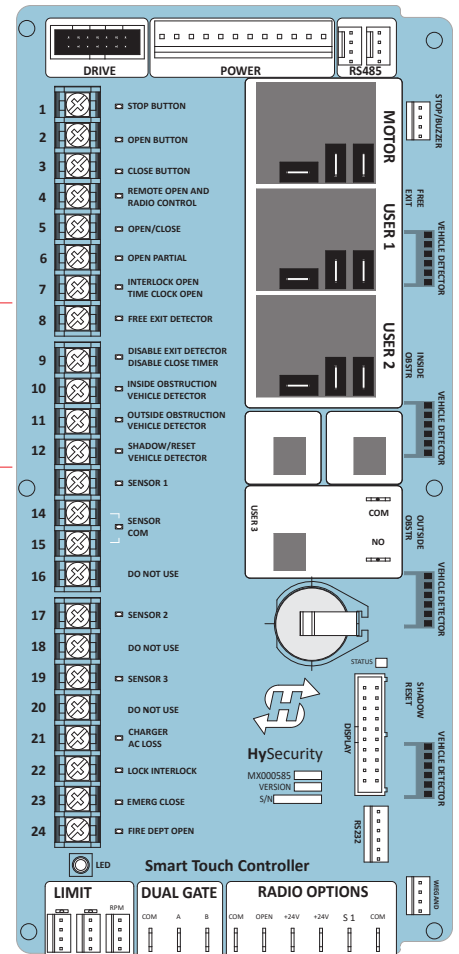
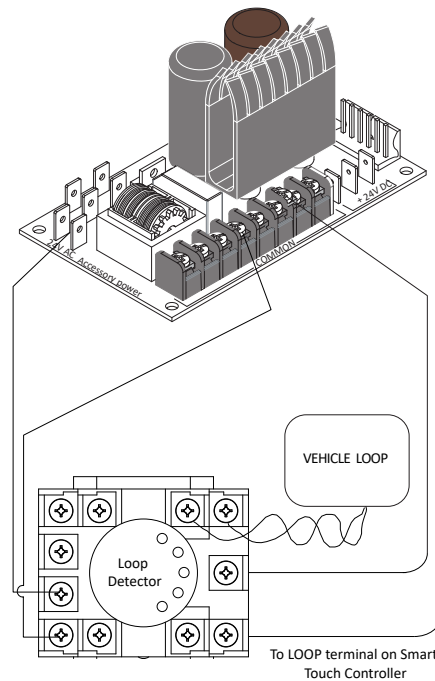
If there is sufficient space, install the sockets in the control box; if not, then install them in a separate external housing. Carefully consider your peripheral connections. Any peripheral device required for safe gate operation should be attached to 24VDC in case of an AC power outage.

NOTE: Box detectors with relays require five times more power than Hy5x detectors. One Hy5x detector draws about 0.005A. Consider Hy5x vehicle detectors for DC and Solar powered sites.

1. Connect 24 Volt power to the detector. Connect Pin No. 1 to a 24VAC or 24VDC terminal and Pin No. 2 to common.
2. Connect output Pin No. 6 to the Common Bus and output Pin No. 5 to one of the four detector terminal inputs (depending upon the detector function required) on the Smart Touch Controller.

If multiple detectors are used, route the power wires and common wire from socket to socket (daisy-chaining) rather than individually running each wire to the same location. The only wires that are separate are the output wire to the Smart Touch Controller and the detector loop input wires.

Always keep the detector loop wires well twisted beyond the area of the loop. The lead in portion sealed in a saw cut does not need to be twisted so long as the wires are encapsulated in loop sealant and cannot move.



Loop Layout: One Lane, Bi- or Single-Directional

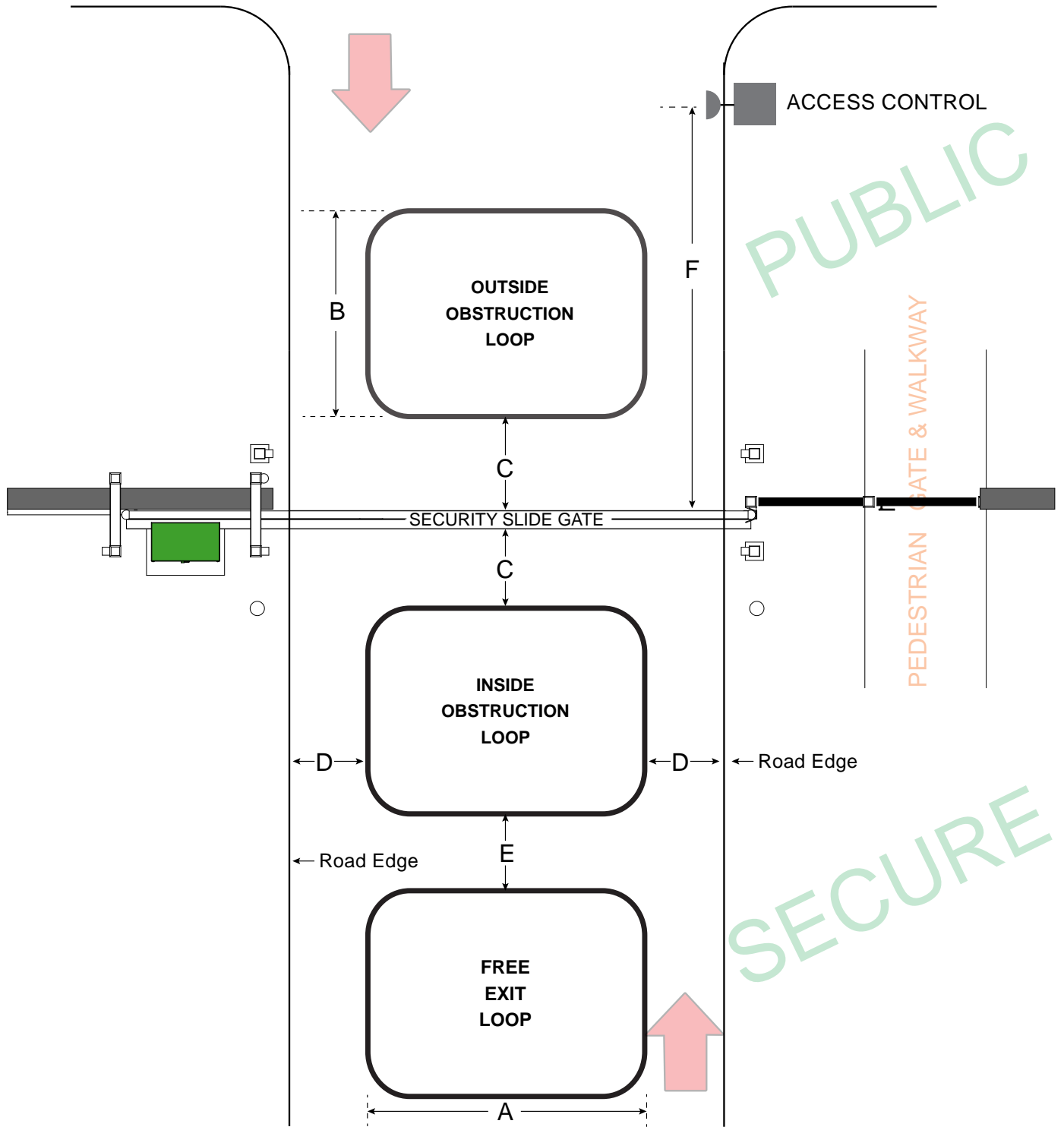
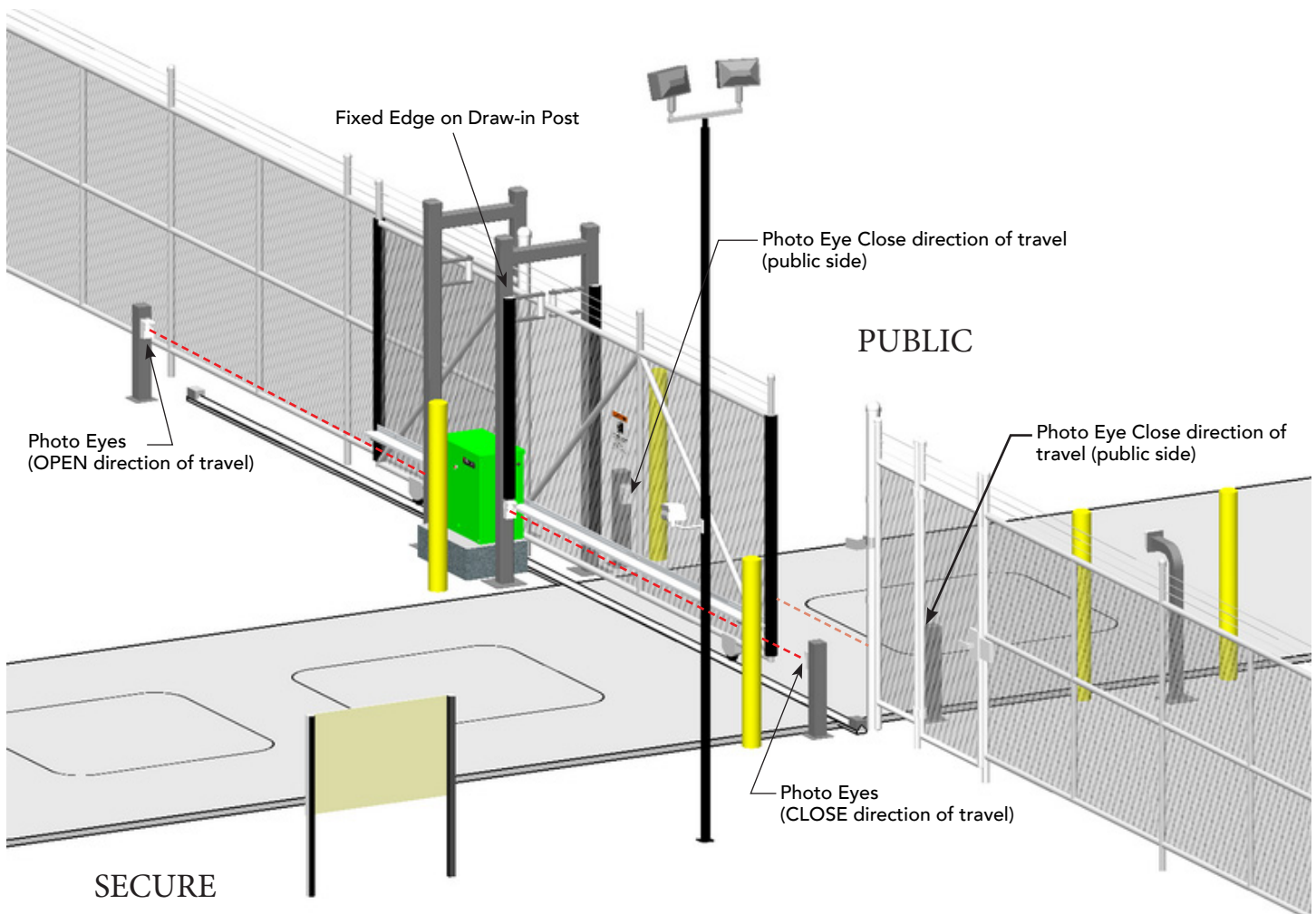


Photo Eye Installation

A monitored connection tests for the presence and correct operation of the photo eyes (and other external entrapment sensors) prior to each gate activation. The monitored connection prevents gate operation if an entrapment protection sensor is missing or any fault is present.

Sensors, such as gate edges and photoelectric beams, must be installed to protect against entrapment. These external entrapment protection sensors are required for the gate installation to be in compliance with the 2018, UL 325 Standard of Safety (7th Edition).

NOTICE: UL 325 Standard of Safety provides the MINIMUM safety standards. Site, gate hardware usage, and other conditions may dictate the use of additional safety designs/components. It is up to the gate system designer and installer to assess appropriate safety design and components above and beyond minimum UL 325 and ASTM F2200 Standard of Safety. Always check your local area codes and comply with all regulations.



NOTE: To enable fully automatic operation, this gate operator requires a MINIMUM of one external entrapment protection sensor to monitor potential entrapment zones in the open and close direction of travel. Visit www.hysecurity.com/gatesafety for more information on UL 325 standards and gate safety.

To learn more about external entrapment protection devices or to learn how to temporarily supply power to the sensors that are wired to the gate operator, review *External Entrapment Protection Sensors: What the Installer Needs to Do* on page 42 and *Supply Power to the Sensors* on page 45.

Photo Eyes (Non-Contact) Installation

Plan to integrate photo eyes (photoelectric sensors) in your site plan. Photo eyes are wired to the Controller and require low voltage conduit to the operator and power supply. Refer to *IMPORTANT SAFETY INFORMATION* on page 12.

If there are no other external entrapment protection sensors (typically an edge sensor), then for slide gates, swing gates or any site that must comply with UL 325 monitored entrapment protection regulations, it is highly recommended that at least two photo eyes are installed to serve and reverse the gate in each direction of travel (Open and Close directions).

Underwriters Laboratories requires that any non-contact sensor used as an external entrapment protection device, must be tested to, and recognized by, the UL 325 Standard.

- There are two common types of photoelectric sensors, thru-beam and retro-reflective, and each has its advantages.
 - A thru-beam sensor is generally more powerful and able to function reliably with dirty optics and in poor weather.
 - A retro-reflective sensor does not require the installation and extra wiring of a separate emitter and receiver as is required in a thru-beam system, but retro-reflective eyes are generally more problematic in poor weather. Avoid using retro-reflective devices across outdoor distances greater than 24 ft (7.3m) because of performance and reliability issues.
 - For pedestrian detection, mount thru-beam type photo eyes approximately 15" to 30" (38 to 76cm) above the ground and as close to the gate as possible. A minimum of one photo eyes is required, but two is recommended, one photo eye to guard the open direction and the other for the close direction of travel, unless gate edges for entrapment protection are installed.
- Three wires to the receiver and two wires to the emitter are all that is required.
 - Depending on how the photo eyes are to be wired, +24VDC or +12VDC, power is provided via spades located just to the right of the COM terminal strip near the left side of the board.
 - The receiver and emitter common wires are connected to the SENSOR COM terminal at the bottom, left of the Smart Touch Controller.
 - The photo eye NO or NC output wires connect to the Smart DC Controller at the Appropriate Sensor Input (1, 2, or 3). The appropriate sensor input must be programmed for Eye Open or Eye Close based on whether it spans the road or the "catch" area of an opening gate.
- If tripped while in motion, the standard function is to stop the gate and automatically restart again if the photo eye is clear within five seconds. An optional setting in the Installer Menu will cause a two second reversal of travel, or, if closing, can be programmed to reverse to full open.

NOTICE: Sensor COM & +24V is the recommended way to connect monitored photo eyes to Smart DC Controller.

NOTICE: If photo eyes are to be used for vehicle detection and logically function the same as a vehicle detector, connect the common wires to the COM terminals on the left side of the board and wire the NO output contact to the appropriate vehicle detector input: EXIT LOOP, IN OBS LOOP, and OUT OBS LOOP.

Compatibility

The UL 325 Standard of Safety requires that a photoelectric sensor be laboratory tested and “recognized” under UL 325. In order to be compatible with all HySecurity gate operators, a photo eye must be rated to function from 24 VDC source power.

A list of tested and approved external entrapment protection sensors (normally closed contacts) that are compatible with HySecurity gate operators can be found online at the following public site: [Gate Safety for HySecurity Gate Operators](#).

Installation

Install photo eyes according to the following steps.

1. Locate the photo eye in line of sight to the receiver or reflector that is mounted to protect zones of potential entrapment. Refer to site layout on 96.
2. Mount the receivers on the left or right side of the gate operator.
3. Mount the emitters just beyond the travel of the gate.

NOTE: The installation locations are intended for pedestrian detection. If photo eyes are also to be used for vehicular detection, consider (in addition to the low elevation photo eye for cars) installing another photo eye at a height of about 55 inches (140 cm) to detect semi (tractor- trailer) trucks.

Configuration

Configure photo eyes attached to gate operators manufactured in 2016 or beyond according to *Wiring HySecurity Sensors: Smart Touch* on page 138.

NOTE: HySecurity gate operators, manufactured with 2016 (or later) in the serial number, require Normally Closed output sensors. Some manufacturers label an output as N.O. (normally open), when it is actually an N.C. (normally closed) contact. Review *Install NC sensors*.

If your gate operator is manufactured prior to 2016 and your gate operator is set to Build Year 1, consider the following:

NOTE: To check the Build Year for your gate operator, press the Menu button. The gate status scroll reveals the Build Year. “Build Year Pre-2016” means the gate operator is configured for Build Year 1.

1. If the photo eye has an internal switch for setting Light Operate versus Dark Operate, select Light Operate.
2. If the photo eye has a relay output and has both N.O. and N.C. terminals, some experimentation may be required to determine the proper connection because, when its in the Light Operate mode, the output relay is normally energized and releases when the beam is blocked.
3. If the photo eye has a solid-state output, you must choose a sinking-type connection.



Photo Eye Connections: Smart Touch & Smart DC Controllers



All external entrapment protection sensors must be NC sensor outputs and wired to the SENSOR COM terminal for monitoring and powering purposes. The sensor becomes actively powered when the gate operator's motor runs.

Connect the four wires to the receiver and two wires to the emitter according to the following procedure.

A. Supply power to the sensor.

1. Obtain the +24 Volt source power at one of the three spade-terminals on the STC Power Supply Board.
2. Obtain the 24 Volt Common from SENSOR COM on the Controller.

B. Wire connection so the controller recognizes the sensor device.

3. Obtain the COM from the STC Power Supply Board.
4. Connect the N.C. output to SENSOR 1, 2, or 3.
5. Configure the Installer Menu according to your site sensor set up. Refer to *Table 4: Installer Menu Settings for SENSOR Inputs* on page 44.

NOTE: Jumper between terminals on Photo Eye sensor so you don't need to pull a fourth wire to the Controller terminal. For examples of wiring diagrams, refer to *Wiring HySecurity Sensors: Smart Touch* on page 138. To test Photo Eyes, see *Supply Power to the Sensors* on page 45.

Photo Eye Function

If the gate is stationary, a tripped photo eye will prevent the gate from starting in either direction. If tripped while in motion, the standard function is to pause the gate motion and then automatically restart again if the photo eye is clear within five seconds. Optional settings exist in the Installer Menu. Refer to Eye Close Logic and Eye Open Logic (EC and EO) in *Table 6: Installer Menu* on page 62 for more information.

Alignment:

Most photo eyes require careful optical alignment in order to aim the emitter beam to the center of the receiver or reflector. In order to avoid false triggering, it is important to carefully align the system, especially with retroreflective photo eyes. The best way to assure true centering of the beam is with some trial testing where the emitter is shifted to move the beam left and right and up and down until the range of the invisible cone of the infrared beam is known. Photo eyes usually provide alignment aid LED's for this setup, but they can be hard to see. HySecurity has provided a unique feature that turns power on to the photo eyes and causes the buzzer to chirp when the photo eyes enter and exit alignment. See "Table X. Smart DC Controller - User Menu Functions" on page XX to enable this feature. Set the menu item PE - PHOTO EYE ALIGN from a 0 to a 1. The buzzer chirps once when the emitter and photo eye receiver are not aligned. When the emitter and receiver are aligned, the buzzer chirps twice. If they go out of alignment again, the buzzer will chirp once. This "alignment mode" will automatically reset to 0 the next time the Close Limit Switch is triggered or the RESET key is pressed.

Retro-Reflective Photo Eye Systems

Correct installation and alignment of a retro-reflective photo eye and its reflector is important for trouble free performance. Any system operating at a range greater than 16 feet is more prone to false triggering due to dirty optics, condensation or poor weather. If care is taken in the initial mounting and alignment of the 3-inch reflector, the chance of problems is greatly reduced. Use only through beam photo eyes for a distances greater than 24 feet because the function of a retro-reflective photo eye will be too unreliable.

Taking steps to protect the photo eye and the reflector from being exposed to fog and being absolutely certain the photo eye is perfectly aligned will greatly reduce any false triggering of the system. The ideal mounting of a retro-reflective photo eye is inside an enclosure.

The ideal reflector mounting suspends it inside a 12-inch long piece of 3-inch PVC conduit. Cut the opening of the PVC conduit at a 45-degree angle to act as a drip shield. Hold the reflector against the backside of the PVC conduit by attaching a 3-inch male connector. Do not cement the connector. This would prevent the reflector from being reached for future cleaning. To create a mounting base, attach a 3-inch aluminum flange (electric meter hub) to the connector. This whole package can be mounted to any flat surface. Locate the reflector in the center of the invisible beam of infrared light to achieve the most sensitive alignment.

The beam center is determined by the following test: while holding the reflector in your hand, slowly raise it until the beam is no longer returned and the photo eye trips. Mark this maximum height. Now lower your hand and determine the lower limit of the infrared beam by watching for the trip point. Mark this position as well. Repeat the same procedure for left and right at the center elevation of the beam, as determined by the previous test. Once the four limits have been determined, either mount the reflector in the center of the area outlined or realign the eye for the position of the reflector. If photo eye is realigned, be sure to perform centering test again to verify that the reflector is truly in the center.

Using Photo Eye Sensors instead of Vehicle Loops

Some site conditions (for example, dirt or gravel roads) may warrant use of photo eye sensors for vehicle detection. In this type of application, the photo eye pair is connected to vehicle loop terminals on the Controller.

NOTE: A pair of photo eye sensors, used in place of vehicle loops and wired to vehicle loop terminals on the Controller, does not satisfy UL 325 Standard of Safety for "monitored" external entrapment protection. To understand external entrapment protection and how HySecurity equipment monitors sensors, refer to the section titled *Entrapment Protection* on page 38.

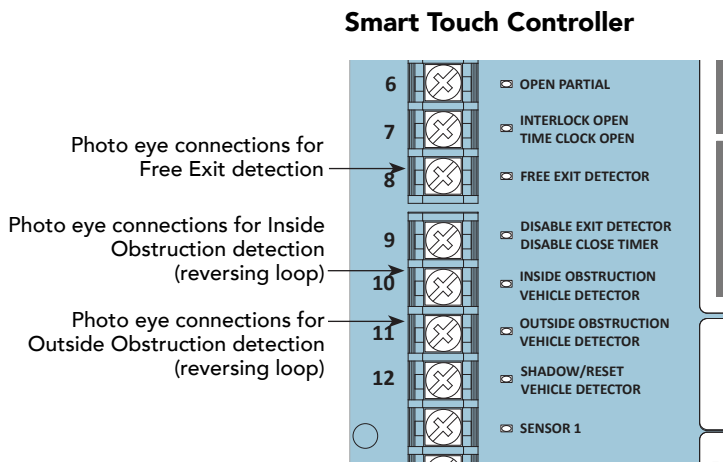


Photo Eye sensor terminal connections when PE sensors used in place of vehicle loops

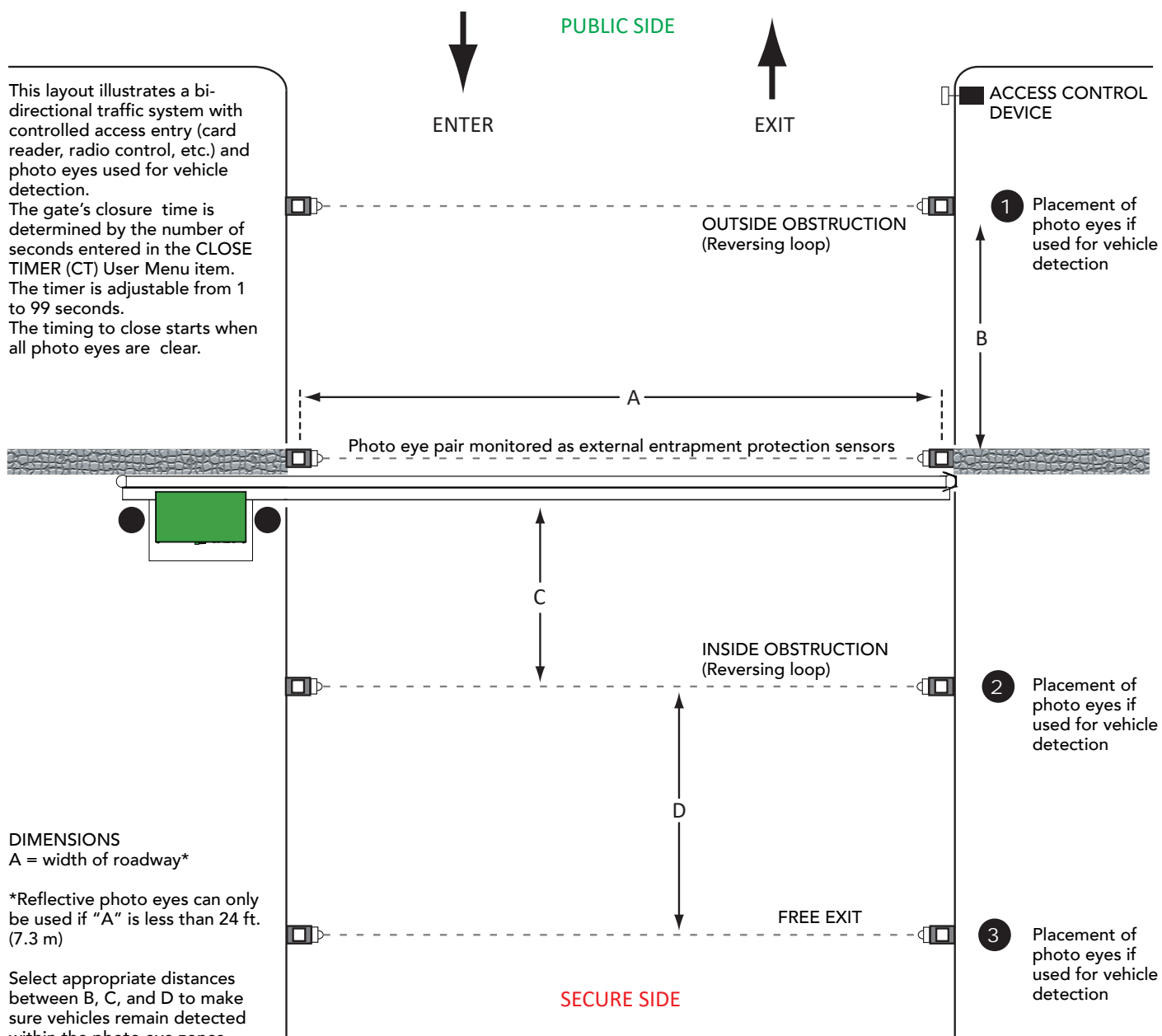
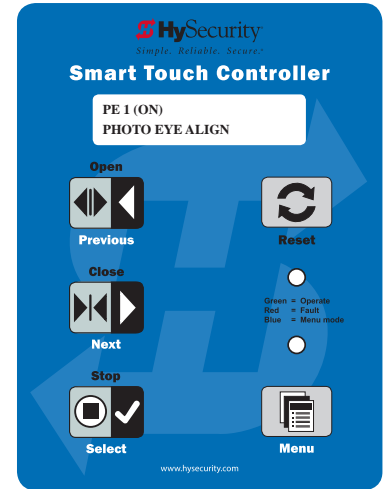


Photo Eye Alignment Feature

Most photo eyes require careful optical alignment in order to aim the emitter beam to the center of the receiver or reflector. In order to avoid false triggering, it is important to carefully align the system.

Align the photo eyes using this feature by taking the following steps:

1. Access the User Menu and select PE.
To access the User Menu, press the Menu button twice. For a refresher on using the Menu Mode navigational buttons, refer to the chart below.
2. Press NEXT and continue to press NEXT until PE 0 (OFF) appears.
3. Press SELECT.
PE characters begin blinking.
4. To turn ON photo eye alignment and temporarily power the sensors, press NEXT so PE 1 (ON) appears.
5. Press SELECT.
PE stops blinking.
6. Move the photo eyes (up/down, side to side) to align the emitter beam.



| Audible Chirp | Beam Aligned ?? |
|---------------|-----------------|
| One | No |
| Two | Yes |

7. When the buzzer chirps twice, indicating the photo eyes are aligned, set the next photo eye (if the site has one) and continue the process until all photo eyes are aligned.
8. Press MENU to exit Menu Mode and return to Run Mode.
9. Move the gate with an open or close command. When a limit is triggered, the User Menu item PE resets to zero (OFF).

NOTE: To cover the potential entrapment areas, mount photo eyes preferably within 5 inches (13 cm) of the gate face. See *Installation* on page 98. To learn how to temporarily power external entrapment protection sensors using the PE User Menu item, see *Supply Power to the Sensors* on page 45.

Smart Touch Controller: Menu Mode Navigation Buttons

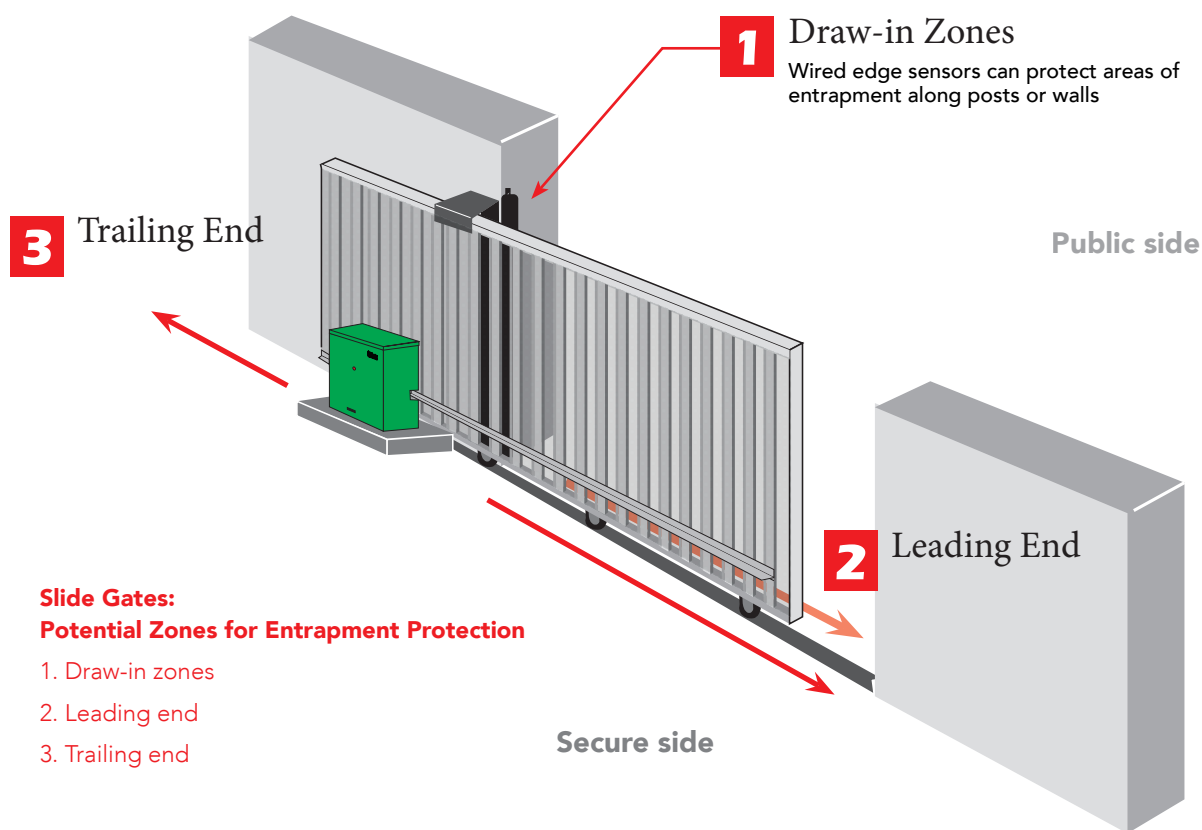
| To access Menu mode | To change menu item appearing in the display | To navigate through the menu item selections | To choose what item appears on the display | To navigate between menu items |
|------------------------------|--|---|---|--|
| Press the Menu button twice. | Press Select. Two left characters blink. | Press Next or Previous. Continue pressing Next to view all selections. | Press Select. Blinking characters become static. | Press Next or Previous. Advance - press Next Previous - press Previous |

Installing Gate Edge Sensors

A monitored connection tests for the presence and correct operation of the gate edge sensors (and other external entrapment sensors) prior to gate activation. The monitored connection prevents gate operation if a sensor is missing or any fault is present.

Sensors, such as gate edges and photoelectric beams, must be installed to protect against entrapment. These external entrapment protection sensors are required for the gate installation to be in compliance with the 2018, UL 325 Standard of Safety (7th Edition).

NOTICE: UL 325 Standard of Safety provides the MINIMUM safety standards. Site, gate hardware usage, and other conditions may dictate the use of additional safety designs/components. It is up to the gate system designer and installer to assess appropriate safety design and components above and beyond minimum UL 325 and ASTM F2200 Standard of Safety. Always check your local area codes and comply with all regulations.



Assess your gate site for the most appropriate placement of edge sensors. Plan to integrate contact (gate edge) and non-contact (photo eyes) sensors in your site plan. Sensors are wired to the Controller and require low voltage conduit to the operator and power supply. For a list of tested and approved external entrapment protection sensors available for use with HySecurity gate operators, see the [HySecurity website](#).

To enable fully automatic operation, this gate operator requires a MINIMUM of one external entrapment protection sensor to monitor potential entrapment zones in the open and close direction of travel. Visit [Gate Safety on the HySecurity website](#) for more information on UL 325 standards and gate safety.

Compatibility

The UL 325 Standard of Safety requires that an edge sensor be laboratory tested and “recognized” under UL 325. In order to be compatible with all HySecurity gate operators, a edge sensor must be rated to function from 24 VDC source power.

A list of tested and approved external entrapment protection sensors (normally closed contacts) that are compatible with HySecurity gate operators can be found online at the following public site: [Gate Safety for HySecurity Gate Operators](#).

Installation

NOTE: Follow the manufacturer’s installation and assembly instructions to properly mount the sensor. Wiring diagrams for several sensor devices are found in *Wiring HySecurity Sensors: Smart Touch on page 138*.

HySecurity gates monitor normally closed (NC) sensors. Wire the NC sensors to SENSOR input terminals (SENSOR 1, SENSOR 2, or SENSOR 3) on the Smart Touch Controller and set the Installer Menu item S1, S2, or S3 to the appropriate setting for the area being monitored.

When using wired edge sensors, the wired edge must be connected to an interface module with an NC output. ASO has UL 325 - 2016 compliant edge sensors. These edge sensors have a 10k Ω resistor that connects to an interface module. The interface module provides the NC output for monitoring purposes. Refer to *Wiring HySecurity Sensors: Smart Touch on page 138*.

For wireless edge sensors, no interface module is required. Wireless edge sensors need the wireless gate links which include a transmitter and receiver. HySecurity has created kits for all-inclusive shipment.

NOTE: The installation locations are intended for pedestrian detection and safety. The potential zones requiring entrapment protection are areas that need to be protected for pedestrian safety.

EDGE SENSOR INSTALLATION TIPS:

- If edge sensors are used sliding gates, one or more contact sensors (edge sensors) must be located at the leading edge, trailing edge and post-mounted both inside and outside of the sliding gate.
- Three-sided detectors are ideal for slide gates.
- If the clearance of the gate is 6” (15cm) or more above the road, then an edge sensor must be mounted on the bottom edge.
- If gate is sliding open to a wall with less than 16” (41cm) of clearance, mount an edge sensor to wall that aligns with gate in open position.
- Always route leads from edge sensors to gate operator so that they are protected from physical damage.
- Underwriters Laboratories requires that any contact sensor used as an external entrapment protection device must adhere to the UL 325 Standard.
- To enable monitoring of edge sensors, there must be a terminating resistor embedded in the edge. This resistor is typically 8.2K or 10K and always has a small current draw to confirm that it is installed.
- HySecurity gate operators must see a NC contact for monitoring purposes, therefore any edge sensor with a terminating resistor will need an interfacing device to convert the resistor output into a NC contact.
 - Types of devices that will convert the resistor output to NC output include the Hy2NC, the WEL-200, and the iGAZE RE.
 - Hy2NC enables the Edge Sensor to be hard wired to the board.

- The WEL-200 and the iGAZE RE are both wireless transmitter/receiver kits that communicate the state of the Edge Sensor wirelessly from the gate mounted transmitter to the operator mounted receiver.
- Hard-wired edge sensor adaptors (like Hy2NC) have inputs for up to two resistor terminated edges and up to two NC contact outputs.
- HySecurity suggests the use of hard-wired edge sensor adaptors with an edge mounted to lead fence post to protect draw-in entrapment zone when the gate is running.
- Wireless transmitters are always monitoring for presence of resistor terminated edge(s) connected to it. Status of edge is then continuously communicated back to receiver which determines when to switch NC contact to NO and tell board edge is tripped or missing.
 - Receiver can only give a NC (edge not tripped) signal or a NO (edge tripped or missing) signal to control board.
 - If edge is tripped, missing, or resistor value is too low, transmitter will communicate this information to receiver which will indicate this to control board as a tripped edge (NC contact opens).
 - Additionally, if communication between transmitter and receiver is ever lost or corrupted, due to too much RF "noise" in area, then the receiver will indicate to control board that the edge is tripped, even if edge is present and functioning normally with transmitter.
- When selecting a wireless edge as one of the external entrapment sensors, be aware of the environment around it and know that RF interference from outside sources can drastically diminish range and performance of wireless device.
 - Airports, police stations, fire departments, hospitals, and other sites with a lot of radio traffic have shown to have a lot of RF noise in frequencies that most transmitter/receiver kits function.
 - Install transmitter in a way that it is in direct line of site with receiver's antenna throughout gate motion.
 - Limit distance between transmitter(s) and receiver(s) to what is specified by manufacturer, and be aware that range may be greatly diminished when operating in a noisy RF environment.

Gate Edge Function

If the gate is stationary, a tripped gate edge sensor will prevent the gate from starting in either direction. If tripped while in motion, the standard function is to stop the gate movement and, if tripped while closing, automatically re-open fully. An optional setting in the Installer Menu will cause a 2 second reversal if triggered while closing. Refer to *Table 6: Installer Menu* on page 62 for more information.



Example: Wired gate edges used with 10K Ω (8.2K Ω) resistor



Example: Wireless gate link (transmitter & receiver) used with wireless gate edges

Troubleshooting

The Smart Touch Controller reports system malfunctions using three simultaneously occurring methods:

- Codes presented on its display (alert, fault or error)
- Activation of a buzzer which emits a series of chirps at defined intervals
- Stop gate travel (and/or reverse direction of travel)

Refer to *Table 8: Troubleshooting Codes* on page 108 for details concerning identification and description of Alerts, Faults and Errors.

Overriding a tripped sensor or fault condition on a HySecurity gate operator with monitored entrapment sensors requires a 2-step process:

- Press Open or Close momentarily. Audible beeps in quick succession indicate tripped sensors or fault conditions.
- Within 5 seconds of hearing the beeps, apply constant hold pressure to override the tripped sensor or fault. The gate operator runs while pressure is maintained to actuating device (examples include, Push button Open, Push button Close, Open Partial or Keypad Open/Close), or a limit is reached, or another sensor trips.



NOTE: A qualified technician may troubleshoot the operator with the aid of the information and procedures that follow. If it is necessary to call a distributor for assistance, be sure to have the model and serial numbers available. Other helpful information is the job name, approximate installation date, and service records of any recently-performed maintenance work.

TIP: On AC-powered gate operators, the active status of each input on the Smart Touch Controller is indicated by its associated lit LED. However, an exception exists in the case of external entrapment protection sensors. The LEDs next to the sensor connections will be lit when no power is being applied. For more information, see *Supply Power to the Sensors* on page 45.

System Diagnostic Messages

| Code | Priority | How to clear |
|-------|---|--|
| ALERT | Low | Enter new command such as Open or Close. |
| FAULT | Medium | Press the Stop or Reset button |
| ERROR | High Serious issue that may require technical service. | Errors can only be cleared by pushing the Reset button or cycling power. |

NOTE: The green LED near the coin-sized battery on the Smart Touch Controller is the “heartbeat” of the processor. This LED flashes continuously and at a constant rate when the system is operating normally. When a fault, error, or alert occurs, it turns red.

The Smart Touch Controller maintains self-diagnostics. Specific codes appear on the display and the Audio Alert buzzer emits distinctive chirping sounds. Any Alert, Fault, or Error is logged into memory and stamped with the date and time. These diagnostic messages can be retrieved for analysis purposes via optional S.T.A.R.T. software and a PC laptop.

NOTE: S.T.A.R.T. configuration and diagnostic software is available at no charge from www.hysecurity.com.

Typical Problems and Troubleshooting Procedures

A few typical problems and their associated troubleshooting procedures are provided to facilitate identification and resolution.

PROBLEM 1: Pressing the Open and Close buttons produce no response (nothing happens).

1. Verify the line voltage is present and matches the operator's input voltage requirement + 10%.
2. Verify the control voltage is present at the Power Supply Common and 24VDC terminals. It may be necessary to reset the circuit breaker (black button) on the transformer.
3. If an external Stop button is not used, verify a jumper wire connects Common to Stop.
4. Verify there are no Faults or Errors being reported on the LCD display.
5. Jump COM to the OPEN or CLOSE INPUT and verify that the LED lights on the STC board which indicates that the input is active and working properly. To help in diagnosing the problem, take note of what other inputs light up and check the display for codes.

PROBLEM 2: Hydraulic pump is running and the hydraulic pressure is between 0 - 700 PSI, but the gate is not moving.

The Smart Touch Controller reports system malfunctions on its LCD display and the buzzer will emit a series of chirps at defined intervals. Review the table of Alerts, Faults and Errors listed in *System Diagnostic Messages on page 106*. To check the status of all inputs on the terminal strip, the LED tact button must be pushed.

If the power is three-phase, verify counter-clockwise Electric Motor rotation. To reverse rotational direction, switch any two AC lines.

NOTE: The VFD Motor Controller displays trip and fault codes. Check to see if any error codes appear on the VFD display. Most VFD issues are resolved through the STC software and modbus interface.

1. Check the hydraulic fluid level by removing the plug in the pump reservoir. If necessary, add fluid at this location until the level is about ½ inch below the filler hole.
2. Unplug the hydraulic hoses and run the pump; if the pressure is low, adjust the Pressure Relief Valve.
3. If the Pressure Gauge does not respond to adjustment of the Pressure Relief Valve, completely remove the valve and depress the plunger at the nose end with a blunt tool (e.g., an Allen wrench) and blow on it to remove any debris.

PROBLEM 3: The gate only opens or only closes.

1. Verify that no external device is commanding the gate to open or close by watching the LEDs associated with each input.
2. If the gate only opens, the Directional Valve is probably stuck and needs to be checked for debris and cleared.
3. If the gate only closes, the Directional Valve Coil is not being energized or is defective.

PROBLEM 4: A run command causes PEC to appear on display.

1. Check that the photo eye is not blocked. If it is, remove the blockage and realign the photo eye. Refer to *Photo Eye Alignment Feature on page 102* and Eye Close Logic (EC) in *Troubleshooting on page 106*.
2. If you have a battery-powered photo eye, check that the batteries are viable and the batteries are fresh.

Table 8: Troubleshooting Codes

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|---------------------------------------|--|--|---|
| ALERT | HYSECURITY Entrapment Mode ENTR | 2 chirps per second every 2s while control input is active | Occurs when IES is tripped when gate is already in Safe Mode. Operator will not function until it is reset, which can occur by: <ul style="list-style-type: none"> • An Open or Stop command from a push-button control • Pressing black button on operator side • Pressing RESET button below display With any one of these inputs, operator will return to Safe Mode. Gate binding or wind can cause a false alert. | <ol style="list-style-type: none"> 1. Remove obstruction. 2. Adjust IES sensitivity. 3. Correct gate hardware. 4. Correct faulty edge sensor. 5. Check for worn motor brushes and replace, if necessary. 6. Was fire open or emergency close input tripped? |
| ALERT | HYSECURITY Safe Mode SAFE | 2 chirps once when in Safe Mode | Occurs when either edge sensor or Inherent Entrapment Sensor (IES) has been tripped. In Safe Mode, automatic close timer is disabled, but any command will reset and/or start gate in motion. Safe Mode clears when full travel is reached or RESET button is pressed. Gate binding, wind, a faulty edge sensor, or worn motor brushes can cause a false alert. | <ol style="list-style-type: none"> 1. Remove obstruction. 2. Adjust IES sensitivity. 3. Correct gate hardware. |
| ALERT | Low 24VDC DC BUSS < 21V | No chirps; LCD flashes for 1s every 5s | Only occurs in DC powered operators. Occurs when battery voltage has dropped to less than 22V. At this level, batteries are 80% depleted. Normal function until 21V. | <ol style="list-style-type: none"> 1. No AC Power. See above item. 2. Wiring / Connector problem - check all connections. Clean or repair as required. 3. Check battery condition. 4. Smart DC Controller or Smart Touch Controller charger failure - check charger voltage and replace Smart DC Controller. 5. Transformer failure - replace transformer. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|-------------------------------|---|---|---|
| ALERT | Critical Low Power | No chirps: LCD steady and controls disabled | <p>The system monitors the 24V control voltage in lieu of line voltage. Low incoming line voltage will cause low control voltage. Verify that the control transformer is connected properly, (white – 115V, red for 208V, orange for 230V and blue for 460V). Refer to <i>Control Transformer Connections (Non-UPS)</i> on page 28.</p> <p>As the motor starts, check the line voltage with a meter that has min/max hold capability. If the line voltage drops more than 10% below nominal (187 on 208 VAC, 207 on 230 VAC, or 416 on 460 VAC) the voltage is dropping too much and must be corrected. Generally, this requires larger wire size. On 3-Phase operators, check each leg to ground to make sure it is balanced.</p> <p>If the line voltage is not dropping below these limits, check the 24V AC and DC power at the power supply. Voltages less than 20V indicate an overloaded or failing transformer or power supply board. Remove the loads until the fault is found.</p> | |
| ALERT | Dead Battery DC BUSS < 21V | 3 chirps upon any operating command entry | Occurs when battery voltage has dropped to less than 21V. At this level, batteries are 90% depleted. Gate will automatically open or close depending upon setting chosen. Refer to AP - AC LOSS "User Menu" on page XX. No additional automatic function is possible, but limited push button control is available to 18V. | <ol style="list-style-type: none"> 1. No AC Power. See above item. 2. Wiring / Connector problem - check all connections. Clean or repair as required. 3. Check battery condition. 4. Smart DC Controller or Smart Touch Controller charger failure - check charger voltage and replace Smart DC Controller. 5. Transformer failure - replace transformer. |
| ALERT | No AC POWER | Chirps once whenever the gate reaches the close limit | AC power is shut off at source (breaker) or is not connected. AC power switch on operator (lower rocker switch) is turned off, or circuit breaker on the operator has tripped. | <ol style="list-style-type: none"> 1. Turn AC power switch on or connect power to operator. 2. Reset operator circuit breaker or connect power to AC switch. Correct gate hardware. 3. Reset circuit breaker at electrical panel. 4. Have a licensed electrician check wiring. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|---|--|---|-----------|
| ALERT | !ACTION BLOCKED PHOTO EYE CLOSE PEC | 5 chirps indicating that the command cannot be initiated | Photo eye input shows as tripped. <ul style="list-style-type: none"> • Clear photo eye path • Realign photo eye. Refer to <i>Photo Eye Alignment Feature on page 102.</i> • Check N.C. wiring (verify wires are not disconnected or shorted) • Review wiring diagrams. Especially path to SENSOR COM • Make sure SENSOR settings S1, S2, and S3 are correctly assigned. Refer to <i>External Entrapment Protection Sensors: What the Installer Needs to Do on page 42.</i> | |
| ALERT | !ACTION BLOCKED PHOTO EYE OPEN PEO | 5 chirps indicating that the command cannot be initiated | Photo eye input shows as tripped. <ul style="list-style-type: none"> • Clear photo eye path • Realign photo eye. Refer to <i>Photo Eye Alignment Feature on page 102.</i> • Check N.C. wiring (verify wires are not disconnected or shorted) • Review wiring diagrams. Especially path to SENSOR COM • Make sure SENSOR settings S1, S2, and S3 are correctly assigned. Refer to <i>External Entrapment Protection Sensors: What the Installer Needs to Do on page 42.</i> | |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|---|--|---|--|
| ALERT | !ACTION BLOCKED GATE EDGE (Open or Close) GEO or GEC | 5 chirps indicating that the command cannot be initiated | <p>Operator received command to run, but movement is prevented. Gate edge tripped or disconnected and causes operator to enter SAFE mode. Gate edge is not recognized as active.</p> <ul style="list-style-type: none"> • Replace transmitter batteries • If using a wireless edge sensor, be aware. Issues with radio interference cause false trips. Placing the antenna high and reducing environmental “noise” is critical to proper wireless transmission. Avoid placing the receiver sets within 100 feet of each other as crosstalk may occur. Use receivers & transmitters Version 1.02 or later. • Verify wired edges are using a gate edge converter-type module. Miller Edges must have a wire with blue tape. The blue tape indicates that a resistor is built in. • Check N.C. wiring (verify wires are not disconnected or shorted) • Review wiring diagrams. Especially path to SENSOR COM • Make sure SENSOR settings S1, S2, and S3 are correctly assigned. Refer to <i>External Entrapment Protection Sensors: What the Installer Needs to Do on page 42.</i> | |
| ALERT | ALERT 1 Forced Open | 2 pulses per second for 30s | Gate has been forced open from a full close limit and is being prevented from re-closing. | Will self-clear after an open or close input. |
| ALERT | ALERT 2 Drift Closed | 2 pulses per second for 10 seconds | Gate has been forced open from a full close limit and is being prevented from re-closing. | Will self-clear after an open or close input. |
| ALERT | ALERT 3 EXCESS DRIFT | Gate drift in transit - Advisory only. The alert appears and is being prevented from re-opening. | Alert appears if gate drifts three times in a five minute period. | Check track to make sure it is level. |
| ALERT | ALERT 4 THERMAL Overload | 2 chirps per second every 15 seconds | Electric Motor built in thermal switch has been tripped. | Check gate hardware, weight/length of gate. Alert automatically clears when temperature drops below threshold. |
| ALERT | ALERT 5 Both Lim ACTIVE | 2 chirps per second every 15 seconds | The STC is seeing both limits tripped at the same time. Check for a stuck limit switch or debris caught in limit switch area and repair any wiring issues. Ensure both limits are plugged into the board. | |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|-----------------------------|--------------------------------------|---|---|
| ALERT | ALERT 6 Lim not released | 2 chirps per second every 15 seconds | Is the pump developing pressure? Are the brake valves set properly? Is there hardware holding the gate? <ul style="list-style-type: none"> • Check fluid levels and brake valve settings. • Check for stuck limit switch | |
| ALERT | ALERT 7 Freq SHIFT FAULT | 2 chirps per second every 15 seconds | Hy5x detector has detected a frequency change outside the normal range. Likely causes are poor integrity of loops or metallic objects within range. This message will also indicate which detector alert applies to: Exit Loop (ELD), Inside Obstruction Loop (IOLD), Outside Obstruction Loop (OOLD), or Center Loop (CLD) - (User Relay 22). | Loop lead in wires and road way should be checked for problems or replaced. |
| ALERT | ALERT 8 LOOP SHORTED | 2 chirps per second every 15 seconds | Hy5x detector has detected a short circuit in the loop. Temporarily switch detector to be sure the loop is at fault and then repair it. Caused by inadequate insulation of loop wires. | Loop lead in wires and road way should be checked for problems or replaced. |
| ALERT | ALERT 9 LOOP OPEN | 2 chirps per second every 15 seconds | Hy5x detector has sensed that the loop has become an open circuit. Check all connections and/or use an ohmmeter to find out where the break is. Caused by broken loop wire or wire has come unplugged from detector. | Loop and lead in wires should be checked for problems or replaced. |
| ALERT | ALERT 10 I2C BUS ERROR | 2 chirps per second every 15 seconds | Communication issue between the Hy5x and the Smart Touch Controller; reset and try again. Replace the Hy5x if the problem continues. Caused by removal of Hy-5B or lack of integrity of socket connection. This message will also indicate which detector alert applies to: Exit Loop (ELD), Inside Obstruction Loop (IOLD), Outside Obstruction Loop (OOLD), or Center Loop (CLD). | Remove and re-install the Hy-5B and press RESET. Replace Hy-5B, if necessary. |
| ALERT | ALERT 11 DETECTOR FAULT | 2 chirps per second every 15 seconds | Unknown fault; perform the megaohm test and fix the loop if necessary. Caused by a fault within Hy-5B. This message will also indicate which detector alert applies to: Exit Loop (ELD), Inside Obstruction Loop (IOLD), Outside Obstruction Loop (OOLD), or Center Loop (CLD). | Remove and re-install the Hy-5B and press RESET. Replace Hy-5B, if necessary. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|------------------------------|--------------------------------------|---|---|
| ALERT | ALERT 12 ON TOO LONG | 2 chirps per second every 15 seconds | Caused when Smart DC Controller sees an active loop for more than 5 minutes. "Active" loop can be actual or false. This message will also indicate which detector alert applies to: Exit Loop (ELD), Inside Obstruction Loop (IOLD), Outside Obstruction Loop (OOLD), or Center Loop (CLD). | Check traffic patterns at site. Loop and lead in wires should be checked for problems or replaced. |
| ALERT | ALERT 13 STIFF GATE | 2 chirps per second every 15 seconds | The STC detects a gate that, over time, is requiring more power to move it. Caused by degrading gate hardware or debris in track. This alert appears in history log. It does not have any effect with regard to opening or closing gate. | Check and correct gate hardware as required. |
| ALERT | ALERT 14 STUCK GATE | 2 chirps per second every 15 seconds | The STC detects that it cannot move the gate because of possible broken gate hardware or ice/snow buildup. | Check and correct gate hardware as required. |
| ALERT | ALERT 15 NO TARGET | | Target magnet on the chain is missing or has not been detected. Target magnet fell off or target sensor wires are damaged - Electro-mechanical operators only. | <ol style="list-style-type: none"> 1. Make sure target is properly fastened to chain. 2. Check target sensor to make sure it is reading magnet. Change sensor if it or its wires are damaged. |
| ALERT | ALERT 16 COM BUS ERROR | | Smart Touch Controller has detected an internal communications error. <ul style="list-style-type: none"> • Excessive electrical noise. • Lack of earth grounding. • Internal problem on Smart Touch Controller. | <ol style="list-style-type: none"> 1. Determine and remedy source of electrical noise. 2. Install a ground rod. 3. Replace Smart Touch Controller. |
| ALERT | ALERT 17 BAD COIN BATTERY | 2 chirps per second every 15 seconds | Small battery on Smart Touch Controller is loose or needs replacing. Use a CR2032 coin battery. | <ol style="list-style-type: none"> 1. Verify that battery is properly seated. 2. Replace coin battery. 3. Restore power. 4. Press RESET button. |
| ALERT | ALERT 18 CHANGE BATTERY | 1 chirp a minute | Batteries are not taking a charge. The STC has detected that the 24VDC UPS batteries need to be replaced. | The buzzer will chirp every minute until the UPS batteries are replaced. |
| ALERT | ALERT 19 FALSE SLOWDOWN | 2 chirps per second every 15 seconds | Appears only on gate operators with VFD. Slowdown switch tripped and released (less than 1 second) in middle of run. Check for loose wires, limits and misaligned rails or limit ramps or wrong slowdown switch was tripped, so open slow down in close direction. Check SH setting and hoses.. | |
| ALERT | ALERT 20 EXT LOCK FAILED | 2 chirps per second every 15 seconds | An interlock contact is closed, indicating that a gate lock is engaged, preventing the operator from starting. Check the interlock terminal and wiring. | |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|-----------------------------------|--------------------------------------|---|---|
| ALERT | ALERT 21 DRIVE TRIP | 2 chirps per second every 15 seconds | Gate travel will not occur until the alert is cleared. Any open or close command resets the alert and starts the gate moving, unless the VFD is experiencing a fatal error. If you cannot clear the error alert by pressing the open or close button, contact HySecurity. | |
| ALERT | ALERT 22 INTLOCK FAILURE | 2 chirps per second every 3 seconds | Appears when the RS-485 communication connection is lost for more than 5s between interlocked (dual gate) or sequenced gate operators. | <ol style="list-style-type: none"> 1. Check cable connections and wiring. Make sure both operators are working properly and have compatible software versions. The alert auto clears when communication between the two operators is restored. 2. If the operator on site is a singular gate and the display code ALERT 22 appears, access the Installer Menu. Verify the Installer Menu items: DG (Dual gate) and SG (Sequential gate) are both set to zero. |
| ALERT | ALERT 24 EXT RELAY FAULT | 2 chirps per second every 15 seconds | <p>The Hy8Relay (extended relay module) is not being recognized. Alert noted in diagnostic log. Check the wiring:</p> <ul style="list-style-type: none"> • Make sure the slide switch on the side of the extended relay module is set at "Normal." • (Y) Data + is connected to "A" DUAL GATE. • (G) DATA - is connected to "B" DUAL GATE. • Connector cable (4-pin) attaches to RS-485. <p>If Hy8Relay module is not connected, access the Installer Menu. Check that the extended user relays are set to zero. STC = R4 to RB (7-segment display) SDC = R3 to R9 (32 character display) STC = R4 to R11 (32 character display)</p> | |
| ALERT | ALERT 25 LOW COIN BATT (HyNet) | N/A | HyNet Only. The HyNet coin battery is dying. Turn off AC power to the HyNet and replace the existing coin battery with a CR1220 coin battery. Turn On power to the HyNet. The ALERT should reset and disappear from the display. | |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-----------------------------------|-----------------------------|--------------------------------------|--|-----------|
| ALERT | ALERT 26 LIM NOT REACHED | 2 chirps per second every 15 seconds | <p>Only appears in HydraSupply XL. When valve closures or IES trips do not detect limit switch triggers or, if the appropriate limit switch is not reached within 10s of receiving an operate command and the pressure switch is open, then Alert 26 – Lim Not Reached will be declared.</p> <p>If the barrier moves by pressing an operate command, the display resets and the ALERT 26 timer rearms.</p> | |
| ALERT | ALERT 27 ACCUMULATOR LOW | 2 chirps per second every 15 seconds | <p>Only appears in HydraSupply XL. The fluid level in the accumulator is low. An EFO may not trigger properly. Have service personnel check the HydraSupply XL. Cycle the barrier and watch the pressure gauge. If the pressure is low, the blocking plate does not rise or the motor times out, check hoses for leaks. If necessary, recharge the accumulator.</p> <p>While ALERT 27 appears on the display, a renewed close command will attempt to run the barrier, but the alert will not clear unless the close limit is reached or a reset is pressed.</p> | |
| ELD OOLD IOLD SLD RLD | "Vehicle Loop Detectors" | | <p>Appears in sequence with another display code which pertains to the loop issue. Refer to the other display code for more information. ELD = Exit Loop Detector OOLD = Outside Obstruction Loop Detector IOLD = Inside Obstruction Loop Detector SLD = Shadow Loop Detector RLD = Reset Loop Detector</p> | |
| FAULT | FAULT 1 MOTOR RUN TIME | 1 chirp once every 15 seconds | <p>The STC has detected the motor is on longer than the maximum run time selected. Check and replace drive belt on applicable gate operators. Increase Max Run Timer in the Installer Menu.</p> | |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|----------------------------------|-------------------------------------|--|---|
| FAULT | FAULT 2 PHOTO EYE FAL2 | 2 chirps per second once per minute | "Monitored" means the Controller must see the photo eye N.C. contact change from open to close after receiving the command to run, but before starting the motor. FAULT 2 indicates the controller did not see this sequence when the gate received a run command or at the open limit. Check the wiring. Refer to the wiring diagram associated with the attached sensor. See <i>Wiring HySecurity Sensors: Smart Touch</i> on page 138. | Be sure the eye "common" wire is wired properly to the SENSOR COM terminal. |
| FAULT | FAULT 3 LOW VOLTAGE SAG | 2 chirps per second once per minute | The 24V control voltage is monitored in lieu of line voltage. Low incoming line voltage will cause low control voltage. Verify that the control transformer is connected properly, (white for 115V, red for 208V, orange for 230V and blue for 460V). Check the line voltage as the motor starts with a meter that has min/max hold capability. If the line voltage drops more than 10% below nominal 104 of 115VAC (187 on 208VAC, 207 on 230VAC, or 416 on 460VAC) the voltage is dropping too low and must be corrected. This condition is often caused by loose connections or the wire size being too small. If the wire is too small, it must be replaced. | |
| FAULT | FAULT 4 GATE NO LOAD | | Smart Touch Controller has detected there is no load on operator. Gate is non-operational while this fault is triggered. <ul style="list-style-type: none"> • Motor wires disconnected. • DC switch off. | <ol style="list-style-type: none"> 1. Check DC motor wires. 2. Turn DC power switch on. 3. Press RESET to clear fault. |
| FAULT | FAULT 5 LIMIT FAILED | 2 chirps per second once per minute | 50VF series only. Not applicable for StrongArm M30/M50. Slow down to stop limit took too long. Possible bad limit switch. <ul style="list-style-type: none"> • Verify limits and placement of slow down limit ramps. • With drive wheels clamped, test Open (GATE OPENING appears on display). Test Close (GATE CLOSING appears on display). Caused when limit switch is not tripped within 5s of slowdown switch trip. | |
| FAULT | FAULT 14 STUCK GATE | 2 chirps per second once per minute | The STC has tried 3 times to overcome a stuck gate. The gate is non-operational while this fault is triggered. Caused by broken gate hardware or ice/snow buildup. (Smart DC only) | <ol style="list-style-type: none"> 1. Check and correct gate hardware as required. 2. Press RESET to clear fault. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|----------------------------|-------------------------------------|---|---|
| ERROR | ERROR 1 Direction Error | 3 chirps per second once per minute | Close Limit tripped after running Open or Open Limit tripped after running Closed. Assess cables and wire connections. <ul style="list-style-type: none"> • Make sure wires are connected to the proper terminals. • Make sure gate handling is appropriate. • Swap connections of hydraulic hoses, if necessary. See <i>Gate Handling</i> on page 30. | |
| ERROR | ERROR 2 IES Disconnect | 3 chirps per second once per minute | <ul style="list-style-type: none"> • The IES sensor could be bad, check to see that the NC contact is intact with the motor not running. • Check that you have the most current sensor; visit our website and view the technical bulletins in the Tech Support area. The sensor wire could be loose; you may want to tighten the female connectors with some pliers. • Verify the version of the software by pressing the Reset button. The software version appears on the display. Make a note of it. The software version should be h4.53 (or later). • If necessary, update the software using a PC laptop and S.T.A.R.T. Register and login in at www.hysecurity.com | |
| ERROR | ERROR 3 Hy5 COMM ERROR | 3 chirps per second once per minute | Caused by Hy-5B removal or lack socket connection integrity. Message indicates which detector alert applies to: Exit Loop (ELD), Inside Obstruction Loop (IOLD), Outside Obstruction Loop (OOLD), or Center Loop (CLD). | <ol style="list-style-type: none"> 1. Press RESET. 2. Remove and reinstall Hy-5B. 3. Replace Hy-5B, if needed. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|---------------------------------------|-------------------------------------|--|--|
| ERROR | ERROR 4 PRIMARY / SECONDARY COM | 3 chirps per second once per minute | <p>Indicates a problem with the communication between the two gate operators in a bi-parting (primary/secondary) gate system.</p> <ul style="list-style-type: none"> • Check the software versions by pressing Reset or cycling power. The version number flashes on the display (examples, h4.54 or h5.56). • The software versions on the Primary and Secondary gate should be the same. If not, upload current software version using S.T.A.R.T. and a PC laptop computer. • Verify the Installer Menu item DG (DUAL GATE) is set to DG2 in Primary and set to DG1 in Secondary gate operator. • Make sure the wires are twisted and shielded. See <i>Dual Gate Wiring Connections on page 81</i>. • Be sure the low voltage wire runs, which include the bi-parting gate communication wires, are separate from any high voltage wires runs. Interference occurs if wire runs are mixed or too close to each other. <p>The error automatically clears when the communication fault is resolved.</p> | |
| ERROR | ERROR 5 NO DISPLAY | | <p>Display provides no indication of this error, but it can appear in START log and means that Smart Touch Controller has detected a serious internal error. Internal software/hardware error. Report any instance of this error to HySecurity Technical Support.</p> | <ol style="list-style-type: none"> 1. Turn both switches off to reset software. 2. Update to latest software version using START. 3. Replace Smart Touch Controller. |
| ERROR | ERROR 6 STC-VFD COMM ERR | 3 chirps per second once per minute | <p>Internal error between the STC board and the VFD. Check cable connections and wiring. Make sure both units are working properly.</p> | |
| ERROR | ERROR 7 MENU CHECKSUM ERR7 | 3 chirps per second once per minute | <p>Software issue exists that may require factory reset. Corrupt software or data.</p> | <p>Call HySecurity Technical Support for assistance.</p> |
| ERROR | ERROR 8 RPM SENSOR | 3 chirps per second once per minute | <p>RPM sensor disconnected.</p> | <p>Check wiring from the hydraulic cylinder to the STC.</p> |
| ERROR | ERROR 9 BATT DISCONNECT | 3 chirps per second once per minute | <p>Only applies to DC Power Supply connection. Smart Touch Controller detects no battery connected. Batteries are disconnected, or a wiring fault exists. Replaced by Alert 29 in h5.57 software version.</p> | <ol style="list-style-type: none"> 1. Ensure red wire in upper left corner of control box is connected to switch. 2. Correct any issues with battery wiring. 3. Check 35 amp fuse on circuit board. |

| Type | Alert/Fault/Error Display | Buzzer Chirp Sequence | Possible Cause & Suggested Corrective Action | Solutions |
|-------|---------------------------------------|-------------------------------------|--|-----------|
| ERROR | ERROR 10 SLOWDOWN SWITCH | 3 chirps per second once per minute | VFD only. The operator tripped the fully Open or Close limit before the Slowdown limit tripped. Check: <ul style="list-style-type: none"> • Slowdown limit wiring and adjustment • Adjustment of the limit ramps to verify that the limit switch is being tripped. Manually trip the slowdown limit. OPEN SLOWDOWN or CLOSE SLOWDOWN should appear on the display which indicates that it is working properly. | |
| FAIL | FAIL PROGRAM DATA ERR FR IL | 3 chirps per second once per minute | <ul style="list-style-type: none"> • Try turning off the power to the operator and having the customer re-seat all of the various connectors and cables. • Upload the latest software release. If the fail does not go away, contact Technical Support. Likely caused from interrupted firmware download. | |

Access the Event Log through the User Menu

NOTE: While you are viewing the event log, the gate operator is in Menu mode and cannot run open or close.

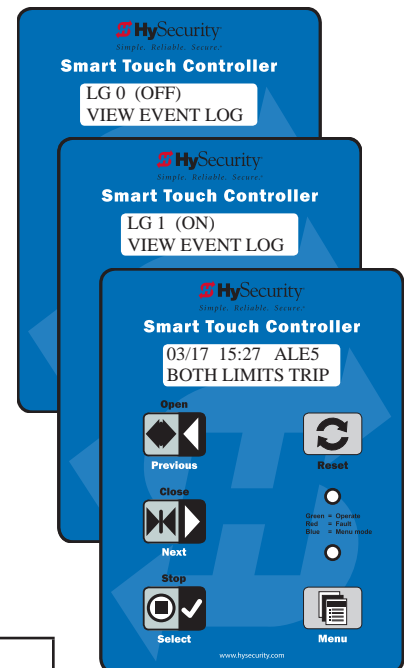
1. To enter the User Menu, press the Menu key twice.
2. Press Next and scroll until "LG 0 (OFF)" appears in the display.
3. Press Select. LG blinks.
4. Press Next to change the number to 1,
LG 1 (ON)
VIEW EVENT LOG
5. Press Select. The most recent event recorded in the log appears.
6. To scroll through the event log, press Next or Prev.

NOTE: Hold down Next or Prev to scroll quickly toward the top or bottom of the event log.

7. To exit, press Menu. The display resets to LG 0 (OFF).
8. Press Menu again to exit the User Menu and return to Run/Program mode.

| Month / Day | Time (HH:MM) | Event Type |
|--|--------------|------------|
| 03/17 | 15:27 | ALE5 |
| Description: ALERT 5: BOTH LIMITS TRIPPED | | |

NOTE: Over 300 events can be recorded before the software begins overwriting the existing log history.



The event log is also accessible through S.T.A.R.T. software with the use of a PC laptop and interface cable. Refer to the [S.T.A.R.T. User Guide](#).

Electrical Issues

A general set of troubleshooting procedures are provided in the following paragraphs. Use a voltmeter to take the measurements described in the steps. If at any point in the process, a result different than what's expected occurs, stop and identify the problem. Refer to *Wiring HySecurity Sensors: Smart Touch* on page 138.

AC-Powered Gate Operators

PROBLEM 1: Pushed the OPEN and CLOSE button, but the motor is not running.

1. Verify the incoming voltage and phase at the incoming power terminals matches the voltage and phase on the nameplate of the motor. They must match!
2. Verify the 24VAC transformer has the proper connection to the incoming power (the black wire is always connected); White = 115VAC*, Red = 208VAC, Orange = 230VAC, Blue = 480VAC.
3. Verify the primary tap wires match line voltage connected to operator. Measure the line voltage carefully to distinguish between 208V and 230V branch circuits or between 390V and 460V branch circuits. A label on top of the transformer identifies the various voltage taps. This connection must match the voltage on the operator nameplate.

NOTE: Primary taps do not exist on battery operators.

4. Verify the 24VAC is present at the Red and Green wires from the control transformer to the Power Supply Board by measuring the bottom of the power supply board at the -ACC+ connectors.
5. Verify that the main power wires are at least the minimum wire size specified in *Wire Sizing and Runs* on page 23. Be certain that the branch circuit wire size versus the distance of the run from the main panel is large enough to avoid excess voltage drop.
6. Verify 24VDC power is present on the Power Supply Board between the +24VDC terminals above the terminal strip and any screw connection on the terminal strip.
7. Be sure a 20A circuit (protected with a 20A inverse time breaker) is provided.
8. Check and make sure the operator is electrically grounded per NEC Article 250 and local codes.
9. Verify the 24VDC is present at the +24VDC and common terminals located along the lower edge of the Smart Touch Controller board. (RADIO OPTIONS, etc.)
10. Verify that the "Heart Beat" LED is blinking green.
11. Verify the display is operational on the LCD and VFD display.
12. With the knowledge that the power is correct and the electric motor runs, check the STC display. If an error, alert or fault code appears, refer to *Table 8: Troubleshooting Codes* on page 108 to determine possible resolutions.

Mechanical Issues

Gates that run smoothly and operate well significantly improve the life of the gate operator's motor and component parts. Refer to *Mechanical Maintenance on page 124*.

On site gate movement issues can usually be resolved in the short term by manually moving the gate open and close. See *Emergency Release on page 19*.

Hydraulic Issues

The speed at which the operator moves the gate is determined by the size of the hydraulic pump and software settings.



Attempting to slow gate speed by changing a valve setting will cause inefficiency and increased heating of the hydraulic system, which will degrade system performance and also may result in premature system failure.

NOTE: If the gate speed must be changed, contact your HySecurity distributor or HySecurity Tech Support.

Extremely cold weather is unlikely to seriously affect the gate speed because HySecurity employs a special grade of hydraulic fluid (Uniflow), which maintains a linear viscosity over a broad temperature range. This high quality fluid, combined with other design considerations, allows HySecurity to rate its operators for service in ambient temperatures of -40°F to 158°F (-40°C to 70°C).

If the gate speed of your operator has been affected by cold weather, perform the following:

1. Verify the gate hardware is not impaired by ice.
2. Verify that the reservoir is filled with Uniflow fluid.

NOTE: Consider adding a heater in extreme cold weather regions. A biodegradable fluid option does exist, but it does not have the same fluid viscosity at extremely low temperatures. The biodegradable fluid option has a temperature rating between -10°F and 158°F (-23°C and 70°C).

General Maintenance

Smart Touch Analyze and Retrieve Tool (S.T.A.R.T.)

HySecurity provides Smart Touch Analyze and Retrieve Tool (S.T.A.R.T.) software to help HySecurity gate operator users and installers conduct the following field service activities:

- Configure installer and user menu settings
- View the operator history (event) log
- Display monitored inputs for operator diagnostics
- Load Smart Touch Controller (STC) software



With S.T.A.R.T. software loaded on your laptop computer, you have an invaluable management tool for all HySecurity operators. The RS-232 serial port (found on the Smart Touch Controller), allows you to download system diagnostics and upload system configurations using the S.T.A.R.T. software. The free S.T.A.R.T. software is conveniently located at www.hysecurity.com. Instructions for downloading S.T.A.R.T. are on the website.

What You Need

HySecurity Serial RS-232 communication cable with USB adapter and current USB driver.

- Laptop computer with Windows PC operating system (XP, Vista, Win7, Win8, or Win 10)
- Minimum 128MB of RAM
- Minimum 5MB of hard drive disk space
- VGA graphics card (minimum resolution of 800 x 600)

Installing S.T.A.R.T. Software

Read the S.T.A.R.T. User Manual, and then take the following steps to download S.T.A.R.T. software:



The latest version of S.T.A.R.T. is encrypted. An error message will appear stating that the file is corrupt if you try to load new operator code using out-dated S.T.A.R.T. software. Be sure to “uninstall” any outdated versions of S.T.A.R.T. from your laptop and install the latest version from www.hysecurity.com.

1. Bring up your web browser and type <http://www.hysecurity.com> in the command line.
2. Click Technical Support (left column) on the HySecurity home page.
3. Click Download: Smart Touch software.
4. Enter your user name and password. If you do not have a user name, register as an online member.
5. Click S.T.A.R.T. Software for Smart Touch and SmartDC to begin the software download.
6. Read the End User License Agreement and, if you agree to the terms, click, “**I accept**” (bottom of page).

7. Save the START< >_setup.exe file to your desktop.
8. Double-click the file to begin the installation.
9. Click RUN. A setup window appears.
10. Follow the step-by-step instructions to complete the installation.*
11. When the download is complete, log off the HySecurity website. Shortcuts for the S.T.A.R.T. and STC History Logs should appear on your laptop's desktop.*

***NOTE:** Confirm you have administrative rights by clicking the following on your computer screen: Windows start ->Control Panel ->User Accounts ->User Accounts. See if your name appears as an administrator. If you are the only user of a computer, you are by default the administrator. If not, you may need to consult with your company's system administrator prior to downloading the HySecurity S.T.A.R.T. program.

Software Maintenance

STC board software is constantly being enhanced with new features that create an easier install and improve on board diagnostic tools. Check the HySecurity website for atest version of software before heading out for field maintenance.

Use S.T.A.R.T. software to download latest software version to a PC laptop and upload it to gate operator in the field.

NOTE: If site includes a bi-parting gate system, make sure software version used in Primary and Secondary operators is identical..

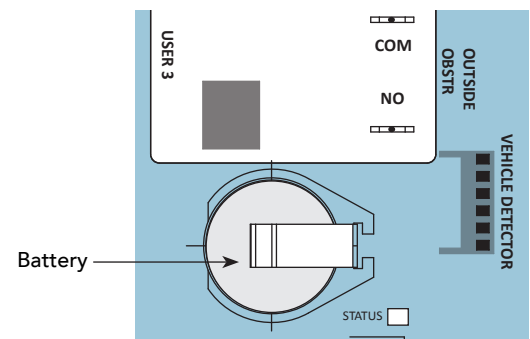
Electrical Controls

NOTICE: Before servicing, turn off all power switches.

No routine maintenance is needed for the electrical system or controls. If the environment is very sandy or dusty, or has many insects, be certain to seal all holes in the electrical enclosure. Blow the dust out of the electric panel with compressed air. Use the *Table 8: Troubleshooting Codes* on page 108 to assess and fix error, alert, and fault codes. If it is necessary to call a distributor for assistance, be sure to have your model and serial number ready. Other helpful information includes the name of the job, approximate date of installation, and the service record of the operator, especially if any work has been done recently.

Clock Battery Replacement

A lithium coin battery supports the clock, so the date and time is retained even when the main power is turned off. Replace the battery about every five years (or as needed) with a DL 2025, DL 2032, or CR 2025, or CR 2032 battery.



Mechanical Controls

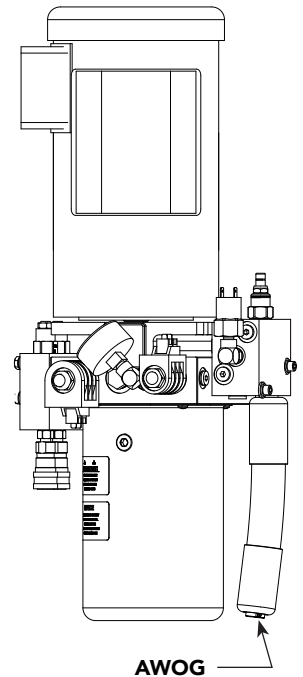
Stopping the Gate

Most models (except SlideDriver 15 and 40) employ a time delay Soft Stop system. Additionally, brake valves are used to control the stopping of heavy or fast moving gates. These valves are exclusive to HySecurity operators. They are independently adjustable to allow the gate to stop predictably and without banging.

Starting the Gate

To accommodate for loads moving beyond one foot per second, it is necessary to Soft Start the load gently and stop it smoothly. HySecurity accomplishes Soft Start with another exclusive feature we call an Accumulator With Out Gas (AWOG), which diverts some of the start-up hydraulic flow, accommodates for the load, and starts the gate smoothly, similar to letting your foot slowly off a car clutch without any lurching.

The downward facing AWOG (shown right) improves the life and performance of a gate system and never needs adjustment.



Mechanical Maintenance



Before checking internal mechanisms of operator, turn off all power switches.

SlideDriver mechanical maintenance is not in depth or difficult, but should be performed on a routine basis. Operator chassis is zinc plated and powder coated, but some environments may speed corrosion of this plating.

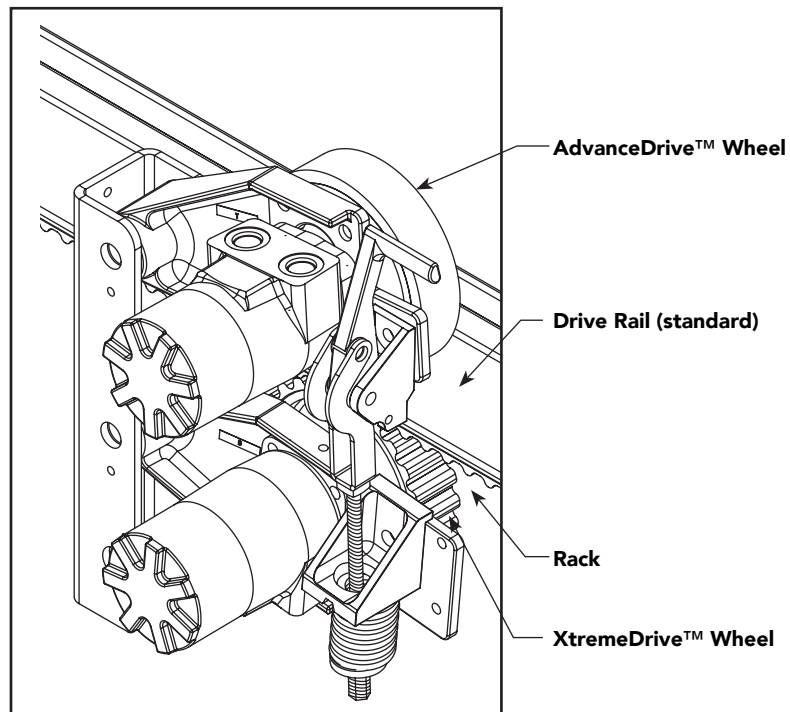
Schedule regular maintenance and look for the following:

- Verify over center clamp has proper compression (see page 126). Check for drive wheel wear and damage. Fraying edges or *galling??* indicate that the wheels may be due for replacement. Refer to "slidedriver operations and maintenance pg131.
- Check for signs of rust. If any areas of rust are found, reduce spread of corrosion by treating areas with a rust inhibitor.
- Some select models use DC motors, which contain carbon brushes which wear over time and must be replaced. Failure to replace brushes will result in DC motor damage. Brushes should be inspected every year in high usage applications or every 100,000 cycles and replaced as needed.
- Replace worn-out batteries. Refer to "DC Battery Replacement" on page 40 of the HyInverter AC Installation and Programming manual (P/N MX3644) and "ClockBattery Replacement" on page 122 of this manual.

Drive Rail

Verify that the drive rail does not move more than 1-inch up and down or ¼-inch side-to-side throughout the entire horizontal travel of the gate. Re-alignment is simple if the rail is mounted with U bolts. Adjusting the rail for side-to-side movements requires inserting shims between the rail and the gate where necessary. To adjust side-to-side movements, loosen the U bolts and add or remove shim stock. To adjust up or down, loosen the U bolts and simply tap the rail with a hammer until the correct height is reached.

If using XtremeDrive wheels, the height of the drive rail needs to be set between 9¾ to 10 inches (24 to 25 cm) from base of SlideDriver chassis if using XtremeDrive™ wheels. Review *SlideDriver Standard and Slow Down Limit Ramps* on page 33.



XtremeDrive™ System

Drive Wheel Spring Tension (Adjustment of Manual Release)

All SlideDriver operators come equipped with a toggle handle manual release mechanism to disengage the drive wheels from the drive rail.

During shipment, a piece of Styrofoam is placed between the coupling nut and the chassis. If the packaging is still in place, discard it.

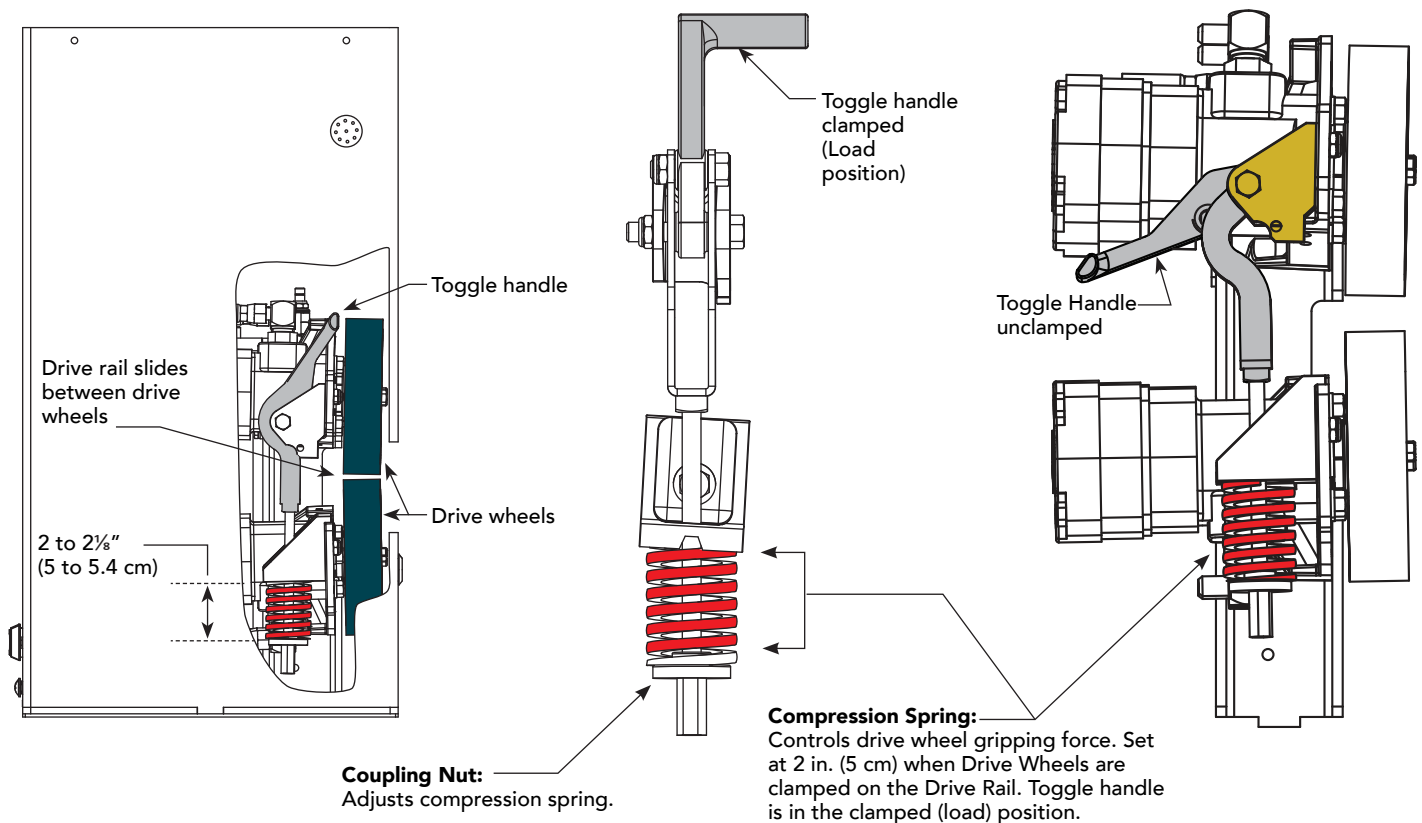


When releasing the handle inside the chassis, be careful as the mechanism is spring-loaded and drops rapidly. Hold the toggle handle appropriately so your fingers do not get pinched, hit, or crushed.

To disengage the drive wheels, simply pull the aluminum toggle handle down. As the lower drive wheel drops and disengages from the drive rail, it causes the coupling nut on the threaded rod to drop to its lowest position and push on the base of the operator. This causes the upper drive wheel to lift and disengage from the drive rail.

The coupling nut must be adjusted correctly so the wheels provide a strong clamping force on the drive rail. The red spring should measure 2 to 2½-inch (5 to 5.5cm) in height when under the correct compression.

NOTE: If the drive rail is installed at the correct height to the chassis, the toggle release mechanism spreads both wheels equally in relation to the drive rail. If the drive rail has been mounted higher than specified, it may be necessary to use an additional coupling nut and ⅜" bolt which can extend beyond the all thread and create additional lift clearance for the upper drive wheel when the toggle handle is released. If this extension method is used, adjust the ⅜" bolt so the drive wheels spread equally when they are fully disengaged.



Grooved Drive Rail

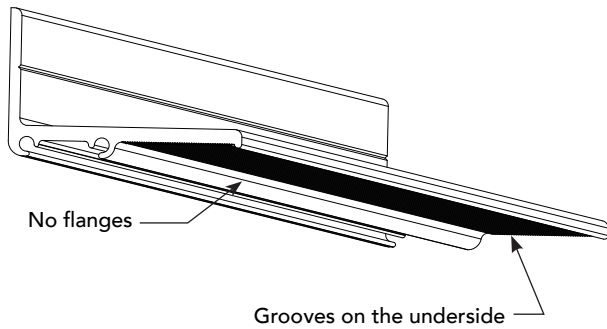
The grooved drive rail has become the standard for all SlideDriver gate operator installations.

The flanged drive rail is only used when a Solenoid Lock option is installed.

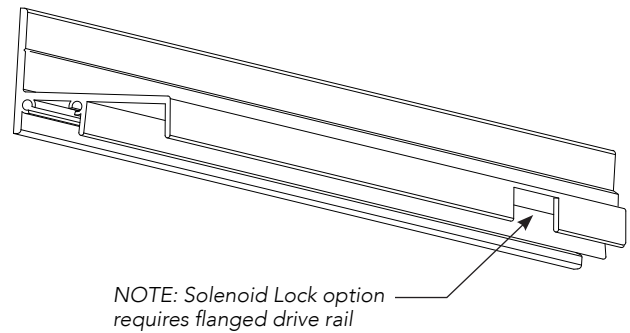
The grooved drive rail has replaced the non-grooved, flanged drive rail.

A section of the two different drive rails is shown in the illustration.

Standard grooved drive rail



Non-grooved, flanged drive rail



Grooved versus non-grooved, flanged drive rail

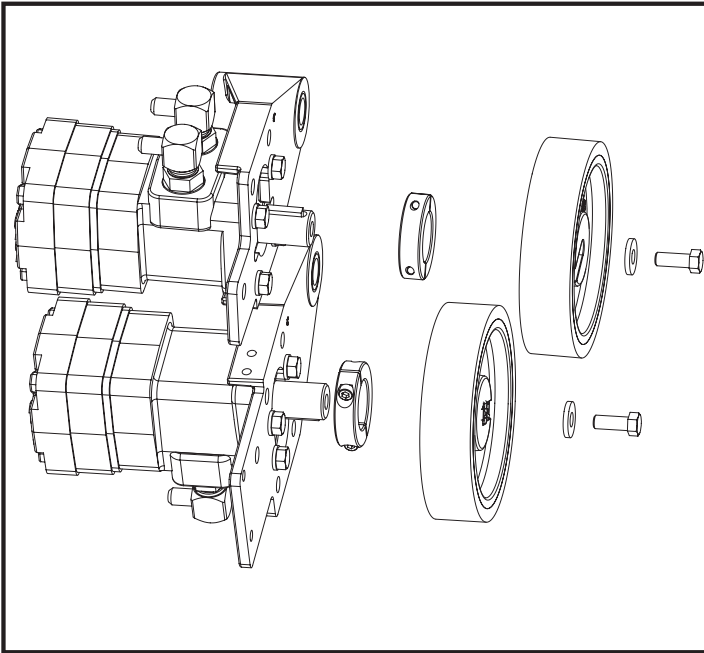
The small grooves on the underside of the drive rail improve traction in slick or wet conditions and provide more pulling and stopping power in SlideDriver installations. The three underside flanges have been eliminated which reduces drive wheel wear and drag in misaligned gate installations. Additionally, the no-flange drive rail stacks better for shipping which reduces the likelihood of freight damage.

NOTE: The non-grooved, flanged drive rail is still available for use with the Solenoid Lock option. The Solenoid Lock option requires an outer edge flange and therefore must be installed with the non-grooved, flanged drive rail.

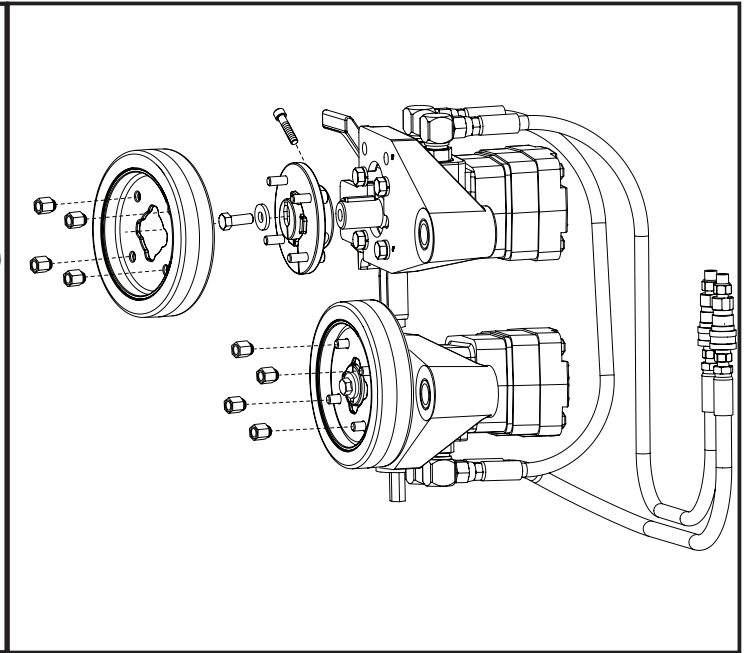
Drive Wheel Assembly

Drive wheel assembly tasks are slightly different depending on the type: AdvanceDrive™ or XtremeDrive™.

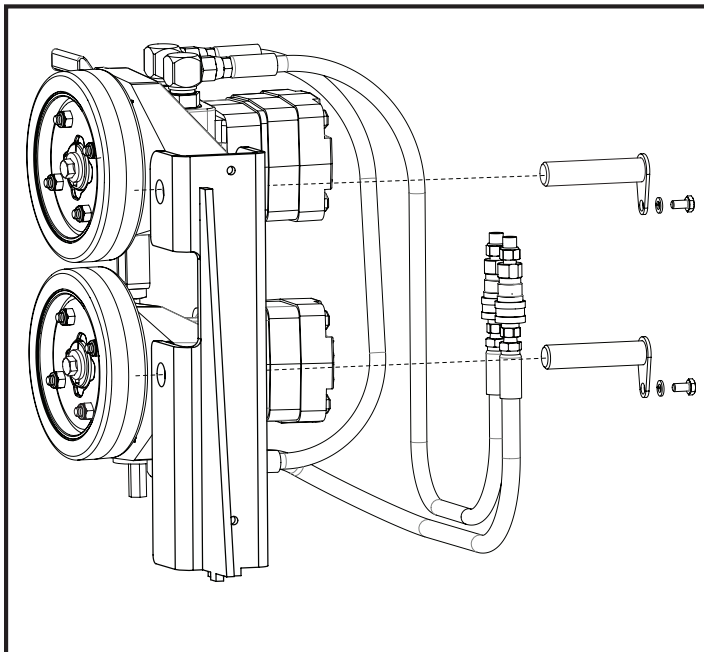
NOTE: Installation instructions are provided with the replacement drive wheels and are accessible online at www.hysecurity.com. A quick look at the drive wheel assembly is shown below. Tighten drive wheel mounting bolts to 25 ft lb.



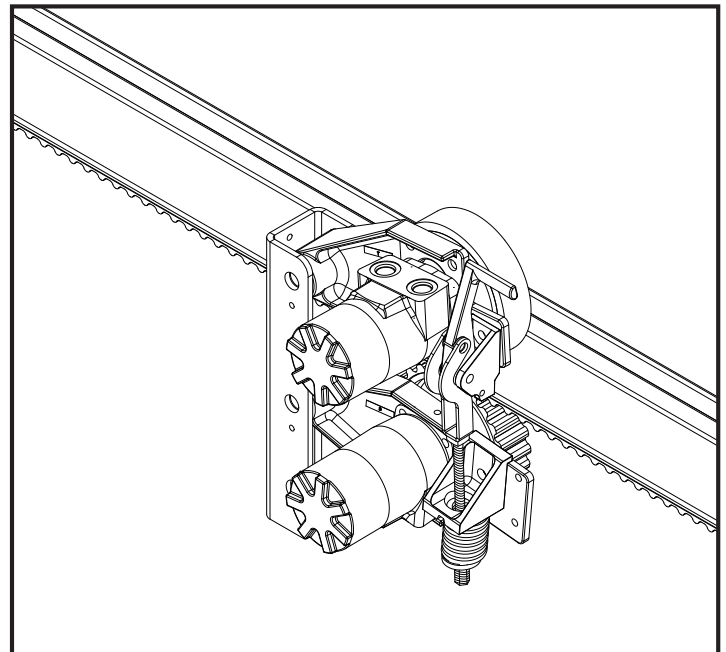
Collared Drive Wheels (pre-2015)



AdvanceDrive Wheels



AdvanceDrive Wheels assembled



AdvanceDrive and XtremeDrive Wheel combo

Hydraulic System Maintenance

Fluid Level: Under normal conditions, hydraulic systems do not consume fluid. Check the system thoroughly for leaks, before adding any fluid. If fluid needs to be added:

1. Remove the metal plug from the tank.
2. Use HySecurity Uniflow hydraulic fluid; part number MX000970. Gallon sold by our distributors.
3. Fill to within ½ inch of the plug level, and then replace plug.

NOTICE: Never use brake fluid. It will severely damage the hydraulic system. Use of any fluid other than fluid recommended by HySecurity may void the operator warranty.

Look for leaks: Occasionally there may be slight seeping at the fittings after some usage. Tightening of the fittings usually corrects the problem. If leaking persists, replace “O” rings, fittings or hoses, if required. No further leaks should occur.

To Change Fluid: Unlike a gas engine, the fluid inside a hydraulic system does not foul, so fluid changes do not need to occur often. HySecurity recommends draining the reservoir and replacing the fluid at five-year intervals. Fluid breakdown caused by heat is the main concern. If the unit is subjected to high use, or you are using the HySecurity biodegradable fluid option (especially in a warm climate), change the fluid more frequently.

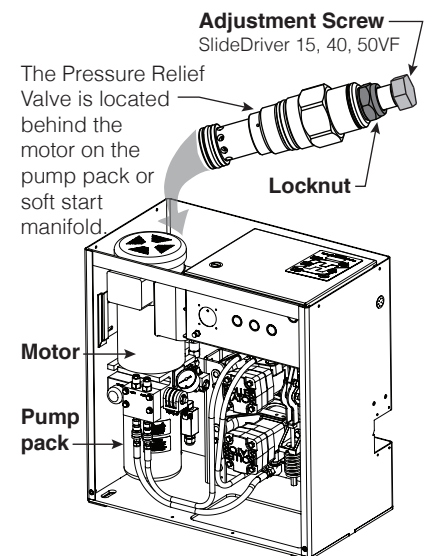
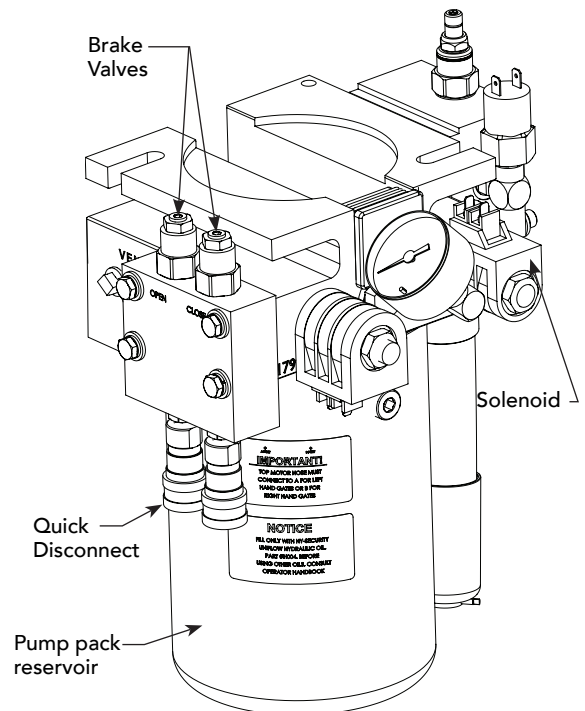
To change the hydraulic fluid,

1. Remove the reservoir from the pump pack.
2. Completely empty it.
3. Wipe the reservoir clean and clean the debris screen.
4. Re-assemble the pump unit and refill it with new Uniflow hydraulic fluid.
5. To avoid overfilling, slowly pour the fluid through the filler port near the reservoir’s top until the fluid is within one inch of the port’s opening.
6. Replace the plug and wipe up any spilled fluid. Spilled fluid dries to a sticky and messy consistency.

Cold Weather Issues:

1. Check that your reservoir is filled with our Uniflow high performance fluid.
2. Excessive ice buildup can partially or totally jam gate operation. Operate the gate manually, while clearing the ice buildup.
3. If the operator is located in an area of extreme snow conditions, regular maintenance to dig the operator out may be required. A heater option may help.

NOTE: A biodegradable fluid option does exist, but it does not have the same fluid viscosity at extremely low temperatures. Uniflow fluid temperature rating is between -40°F and 158°F (-40°C and 70°C). The biodegradable fluid has a temperature rating between -10°F and 158°F (-23°C and 70°C).

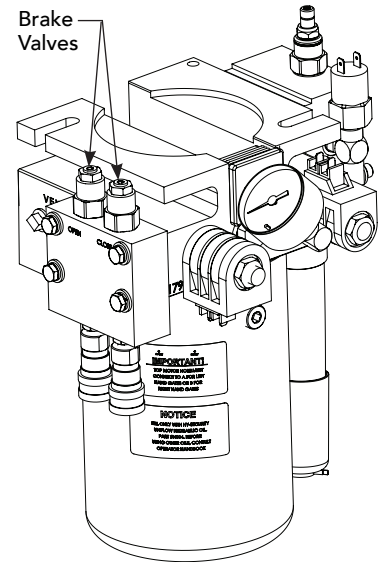


Brake Valve Adjustments

Proper adjustment of the brake valves is important for smooth operation of the gate. The position and placement of the limit ramps on the drive rail plays an important part on how the brake valves work. See *SlideDriver Standard and Slow Down Limit Ramps* on page 33.

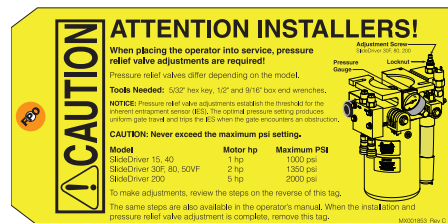
Adjustment of the brake valves, one for each direction of travel, will determine how quickly the gate actually stops. If adjustment is needed, loosen the 1/8-inch lock nut on the top of the brake valve and make 1/4-inch incremental turns on the adjustment stem with a hex key. Test cycle the gate after each incremental turn. Note that the adjustment screw varies depending on model type.

See *Adjusting the Brake Valves* on page 31.



Pressure Relief Valve Adjustments

The Pressure Relief Valve governs the maximum system hydraulic pressure. It is located on the backside of the pump. The pressure relief valve is factory set and may need to be adjusted depending on the gate weight. See *Adjusting the Pressure Relief Valve* on page 34 or refer to the yellow tag wire tied to the unit and follow the instructions.



Open Valve

The open valve is solenoid operated and, when energized, directs the hydraulic flow to open the gate. No adjustment of this valve is possible or necessary. The black solenoid coil mounts on its valve stem.

SlideDriver Operator Maintenance Schedule

| Name of part | What to do | Check at these recommended monthly intervals | | | | |
|-------------------------|---------------------------------|--|---|---|----|----|
| | | 1 | 3 | 6 | 12 | 24 |
| Gate and hardware | Check for damage and wear *1 | X | | | | |
| Drive wheels | Check for tightness and wear *2 | | X | | | |
| Wheel clamp spring | Check for clamping tension *3 | | X | | | |
| Stop limit switches | Check for adjustment *4 | | X | | | |
| Deceleration switches | Check for adjustment *4 | | | X | | |
| Anchor bolts | Check for tightness | | | X | | |
| Fluid level | Check for loss of fluid *5 | | | | X | |
| Hydraulic fluid | Drain and replace fluid | | | | | X |
| Clock battery | Replace *6 | | | | | X |
| Motor Brushes (DC Only) | Replace *7 | | | | | X |

Special Notes:

- *1. Your gate and gate hardware will require more maintenance than your HySecurity operator. A damaged gate or worn hardware may cause slow or erratic operation and will result in excess drive wheel wear. Lubricate gate hardware more frequently and check for smooth operation by opening the toggle clamping mechanism and then pushing the gate manually. One person should easily be able to push all but the largest of gates. Damaged or warped gate panels should be straightened or replaced.
- *2. Normally, drive wheel life is many years. They are designed to avoid slipping on the rail. Drive wheel life may be greatly shortened by any of these faults: clamping spring not adjusted correctly, operator or drive rail misaligned in relation to gate panel, badly warped gate panel, extremely stiff gate hardware, and/or loose wheel mounting bolts (tighten to 25 ft. lb).
- *3. Verify that the red clamping spring is compressed tightly so that drive wheels apply a strong grip on drive rail. The red spring should be compressed to 2-inches in height. See *Drive Wheel Spring Tension (Adjustment of Manual Release)* on page 126.
- *4. The limit switch and deceleration switch rollers should ride ¼ to ½-inch below the drive rail, near the center of the channel. Maladjustment may result in false or early tripping or no limit function at the end of travel. Verify that the slow down limit ramps are tightly bolted to the drive rail.
- *5. The fluid level should remain no less than one inch below the filler hole. Refer to maintenance instructions for fluid filling. Loss of fluid is not normal and indicates a leak that must be located and repaired. Use Uniflow fluid, part MX000970, if additional fluid is required.
- *6. Replace the Smart Touch Controller coin battery with DL 2025 / DL 2032 or CR 2025 / CR 2032.
- *7. DC Operators use DC motors with 4 carbon brushes which wear in normal operation. Worn brushes can damage the DC motor. Under severe conditions HySecurity recommends that brushes be checked after 2 years or 250,000 cycles and the replacement interval be adjusted as necessary.

SlideDriver Installer Checklist

This check list is provided by HySecurity and is to be used after installing a SlideDriver gate operator.

1. Before checking the items in this list, make sure power is turned OFF at the main power disconnect and the operator's control box power switch is also in the OFF position.
2. Lower the toggle handle to unclamp the drive wheels from the drive rail and check the following:
 - Gate moves smoothly and freely by hand.
 - Electric motor and transformer wired properly.
 - Incoming power supply voltage matches the label on the motor.
 - Gate operator is level.
 - Operator is labeled as appropriate for both the type and UL usage class of the gate.

Make sure the phase, hertz, and power match the operator and its labeling:

- 1 Ø
 - 3 Ø
 - 50 Hz
 - 60 Hz
 - DC-24V
 - 115 VAC
 - 208 VAC
 - 230 VAC
 - 480 VAC
 - ____V
- Power cable run to the operator is of sufficient wire size to handle starting current.
 - NEC/NFPA ground rod is installed.
 - All wires and cables are clear of moving parts (limits, valves, power, etc.).
 - Breather cap has been installed, replacing the Vent Plug in the pump.
 - Oil level checked.
 - All chassis and base riser bolts are tight.
 - Gate wheels & rollers have covers.
 - Pinch points protected.
 - 6 foot (1.8 m) minimum distance to access controls.
 - Pedestrian gate exists.
 - Physical gate stops are present.
 - On gate, protective mesh complies with ASTM F2200 and UL 325 standards.
 - Gate is not on a slope.
3. For the remaining checks, you want to cycle test the gate operator. To do so,
 - Temporarily, disconnect any peripheral devices.
 - Re-engage the wheels by lifting the toggle handle and clamping the drive wheels onto the drive rail.
 - Turn the main power ON, and then turn ON the power switch located on the operator's control box.

NOTE: Be sure to read the *Installation Instructions* and the *Programming and Operations Manual* that accompany the operator. The product literature explains, in detail, many aspects about installation, programming, maintenance and safety procedures. If you have further questions, please contact Technical Support at 800-321-9947.

4. Prior to moving the gate, make sure the wheel clamp spring is compressed to 2 inches (5 cm).

5. Cycle test the gate by pressing the CLOSE and OPEN buttons. Allow the gate to continue traveling throughout its entire range while you or your assistant check the following:
 - Gate handing is set correctly. See product literature for information on gate handing.
 - Horizontal rail surface is 9¼ in. ± ½ in. (23 cm ± 1 cm) above the pad over full gate travel. Keep in mind, if using XtremeDrive™, the placement of the drive rail is ¼ to ½ inch higher.
 - Rail flange, attached to the gate supports, remains at a distance of 1¾ in. ± ⅛ in. (4 cm ± 3 mm) from the outside edge of the operator (edge closest to the gate panel) over the full range of gate travel.
 - Drive wheel face(s) are parallel to the rail ± ⅛ in. (3 mm) with a 2 ft (61 cm) straight edge.
 - Limit switches are adjusted to clear the drive rail, but solidly contact the limit ramps.
 - Limit ramps are adjusted to stop the gate 1 to 2 inches (2 - 5 cm) from the end of the drive rail.
 - Pressure relief valve is properly set. Refer to the yellow tag inside the operator or refer to the product literature, *Adjusting the Pressure Relief Valve on page 34*.
6. External entrapment protection sensors, accessories, and options have been installed tested and comply with UL 325 Standard of Safety.
7. Check all those that apply:

| | | | |
|---|--|---|--|
| <input type="checkbox"/> Free exit | <input type="checkbox"/> Inside Obstruction Loop | <input type="checkbox"/> Outside Obstruction Loop | |
| <input type="checkbox"/> Open edge | <input type="checkbox"/> Close edge | <input type="checkbox"/> Open photo eye | <input type="checkbox"/> Close photo eye |
| <input type="checkbox"/> Stop input (1) | <input type="checkbox"/> Local Open (2) | <input type="checkbox"/> Close timer set (3) | <input type="checkbox"/> Radio open (4) |
| <input type="checkbox"/> IES sensor | <input type="checkbox"/> Fire Dept. Open | <input type="checkbox"/> Emergency Close | <input type="checkbox"/> Solenoid lock |

WARNING placards mounted on both sides of the gate within sight of vehicle and pedestrian traffic per UL 325 standards.
8. Sensors programmed properly.

Date: _____

Operator Serial Number: _____

Installer Name (please print): _____

End user's name (please print): _____

Site address: _____

Notes: _____

Appendix A - French Translations

FRENCH TRANSLATIONS

The following French translations provided below are found in the Safety Section located at the beginning of the manual.

| English | French |
|--|--|
| <p>IMPORTANT SAFETY INSTRUCTIONS WARNING – To reduce the risk of injury or death:</p> | <p>INSTRUCTIONS DE SÉCURITÉ IMPORTANTES AVERTISSEMENT – Pour réduire les risques de blessures et de mort :</p> |
| <p>1. READ AND FOLLOW ALL INSTRUCTIONS.</p> | <p>1. LISEZ CETTE NOTICE ET CONFORMEZ-VOUS AUX MISES EN GARDE</p> |
| <p>2. Never let children operate or play with gate controls. Keep the remote control away from children.</p> | <p>2. Ne laissez jamais les enfants manoeuvrer les commandes de la barrière ou jouer avec celles-ci. Laissez la télécommande hors de la portée des enfants.</p> |
| <p>3. Always keep people and objects away from the gate. NO ONE SHOULD CROSS THE PATH OF THE MOVING GATE.</p> | <p>3. Tenez toujours à l'écart de la barrière toute personne ou tout objet avoisinant. IL NE FAUT JAMAIS PASSER DANS LA TRAJECTOIRE D'UNE BARRIÈRE EN MOUVEMENT.</p> |
| <p>4. Test the gate operator monthly. The gate MUST reverse on contact with a rigid object or stop when an object activates the non-contact sensors. After adjusting the force or the limit of travel, retest the gate operator. Failure to adjust and retest the gate operator properly can increase the risk of injury or death.</p> | <p>4. Vérifiez le fonctionnement de l'ouvre-barrière une fois par mois. Le sens de la course DOIT s'inverser lorsque la barrière entre en contact avec un objet dur ou la barrière DOIT s'arrêter lorsqu'un objet active les capteurs sans contact. Vérifiez à nouveau l'ouvre-barrière après tout réglage de la force de déclenchement ou du seuil de fin de course. Un réglage incorrect de l'ouvre-barrière ou l'omission de vérifier à nouveau le fonctionnement de l'ouvre-barrière peut causer des blessures, voire la mort.</p> |
| <p>5. Use the emergency release only when the gate is not moving.</p> | <p>5. Ne déclenchez le dispositif de désaccouplement d'urgence que lorsque la barrière ne bouge pas.</p> |
| <p>6. KEEP GATES PROPERLY MAINTAINED. Read the user's manual. Have a qualified service person make repairs to gate hardware.</p> | <p>6. ASSUREZ-VOUS QUE LA BARRIÈRE EST CORRECTEMENT ENTRETENUE. Lisez le manuel de l'utilisateur. Confiez la réparation du matériel de la barrière à un technicien qualifié.</p> |
| <p>7. The entrance is for vehicles only. Pedestrians must use separate entrance.</p> | <p>7. La voie d'accès est réservée aux véhicules seulement. Les piétons doivent utiliser une voie d'accès différente.</p> |
| <p>8. SAVE THESE INSTRUCTIONS.</p> | <p>8. CONSERVEZ CES INSTRUCTIONS.</p> |

| English | French |
|---|---|
| 2.3 Install the gate operator only when: | 2.3 N'installez l'ouvre-barrière que si : |
| a. The operator is appropriate for the construction of the gate and the usage Class of the gate, | a. l'ouvre-barrière est approprié pour la structure et la classe d'utilisation de la barrière; |
| b. All openings of a horizontal slide gate are guarded or screened from the bottom of the gate to a minimum of 1.83 m (6 ft) above the ground to prevent a 57.2 mm (2-1/4 inch) diameter sphere from passing through the openings anywhere in the gate, and in that portion of the adjacent fence that the gate covers in the open position, | toutes les ouvertures de la barrière coulissante sont protégées ou grillagées du bas de la porte jusqu'à un minimum de 1,83 m (6 pi) du sol si bien qu'une sphère de 57,2 mm (2 1/4 po) de diamètre ne peut passer par une ouverture au niveau de la barrière et de la portion de la clôture adjacente que la barrière couvre en position ouverte; |
| c. All exposed pinch points are eliminated or guarded, and | c. tous les points de pincement sont éliminés ou protégés; |
| d. Guarding is supplied for exposed rollers. | d. des protections sont fournies pour les galets exposés. |
| 2.4 The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come in contact with the vehicular gate during the entire path of travel of the vehicular gate. | 2.4 L'ouvre-barrière est destiné à n'être installé que sur des barrières utilisées pour les véhicules. Il faut fournir une autre voie d'accès aux piétons. La voie d'accès pour les piétons doit être conçue pour favoriser le passage des piétons. Placez la barrière de sorte que personne ne puisse entrer en contact avec la barrière pour les véhicules sur l'ensemble de sa trajectoire |
| 2.5 The gate must be installed in a location so that enough clearance is supplied between the gate and adjacent structures when opening and closing to reduce the risk of entrapment. Swinging gates shall not open into public access areas. | c) Pour réduire les risques de coincement lors de l'ouverture et de la fermeture, la barrière doit être installée dans un endroit où la barrière et les structures avoisinantes sont suffisamment éloignées l'une de l'autre. Les barrières battantes ne doivent pas ouvrir dans une zone d'accès public. |

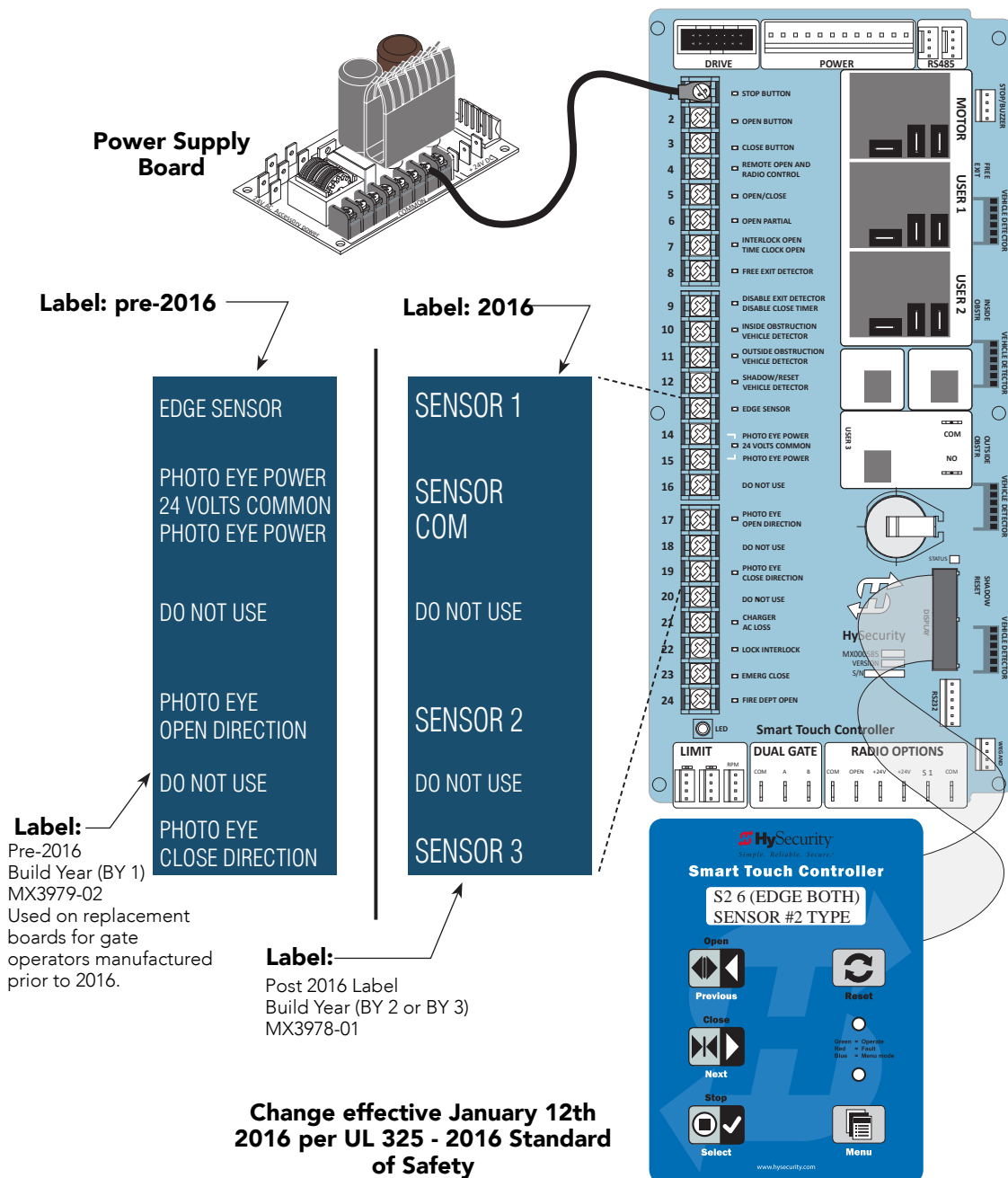
| English | French |
|--|---|
| <p>2.6 The gate must be properly installed and work freely in both directions prior to the installation of the gate operator. Do not over-tighten the operator clutch or pressure relief valve to compensate for a damaged gate.</p> | <p>2.6 La barrière doit être bien installée et fonctionner librement dans les deux directions avant d'entreprendre l'installation de l'ouvre-barrière. Ne serrez pas trop l'embrayage ou la soupape de surpression de l'ouvre-barrière pour compenser une barrière endommagée.</p> |
| <p>2.7 Controls intended for user activation must be located at least 1.83 m (6 ft) away from any moving part of the gate and where the user is prevented from reaching over, under, around or through the gate to operate the controls. Exception: Emergency access controls only accessible by authorized personnel (e.g. fire, police, EMS) may be placed at any location in the line-of-sight of the gate.</p> | <p>2.7 Les commandes destinées à l'activation par l'utilisateur doivent être situées à au moins 1,83 m (6 pi) des pièces mobiles de la barrière et à un endroit où l'utilisateur ne peut pas atteindre les commandes par le dessus, par le dessous, par les côtés et au travers de la barrière. Exception : Les commandes d'accès d'urgence accessibles au personnel autorisé seulement (p. ex. pompier, policier, SMU) peuvent être placées à tout endroit dans le champ de visibilité de la barrière.</p> |
| <p>2.8 The Stop and/or Reset button must be located in the line of-sight of the gate. Activation of the reset control shall not cause the operator to start.</p> | <p>2.8 Le bouton d'arrêt, le bouton de réenclenchement ou ces deux boutons doivent être situés dans le champ de visibilité de la barrière. L'activation des commandes de réenclenchement ne doit pas mettre en marche l'ouvrebarrière.</p> |
| <p>2.9 A minimum of two (2) WARNING SIGNS shall be installed, in the area of the gate. Each placard is to be visible by persons located on the side of the gate on which the placard is installed.</p> | <p>2.9 Au moins deux panneaux de mise en garde doivent être installés dans la zone de la barrière. Chaque étiquette doit être visible des personnes situées de chaque côté de la barrière sur laquelle l'étiquette est installée.</p> |
| <p>2.10 For gate operators utilizing a non-contact sensor</p> | <p>2.10 Pour les ouvre-barrières qui fonctionnent avec des capteurs</p> |
| <p>a. See instructions on the placement of non-contact sensors for each Type of application,</p> | <p>a. Voir les instructions sur le positionnement des capteurs sans contact pour chaque type d'utilisation.</p> |
| <p>b. Care shall be exercised to reduce the risk of nuisance tripping, such as when a vehicle, trips the sensor while the gate is still moving, and</p> | <p>b. Des précautions doivent être prises pour réduire les risques de déclenchement inutile, comme lorsqu'un véhicule déclenche le capteur alors que la barrière est encore en mouvement.</p> |
| <p>c. One or more non-contact sensors shall be located where the risk of entrapment or obstruction exists, such as the perimeter reachable by a moving gate or barrier.</p> | <p>c. Un capteur sans contact ou plus doit être situé où il existe un risque de coincement ou d'obstruction, comme dans l'espace que peut occuper la barrière lorsqu'elle est en mouvement.</p> |
| <p>2.11 For a gate operator utilizing a contact sensor</p> | <p>2.11 Pour les ouvre-barrières qui fonctionnent avec des capteurs</p> |

| English | French |
|---|---|
| <p>a. One or more contact sensors shall be located where the risk of entrapment or obstruction exists, such as at the leading edge, trailing edge, and postmounted both inside and outside of a vehicular horizontal slide gate.</p> | <p>a. Au moins un capteur de contact doit être situé où il existe un risque de coincement ou d'obstruction, comme sur le bord d'ouverture, sur le bord de fermeture et sur les poteaux montés sur l'intérieur ou l'extérieur d'une barrière coulissante pour véhicules.</p> |
| <p>b. A hardwired contact sensor shall be located and its wiring arranged so that the communication between the sensor and the gate operator is not subjected to mechanical damage.</p> | <p>b. Un capteur de contact doit être installé et câblé de sorte à éviter que la communication entre le capteur et l'ouvrebarrière soit gênée par des dommages mécaniques.</p> |
| <p>c. A wireless device such as one that transmits radio frequency (RF) signals to the gate operator for entrapment protection functions shall be located where the transmission of the signals are not obstructed or impeded by building structures, natural landscaping or similar obstruction. A wireless device shall function under the intended end-use conditions.</p> | <p>c. Un dispositif sans fil, comme un appareil qui transmet des signaux de radiofréquence (RF) à l'ouvre-barrière pour prévenir le coincement, doit être situé à un endroit où la transmission des signaux ne sera pas obstruée ou gênée par des structures, des arbres ou d'autres obstacles similaires. Un dispositif sans fil doit fonctionner selon les conditions d'utilisation finale prévues.</p> |
| <p>d. One or more contact sensors shall be located on the inside and outside leading edge of a swing gate. Additionally, if the bottom edge of a swing gate is greater than 152 mm (6 inches) but less than 406 mm (16 inches) above the ground at any point in its arc of travel, one or more contact sensors shall be located on the bottom edge.</p> | <p>d. Au moins un capteur de contact doit être situé sur les bords d'ouverture intérieur et extérieur d'une barrière battante. De plus, si le dessous d'une barrière battante est situé à plus de 152 mm (6 po) mais à moins de 406 mm (16 po) du sol à l'un des points de sa trajectoire, au moins un capteur de contact doit être situé sur le bord inférieur.</p> |

Wiring HySecurity Sensors: Smart Touch

Wiring diagrams are provided on the following pages. The diagrams illustrate how to connect sensors and program the gate operator. HySecurity Smart Touch gate operators can monitor entrapment protection sensors per UL 325 - 2016 Standard of Safety using software version h4.50 (or later).

The site designer or installer must determine which external entrapment protection sensors will be installed with the gate operator to create a UL 325 compliant installation site. For additional information, review [Gate Safety on the HySecurity website](#).

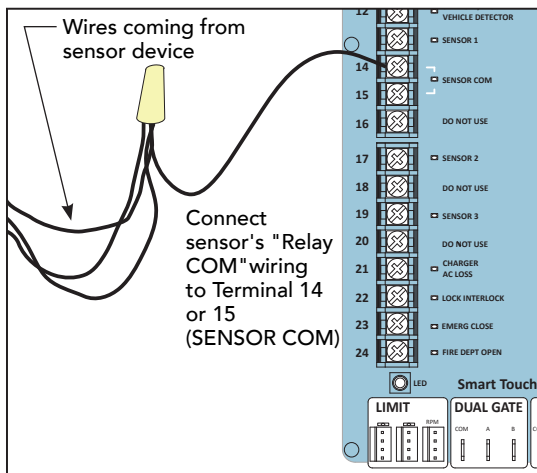


Wiring Tips for SENSOR COM Terminal: Smart Touch

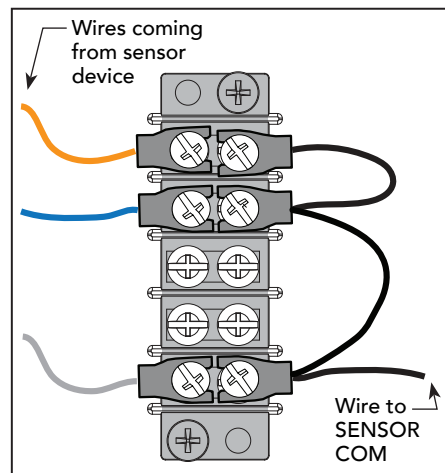
Two SENSOR COM terminals exist (Terminal 14 and Terminal 15). If using multiple sensor devices, use a wire nut as a junction and pigtail to SENSOR COM. Or, install a separate terminal block and jumper outputs to one



All external entrapment protection sensors must be NC sensor outputs and wired to the SENSOR COM terminal for monitoring and powering purposes. The sensor becomes actively powered when the gate operator receives a run command.



Wire nut and pigtail to SENSOR COM



Add terminal block

NOTE: LEDs next to the sensor connections will be lit when NO POWER is being applied. To temporarily supply power to the sensors. see See *Photo Eye Alignment Feature* on page 102. When PE is turned ON, the LEDs turn off. If they do not turn off, check for wiring issues such as a short or misapplied relay COM connections. See *Supply Power to the Sensors* on page 45.

lead for either SENSOR COM terminal.

Menu Mode Navigational Tips

To access Menu mode, press the Menu button twice. The gate operator will not run while in Menu Mode. The buttons on the display keypad perform certain functions while in Menu Mode. Refer to the chart.

| To change data appearing in the display | To navigate through the Selections | To choose what appears on the display | To navigate between menu items |
|---|--|---|---|
| Press Select . Two left characters blink. | Press Next or Previous . Continue pressing Next to view all selections. | Press Select . Blinking characters become static. | Press Next or Previous . Advance - press Next Previous - press Previous |

Smart Touch: 2 CH Wired Edge with Hy2NC

The wiring diagram illustrates a WIRED edge receiver connected to the STC controller via the 2 channel Wired Edge Sensor N/C adapter Hy2NC™.

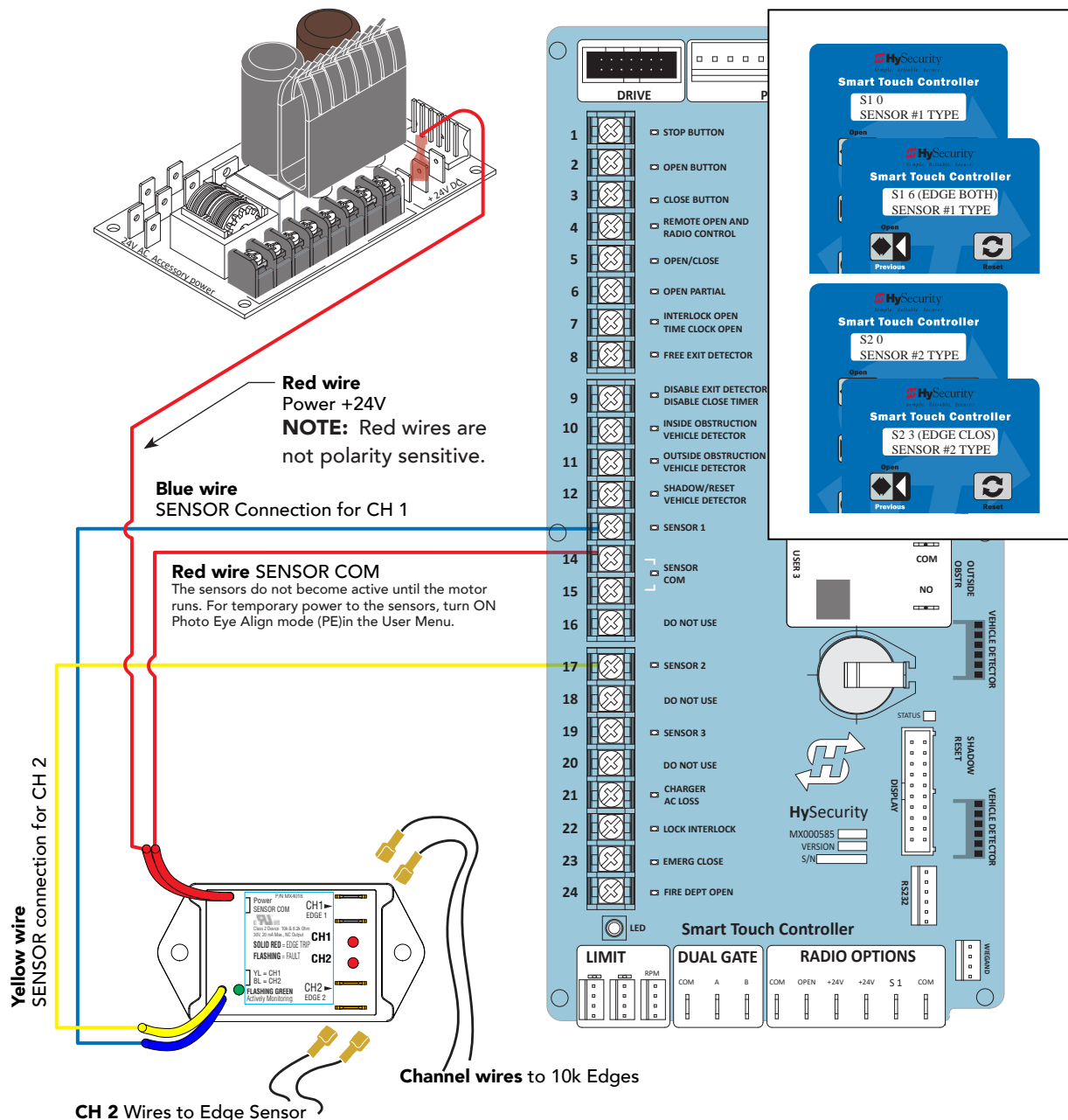
NOTE: Turn OFF AC power before connecting sensor wires to the Smart Touch Controller.



Connect all contact and non-contact sensors to same power source. Example, Do NOT connect photo eyes to +24VDC and gate edges to +12VDC. Incompatible electricity flow. A FAULT 2 will appear.



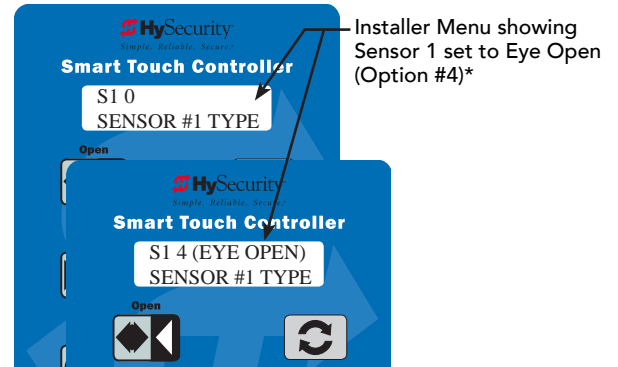
All external entrapment protection sensors must be NC sensor outputs and wired to the SENSOR COM terminal for monitoring and powering purposes. The sensor becomes actively powered when the gate operator receives a run command.



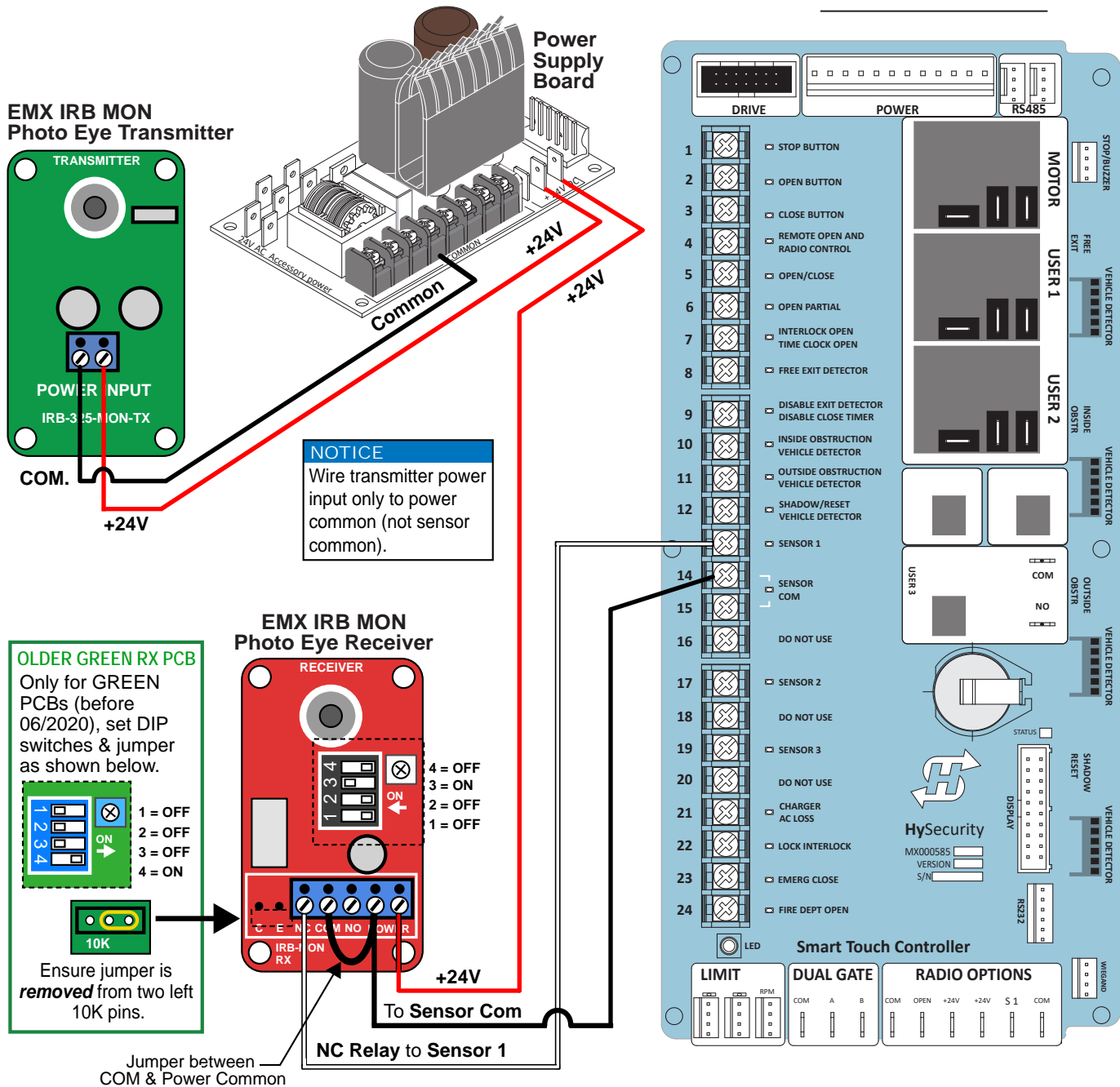
Smart Touch: Photo Eye Thru Beam (EMX IRB MON)

1. Connect photo eye wiring.
NOTE: Run a jumper between photo eye -24V (POWER INPUT) and COM terminals on the Receiver.
2. Turn ON power.
3. Access the Installer Menu and configure SENSOR setting according to the entrapment area that the photo eye is monitoring. Refer to table on page 44.

***NOTE:** Make sure whichever wired input used (SENSOR 1, 2, or 3) is the same Sensor # configured through the Installer Menu.

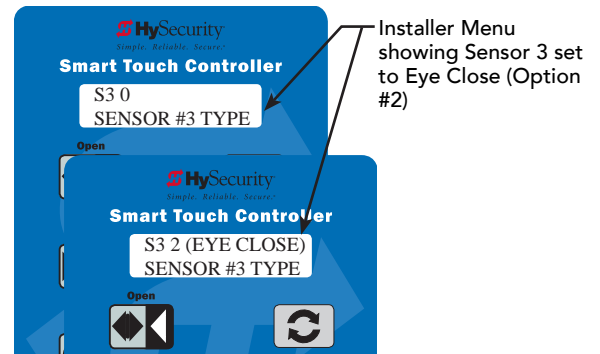


NOTICE
 DIP switches must be set as shown, otherwise the photo eye will not operate correctly. Note that older green receiver PCBs are set differently from the newer red PCBs. If you receive an Alert, "IACTION BLOCKED" "Photo Eye Open" PEO or "Photo Eye Close" PEC, take steps to align the photo eye. See Photo Eye Alignment Feature on page 102.



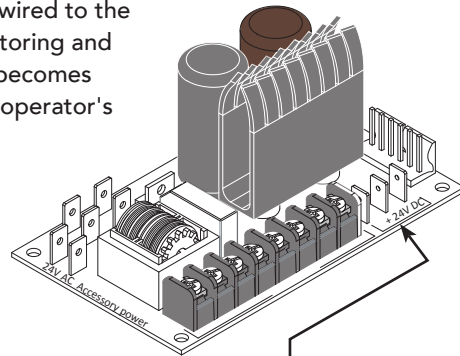
Smart Touch: Photo Eye / Reflective (E3K R10K4)

1. **Set Photo Eye switch to LIGHT ON. See NOTE.**
1. Connect photo eye wiring.
NOTE: Run a jumper between photo eye -24V and Relay COM (C2) terminals. See photo.
2. Turn ON power.
3. Access the Installer Menu and configure SENSOR setting according to the entrapment area that the photo eye is monitoring. Refer to *Table 4: Installer Menu Settings for SENSOR Inputs on page 44.*



All external entrapment protection sensors must be NC sensor outputs and wired to the SENSOR COM terminal for monitoring and powering purposes. The sensor becomes actively powered when the gate operator's motor runs.

Power Supply Board



Omron (E3K R10K4)

Reflective Photo Eye

NOTE: Light/Dark switch must be set to LIGHT ON.



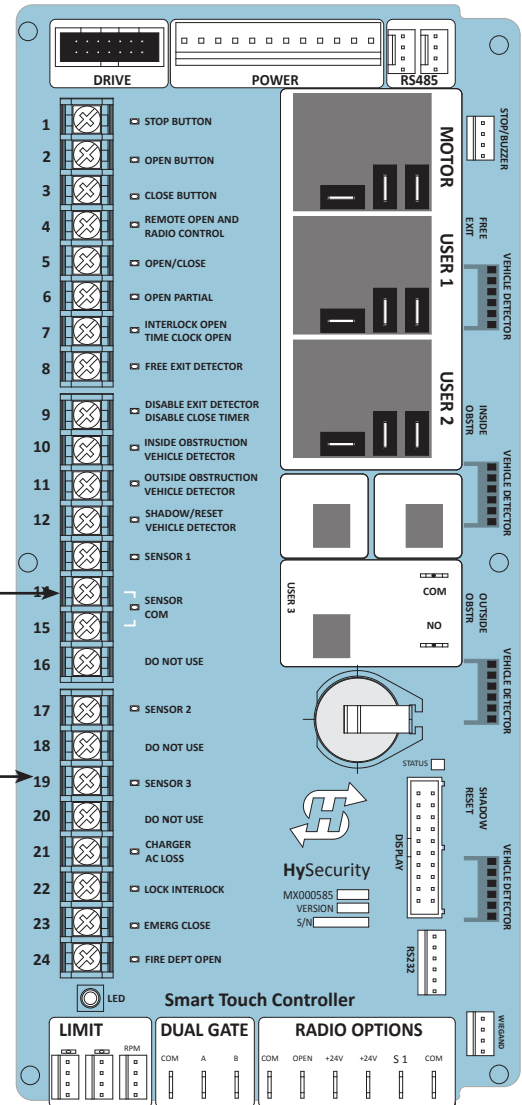
Do NOT connect the 10K resistor to HySecurity gate operators. Follow the instructions on this sheet to avoid FAULT 2.

+24V

Jumper -24V to Relay COM (Terminal 6, C2)

Relay NO (Terminal 5, NO2)

COMMON / NEG. to SENSOR COM



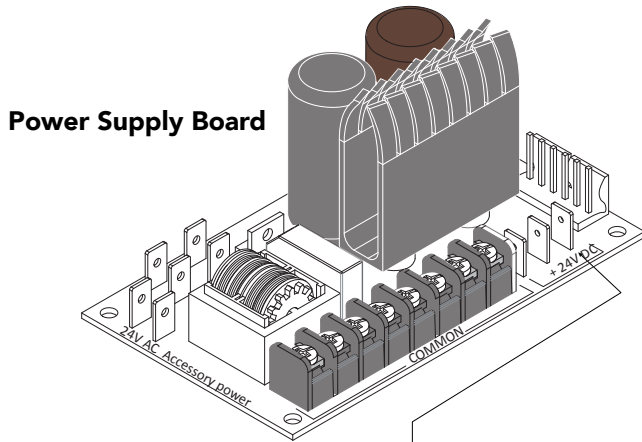
NOTE: If you receive an Alert, "!ACTION BLOCKED" "Photo Eye Open" PEO or "Photo Eye Close" PEC, take steps to align the photo eye. Refer to See *Photo Eye Alignment Feature on page 102.*

Smart Touch: The Solution, MIM-62 (Multi-input Module)

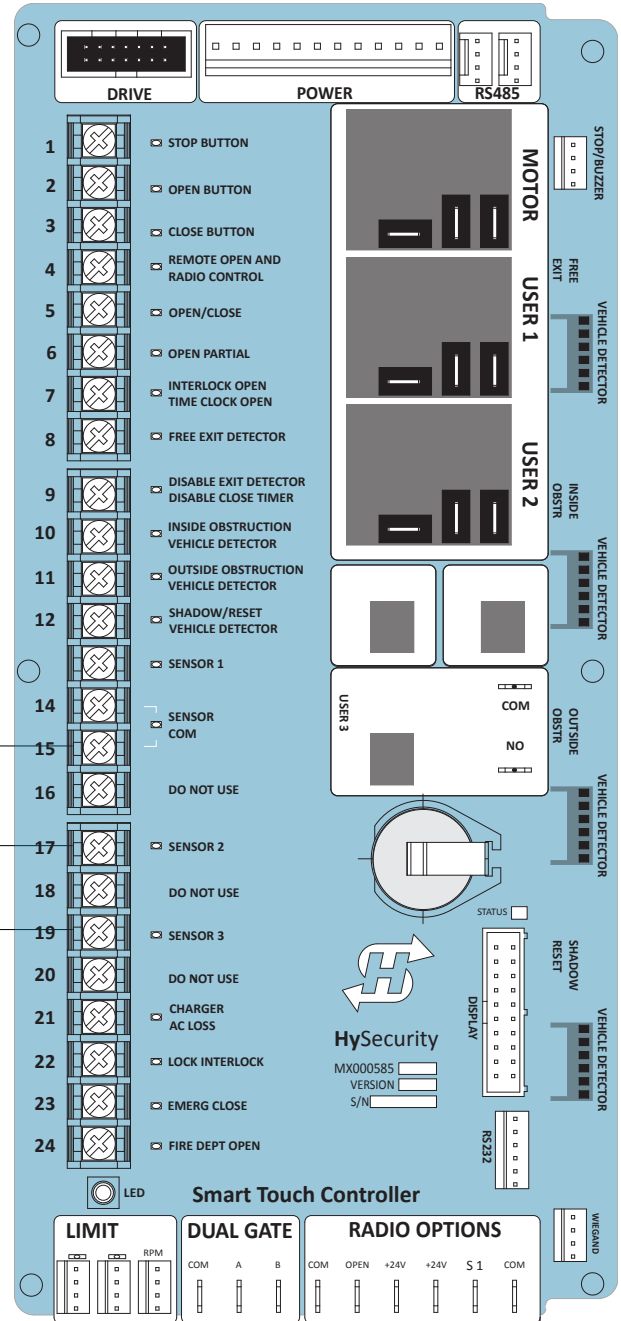
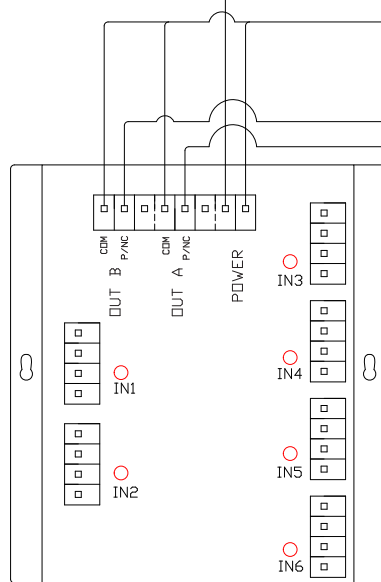
1. Turn OFF AC power.
2. Input channels 1 and 2 must be used and are always assigned to OUTPUT A.
3. All other input channels may be configured to either A or B.

NOTE: If different sensor types are connected to the same output, then program the Controller SENSOR type for EDGE options.

4. Turn ON power.
5. Access the Installer Menu. Configure SENSOR setting according to the types of sensors wired to the Smart Touch Controller.

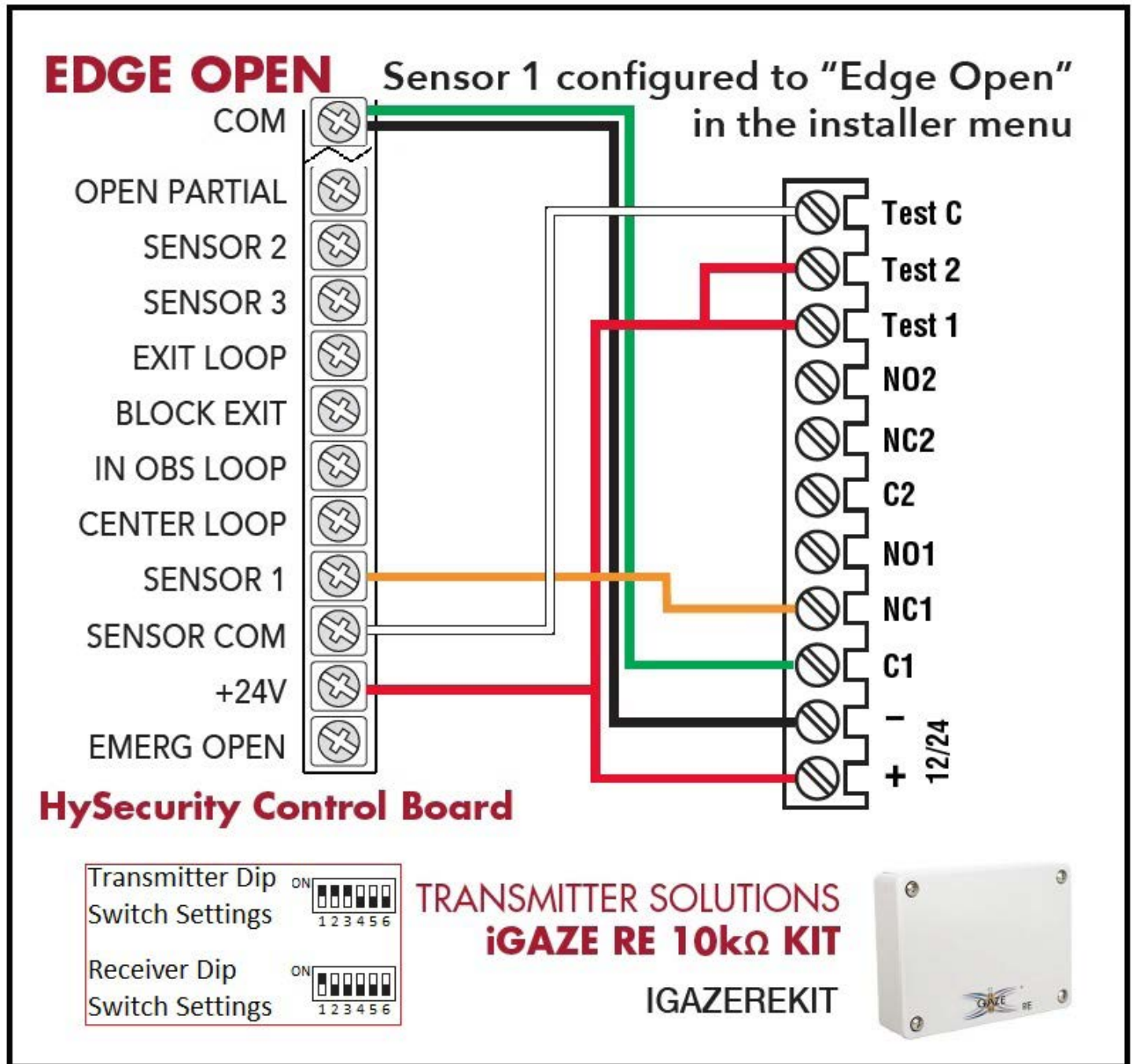


Connect either output (P/NC wire) to SENSOR 1, 2, or 3.



All external entrapment protection sensors must be NC sensor outputs and wired to the SENSOR COM terminal for monitoring and powering purposes. The sensor becomes actively powered when the gate operator's motor runs.

Smart Touch: iGAZE Kit Wiring Diagram



WARRANTY

1. Warranty.

Hy-Security Gate, Inc. (“HySecurity”) warrants that at the time of sale each HySecurity-branded product that it sells will, in all material respects, conform to its then applicable specification and will be free from defects in material and manufacture.

The following additional durational warranties apply to HySecurity products, depending on whether (1) the product is purchased through an authorized HySecurity distributor and (2) whether a timely and complete product registration is submitted to HySecurity.

It is therefore important that you register your product with HySecurity, online at www.hysecurity.com/warranty, within the 60-day period described below.

1(a) HySecurity Products Purchased Through Authorized Distributors and Properly Registered

For any gate operator product that is purchased from an authorized HySecurity distributor (this excludes product purchased through internet resellers or any distributor not authorized by HySecurity), if the product registration is completed by the Dealer/Installer or End User within 60 days of the date of purchase, the following warranty terms will apply. HySecurity warrants that the product will remain serviceable for the following periods:

- Hydraulic industrial gate operator hydraulics, controls, and mechanical components: Five Years or 500,000 gate cycles (whichever occurs first) after the date of installation,
- Hydraulic wedge operator hydraulics and controls: Five Years or 500,000 cycles (whichever occurs first) after the date of installation. Wedge mechanical components: Two Years after the date of installation,
- Electromechanical pad-mounted Slide and Swing operators: Five Years or 500,000 cycles (whichever occurs first) after the date of installation, except single family residential usage, where the warranty term shall be Seven Years after the date the product was shipped from HySecurity,
- Electromechanical linear actuator Swing operators: Two Years after the date of installation,
- Electromechanical surface mount wedge operator electronics: Two Years or 500,000 gate cycles (whichever occurs first), after the date of installation,
- Electromechanical Barrier Arm Operators: Two years or 1,000,000 gate cycles (whichever occurs first) after the date of installation,

provided that the preceding Five Year warranty period in (a), (b), and (c) will not extend beyond seven years from the date that the product was shipped from HySecurity, and the Two Year warranty period in (b), (d), (e), and (f) will not extend beyond four years from the date that the product was shipped from HySecurity.

The preceding warranty durations do not apply to the products or components described below (g-j), which have a shorter warranty period:

- Hydraulic gate operator drive wheels, including XtremeDrive™ wheels and rack: Two Years from date of installation.
- AC and DC power supplies, chargers, and inverters and HyNet™ Gateway: Two Years from date of installation, except batteries.
- Batteries: One Year from date of shipment from HySecurity.
- Components subject to normal wear including, but not limited to, chains, belts, idler wheels, sprockets and fuses: One Year from date of installation.

1(b) HySecurity Products Not Purchased Through an Authorized Distributor or Not Properly Registered within 60 Days

For any product that is not purchased from an authorized HySecurity distributor or for which the product registration was not completed by the Dealer/Installer/End User within sixty (60) days of the date of purchase, the following warranty will apply: HySecurity warrants that the product will remain serviceable for the following periods, which begin on the date that the product was shipped from HySecurity:

- All gate operators: One Year or 100,000 gate cycles, whichever comes first.
- AC and DC power supplies, chargers, or inverters: One Year.
- HyNet™ Gateway: One Year.
- Hydraulic gate operator drive wheels: One Year.

1(c) Replacement Parts

HySecurity warrants that replacement parts (whether new or reconditioned) will remain serviceable for One Year from the date that the part was shipped from HySecurity or the remaining period of the Gate Operator warranty, whichever is longer.

1(d) Limitations and Exclusions Applicable to Each of the Preceding Warranties.

The preceding warranties shall not apply to equipment that has been (1) installed, maintained, or used improperly or contrary to instructions; (2) subjected to negligence, accident, vandalism, or damaged by severe weather, wind, flood, fire,

terrorism or war; or (3) damaged through improper operation, maintenance, storage or abnormal or extraordinary use or abuse. Any modification made to products will void the warranty unless the modifications are approved in writing by HySecurity in advance of the change (this exclusion does not apply to normal installation of approved accessories and/or protective devices or sensors). It is the responsibility of the Distributor, Dealer/Installer, or End User to ensure that the software version in the product is maintained to the latest revision level.

The preceding warranties do not extend to accessories when those items carry another manufacturer’s name plate and they are not a part of the base model. HySecurity disclaims all warranties for such accessory components, which carry only the original warranty, if any, of their original manufacturer. HySecurity hereby assigns its rights under such manufacturer warranties—to the extent that such rights are assignable—to Buyer.

These warranties extend to HySecurity’s Distributors, to the Dealer/Installer, and to the first End User of the product following installation. They do not extend to subsequent purchasers.

2. Exclusion of Other Warranties.

The warranties contained in Section 1 are the exclusive warranties given by HySecurity and supersede any prior, contrary or additional representations, whether oral or written. Any prior or extrinsic representations or agreements are discharged or nullified. HYSECURITY HEREBY DISCLAIMS AND EXCLUDES ALL OTHER WARRANTIES—WHETHER EXPRESS, IMPLIED, OR STATUTORY—INCLUDING ANY WARRANTY OF MERCHANTABILITY, ANY WARRANTY OF FITNESS FOR A PARTICULAR PURPOSE, ANY LIABILITY FOR INFRINGEMENT, AND ANY WARRANTIES OTHERWISE ARISING FROM COURSE OF DEALING, COURSE OF PERFORMANCE, OR USAGE OF TRADE.

3. Buyer’s Exclusive Remedies for Any Nonconformity.

If a HySecurity product fails to conform to the warranties in Section 1, Buyer must notify and order replacement parts from the Distributor through which the product was purchased within a reasonable time and in no event more than thirty (30) days after the discovery of the nonconformity. HySecurity will investigate and, in the event of a breach, will provide, within a reasonable period of time, one of the following:

- repair or replacement of any nonconforming products or components or
- refund of the price upon return of the nonconforming items. HySecurity reserves the right to supply used or reconditioned material for all warranty claims. HySecurity will not be considered to be in breach of or default under this Warranty because of any failure to perform due to conditions beyond its reasonable control, including any force majeure. This warranty does not cover any incidental expenses, including fines or penalties, temporary security, labor, shipping, travel time or standby time that are incurred for inspection or replacement of any nonconforming items. As a condition of warranty coverage, warranty claims must be submitted in accordance with the procedures described on the HySecurity form, “RMA Procedures.”

THE REMEDY SELECTED BY HYSECURITY IN ACCORDANCE WITH THIS PARAGRAPH SHALL BE THE EXCLUSIVE AND SOLE REMEDY OF BUYER FOR ANY BREACH OF WARRANTY.

4. Exclusion of Consequential and Incidental Damages.

HYSECURITY SHALL NOT BE LIABLE FOR ANY INCIDENTAL, SPECIAL, OR CONSEQUENTIAL DAMAGES, WHETHER RESULTING FROM NONDELIVERY OR FROM THE USE, MISUSE, OR INABILITY TO USE THE PRODUCT OR FROM DEFECTS IN THE PRODUCT OR FROM HYSECURITY’S OWN NEGLIGENCE. This exclusion applies regardless of whether such damages are sought for breach of warranty, breach of contract, negligence, or strict liability. This exclusion does not apply to claims for bodily injury or death.

5. Severability.

If any provision of this warranty is found to be invalid or unenforceable, then the remainder shall have full force and effect.

6. Proprietary Rights.

HySecurity retains and reserves all right, title, and interest in the intellectual property rights of its products, including any accompanying proprietary software. No ownership of any intellectual property rights in the products or accompanying software is transferred to Distributor, Dealer/Installer, or End User.

7. Applicable Law.

This warranty will be interpreted, construed, and enforced in all respects in accordance with the laws of the State of Washington, without reference to its choice of law principles. The U.N. Convention on Contracts for the International Sale of Goods will not apply to this warranty.

Specifications

SlideDriver™ models

| | FAST | | FAST | | | |
|---------------------|--|---|---|--|--|---|
| | 1,500 lb gates 1 ft/s | 3,000 lb gates 1.7 ft/s | 4,000 lb gates 1 ft/s | 5,000 lb gates 2.2 ft/s or 3 ft/s | 8,000 lb gates 1 ft/s | 20,000 lb gates 1 ft/s |
| Model | SlideDriver 15 | SlideDriver 30F | SlideDriver 40 | SlideDriver 50VF2/3 | SlideDriver 80 | SlideDriver 200 |
| Part # | 222 SS ST | 222 EX 1.7 ST | 222 E ST | 222 X3 ST | 222 X1 ST | 444 XS ST |
| Duty Cycle | Continuous | | | | | |
| Horsepower | 1 hp UPS model: 2 hp | 2 hp | 1 hp UPS model: 2 hp | 2 hp | 2 hp | 5 hp |
| Drive | Hydraulic | | | | | |
| Drive Wheels | Two 6 inch (15 cm) AdvanceDrive wheels | Two 6 inch (15 cm) AdvanceDrive wheels | Two 6 inch (15 cm) AdvanceDrive wheels | Two 8 inch (20 cm) AdvanceDrive wheels | One 8 inch (20 cm) AdvanceDrive wheel, One 8 inch XtremeDrive wheel and 27 ft (8 m) of rack | Two 8 inch (20 cm) AdvanceDrive wheels, Two 8 inch XtremeDrive wheels and 52 ft (16 m) of rack |
| Gate Weight Max. | 1,500 lb (680 kg) | 3,000 lb (1,361 kg) | 4,000 lb (1,814 kg) | 5,000 lb (2,268 kg) | 8,000 lb (3,629 kg) | 20,000 lb (9,072 kg) |
| Gate Length Max. | Limited only by weight | | | | | |
| Drawbar Pull | 300 lb (136 kg) | 300 lb (136 kg) | 300 lb (136 kg) | 300 lb (136 kg) | 600 lb (272 kg) | 1,200 lb (544 kg) |
| Rate of Travel | 1 ft/s (30 cm/s) | 1.7 ft/s (50 cm/s) | 1 ft/s (30 cm/s) | Field adjustable, 2.2 ft/s (70 cm/s) or 3 ft/s (91 cm/s) Emergency Fast Operate 3 ft/s (91 cm/s) | 1 ft/s (30 cm/s) | 1 ft/s (30 cm/s) |
| Temperature Rating | -40° to 158° F (-40° to 70° C) | | | | | |
| 1 Phase Power | 115/208/230V 60 Hz 110/220V 50 Hz*** | 208/230V 60 Hz 220V 50 Hz*** | 115/208/230V 60 Hz 110/220V 50 Hz*** | 208/230V 60/50 Hz | 208/230V 60 Hz 220V 50 Hz*** | 230V 60 Hz 220V 50 Hz*** |
| 3 Phase Power | 208/230/460V; 220/380/440V 50Hz*** | | | 208/230V 60/50Hz or 380/460V 60/50Hz | 208/230/460V; 220/380/440V 50Hz*** | |
| Communication | RS-232, RS-485, Ethernet/fiber using optional HyNet™ Gateway accessory | | | | | |
| User Controls | Smart Touch Controller with 70+ configurable settings, programmed via the keypad and display or a PC using S.T.A.R.T. software. | | | | | |
| Relays | Three configurable user relays: one 30VDC, 3A solid state and two 250VAC, 10A electromechanical; Optional Hy8Relay™ for 8 additional relay outputs | | | | | |
| Finish | Zinc plated with powder coating | | | | | |
| ETL Listed (UL 325) | Usage Class I, II, III, IV | Usage Class III, IV | Usage Class I, II, III, IV | Usage Class III, IV | Usage Class III, IV | Usage Class III, IV |
| Warranty | 5 year w/product registration | | | | | |

UPS Battery Backup Power and Additional Models

| | | | | | | |
|---|--------------------------------------|---------------------|--------------------------------------|---|--------------------|-----------------------|
| DC Power Supply* † with HyCharger DC | SlideDriver 15 UPS | SlideDriver 30F UPS | SlideDriver 40 UPS | - | SlideDriver 80 UPS | SlideDriver 200 UPS** |
| AC Power Supply with HyInverter AC* | SlideDriver 15 with HyInverter AC | - | SlideDriver 40 with HyInverter AC | SlideDriver 50VF2/3 with HyInverter AC | - | - |
| Correctional Facility | - | SlideDriver 30F-C | SlideDriver 40-C | SlideDriver 50VF2/3-C | SlideDriver 80-C | SlideDriver 200-C |
| Modular | SlideDriver 15-M | SlideDriver 30F-M | SlideDriver 40-M | SlideDriver 50VF2/3-M | SlideDriver 80-M | SlideDriver 200-M |

* 3,000 ft/hr expected duty cycle. The operator's normal duty cycle and the actual number of gate cycles available from battery depends upon gate resistance to travel, cycle length, battery size, state of charge and health, ambient temperature, accessory power draw and frequency of gate cycles during power outage.

** SlideDriver 200 UPS has a 2,000 ft/hr (610 m/hr) expected duty cycle. Actual duty cycle depends on site specific conditions and gate configuration.

*** Refer to Installed Options on pricing for all 50Hz voltages, which are special order.

† 115V DC Power Supply requires a 30A branch circuit. Choose voltage with care as chargers are not field convertible.

To enable fully automatic operation, all SLIDE gate operators require a minimum of TWO monitored external entrapment protection sensors (one for each direction) to protect entrapment zones in both the open and close direction of travel. Visit hysecurity.com/gatesafety for more information on UL 325 standards and gate safety.

Contact Information: Visit <https://support.hysecurity.com/hc/en-us> for installation manuals, replacement part instructions, part diagrams and more. Qualified Nice distributors are experienced and trained to assist in resolving installation problems. For the name of a qualified distributor near you, call Nice at 800-321-9947. *Before contacting your distributor or Nice Technical Support, obtain the serial number of your operator.